



Measurement Methods for Noise Emitted by Light-duty Vehicles in Multiple Driving Mode Conditions

-Historical Background, Current Development and Future Topics-

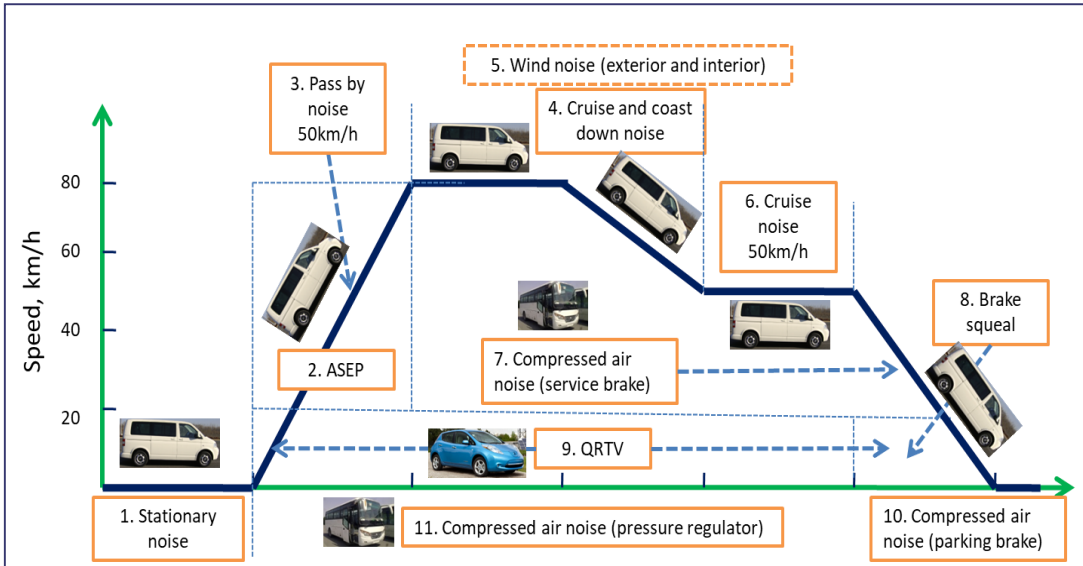
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The Origin of Test Methods Standard



- China released plans and a long-term technology roadmap for vehicle noise standards and regulations during the 62th session of WP.29 GRB in 2015.
- In the roadmap, it is realized that a noise regulation system to cover all typical behaviors of all vehicles on road will be the top priority of China.
- During the recent 5 years, all 11 items in the left Fig. have been covered or planned by 5 standards projects in China noise standards system .

●National Standard of China GB/T <Measurement Methods for Noise Emitted by Light-duty Vehicles in Multiple Driving Mode Conditions>

- The test methods standard project launched in 2018 and is now waiting for the technical review after comments.
- It is expected for corresponding to the test methods of UN Regulation No.51-03 ASEP.
- The use of China Automotive Test Cycle (corresponding to WLTP) makes it possible for a refined and accurate design.

Background Knowledge



● From GRB(P) and ASEP

- The discussion for creating current Method B (Documents from Netherlands and OICA)
- Assessments of UN Regulation No. 51-03 (Venoliva Study)
- ISO system (Annex A of ISO 362-1: 2007, from test cycles to test methods)
- ASEP system (Documents from previous ASEP IWG)

● From Ecology and Environment Fields

- Environmental quality standards for noise (Noise functional areas of China, Japan and WHO Europe)
- Complexity of traffic noise (functional areas planning, noise sources and transfer paths)
- Complexity of vehicle noise (Noise sources, and real driving conditions)

- **Opinions and technologies for designing the test methods are derived from historical researches of GRB(P), ASEP, ISO, China and actual environmental status.**

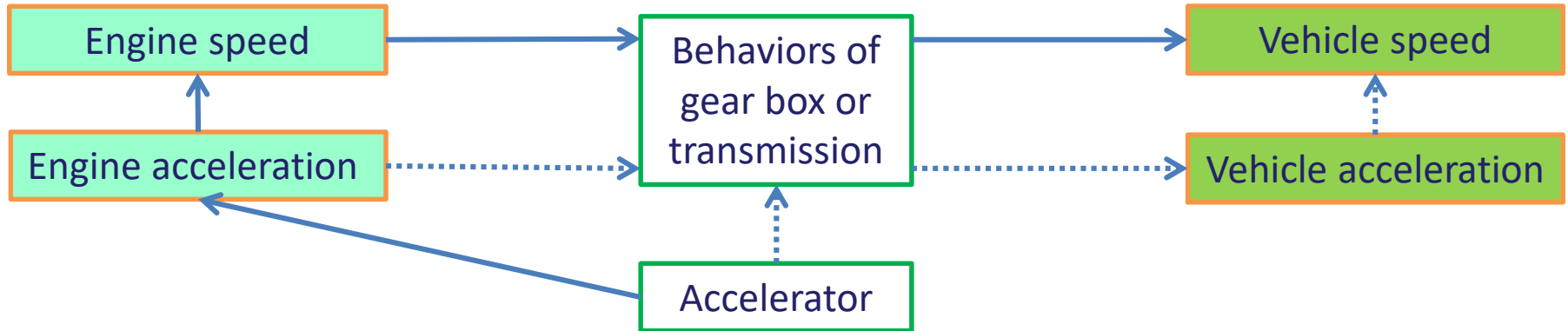
Key Parameters for Tests

● Key parameters for test methods

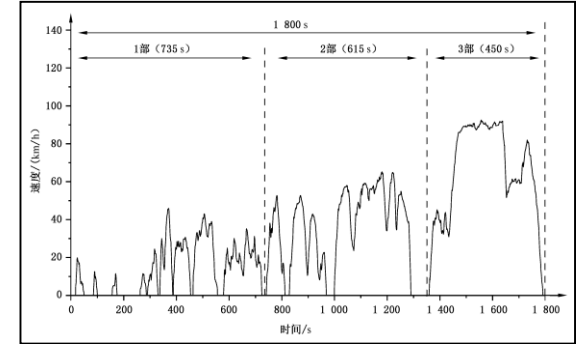
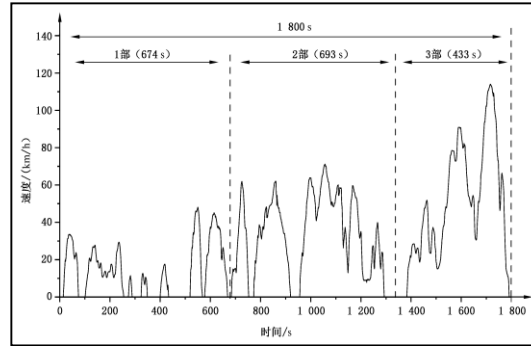
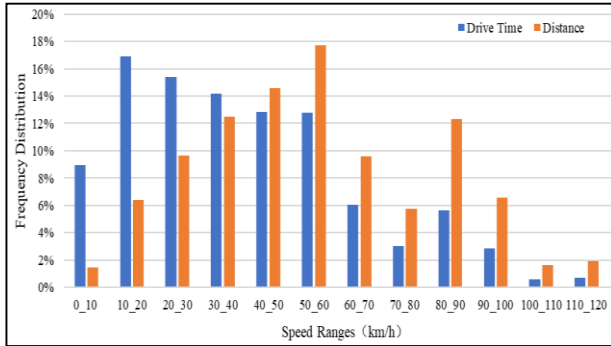
- Vehicle Speed
- Engine Speed
- Vehicle Acceleration
- Engine Acceleration

• **Vehicle speed ” is the most sensitive parameters for environmental noise.**

- ① Set realistic and representative speeds;
- ② Use reasonable gear @ speed for realistic engine speed;
- ③ Control the accelerator properly @ speed for reproduced.



Realistic and Sensitive Speeds



- 30km/h, 50km/h and 70km/h for acceleration noise, 80km/h and 110 (90) km/h for cruise noise.

Drive Time Distribution (%)	0~70km/h	>70km/h	>75km/h	>80km/h
Acceleration	34.80%	18.99%	16.72%	12.45%
Deceleration	33.40%	18.72%	16.40%	13.92%
Cruise	31.80%	62.29%	66.88%	73.63%

Road type	Residential (urban/suburban)	Residential (urban/suburban)	Main roads (urban/suburban)	Main roads (urban/suburban)	Arterial roads (urban/suburban)	Urban motorways (urban/suburban)	Rural motorways	Rural roads	Total
Traffic type	intermittent	free flow	intermittent	free flow	free flow	free flow	free flow	free flow	
Speed range	V<50	V<50	V<50	V<50	50-V<70	70-V<100	80-V<130	50-V<100	
Full road length/km	547998	1112603	83030	168576	100643	5032	95610	2018633	5032125
Percentage of total road network	11%	22%	2%	3%	2%	0.1%	2%	58%	100%
Selected road length/km	356199	723192	66424	134861	80578	4026	47806	1459318	2882401
Percentage of selected road network	12%	25%	2%	5%	3%	0.1%	2%	51%	100%
Estimated avg. level of noise									
Inhabitants/km	250	250	500	500	500	1000	50	20	
Typical distance to road (m)	15	15	15	15	15	50	50	50	
Applied penalty, dB	3	0	3	0	0	0	0	0	
Noise sources	Powertrain, tyre	Powertrain, tyre	Powertrain, tyre	Powertrain, tyre	Powertrain, tyre	Powertrain, tyre	Powertrain, tyre	Powertrain, tyre	

Choose Reasonable Gears



- The increasing gear numbers are expected for covering frequent speed distribution better.

Test speeds		30km/h	50km/h	70km/h	≥80km/h
Formulas for Test Gears		$(1+X/2)/2+1$	$(1+X/2)$	$(X+X/2)/2+1$	----
Calculated Test Gears for lockable gear boxes*					
Total gears	4	2	3	4	Highest lockable gear
	5	2	3	4	
	6	3	4	5	
	7	3	4	6	
	8	3	5	7	
	9	3	5	7	
	10	4	6	8	

* Round down if the result is not an integer.

Principle for lockable gears:

- Try to use the calculated gears shown above, but if cannot, it is permitted to make measurement as per the adjacent gear recommended by manufacturers.

Principal for non-lockable gears:

- For non-lockable automatic transmission, adaptive transmission or CVT, it is allowed to use additional electronic or mechanical devices to fix the gear ratios.
- If A is unsatisfied, use Gear position D and try to avoid gear shifting to a gear ratio which is not used in urban traffic at least.

Control the Accelerator Properly



How to use accelerator:

- When test vehicle enters line AA' or pre-acceleration position point before line AA', quickly depress acceleration pedal to **appropriate position (POT or WOT)** and keep the pedal at the position **stably**;
- Release the accelerator until the rearmost part of test vehicle passes line BB'.

How to calculate the acceleration:

- Record $v_{AA'}$, $v_{PP'}$ and $v_{BB'}$ and perform test acceleration calculation;
- Acceleration formulas are the same as UN Regulation No. 51-03.

What's the target acceleration:

Test Speeds	30km/h	50km/h	70km/h	≥80km/h
Accelerator Position	POT or WOT (Both are possible)			POT (Cruise)
Acceleration (m/s ²)	$0.5 \leq a_{\text{test}} \leq 3.5$	$0.5 \leq a_{\text{test}} \leq 3.0$	$0.3 \leq a_{\text{test}} \leq 2.5$	$a_{\text{test}} \leq 0.15$

- The wide range of acceleration is for purpose of covering different vehicle performance.

Scope, Sub-categories and Summary

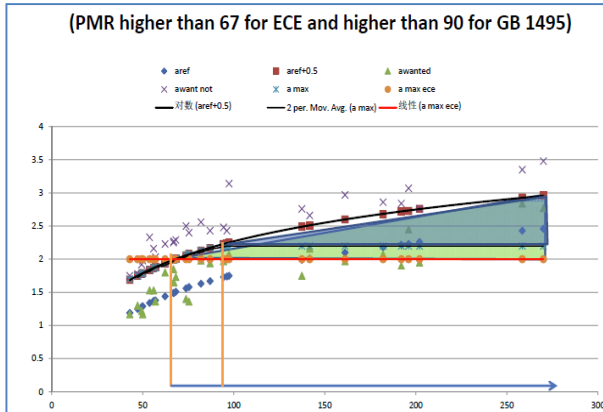


Full scope:

- M_1, N_1, M_2 (GVM ≤ 3 500kg)

Sub-categories:

- M_1 (PMR < 90kw/t): 2 runs @ 30km/h, 50km/h, 70km/h, 80km/h, 110km/h;
 - ✧ Thereinto, Multi-purpose Van: 2 runs @ 30km/h, 50km/h, 70km/h, 80km/h, 90km/h.
- M_1 (PMR ≥ 90 kw/t): 2-4 runs @ 30km/h, 50km/h, 70km/h; and 2 runs @ 80km/h, 110km/h.
- N_1 and M_2 (GVM ≤ 3 500kg): 2 runs @ 30km/h, 50km/h, 70km/h; and 2 runs @ 80km/h, 90km/h.



Test speeds (km/h)	$V_{pp}=30 \pm 1$	$V_{pp}=50 \pm 1$	$V_{pp}=70 \pm 2$
Engine speeds (r/min)	$n_{BB} = \text{Idle to } 80\%S$		
Acceleration (m/s^2)	$0.5 \leq a_{test} \leq 3.5$	$0.5 \leq a_{test} \leq 3.0$	$0.3 \leq a_{test} \leq 2.5$
Test Gears	$(1+X/2)/2+1$	$(1+X/2)$	$(X+X/2)/2+1$
Accelerator Position	POT or WOT (Both are possible)		
Noise Tested	L_{max} per run for left side and right side separately		
No. of Runs*	2	2	2
Intermediate Result	Average of per side	Average of per side	Average of per side
Final result	Higher of averages	Higher of averages	Higher of averages
* M_1 (PMR ≥ 90 kW/t), 2 runs can add at different acceleration.			

Test speeds (km/h)	$V_{pp}=80 \pm 2$	$V_{pp}=110 \pm 2$ for M_1 $V_{pp}=90 \pm 2$ for others
Engine speeds (r/min)	$n_{BB} = \text{Idle to } 80\%S$	
Acceleration (m/s^2)	$a_{test} \leq 0.15$	
Test Gears	Highest lockable gear or D for unlockable	
Accelerator Position	POT (Cruise)	
Noise Tested (dB(A))	L_{max} per run for left side and right side separately	
No. of Runs	2	2
Intermediate Result	Average of per side	Average of per side
Final result	Higher of averages	Higher of averages

Comparison with ASEP Test Method



Items		GB/T (Draft)	UN ASEP (Draft)
Control Ranges	Speed	20-110 km/h (30, 50, 70, 80, 90, 110km/h)	0-100 km/h (Any, not fixed)
	Engine speed	Idle to 80% S	Idle to 80% S
	Acceleration	0-3.5 m/s ² (corresponding to speed)	0-4.0 m/s ²
	Performance	0-48.6 m ² /s ³ (corresponding to speed)	0-35.0 m ² /s ³
	Gear	Recommended gears (corresponding to speed)	Any
	Mode	Any	Any
No. of Runs		10 or 16	[15]
Intermediate Result		Average of per side	----
Final result		Higher of averages	[Higher of per side]

The differences between GB/T (Draft) and UN ASEP (Draft) :

- GB/T tests at fixed speeds, and builds up ranges for other parameters based on different speed conditions;
- UN ASEP sets general ranges for all parameters, and tests randomly.

Relevant Research Topics



● **Assessment system**

- The potential to combine the test methods with the Statistical Sound Expectation Model.
- The potential to enrich and simplify the current Regulation or standard system.

● **More vehicle categories**

- How is the typical noise pollution, noise sources and test cycles for Heavy-duty vehicles?
- How to design more simplified, accurate and effective test methods for different sub-categories.

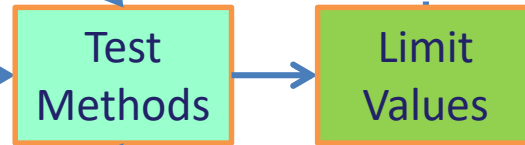
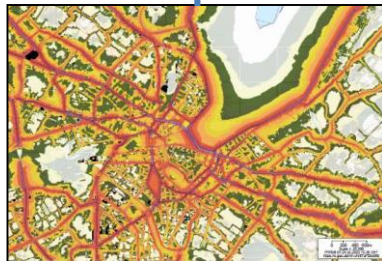
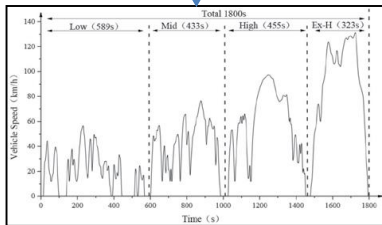
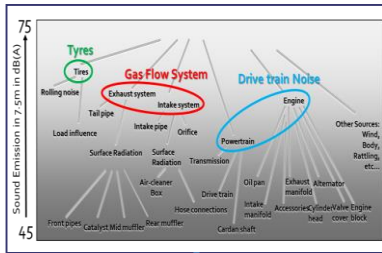
● **Other noise caused by vehicles**

- How is the burst noise, the low frequency noise and delivery noise, and how to test properly?

● **Systematic consideration**

- What is the exact role and the target of the current test methods inside the general system?
- The ethical issues of setting control ranges.
- Further more, how the control ranges clear and definite social responsibilities of different participants, and how a new system will match with the new situations?

Technical Roadmap and Conclusions



- Noise sources, test cycles and noise issues are the three key source powers for creating the test methods. More studies are needed for the correlations.
- The big data from environmental noise monitoring and test cycle studying makes the previous technical route for test methods more possible, more accurate and it should be proved effective.
- The development of ASEP Sound Model are releasing more space for the creation of test methods and assessments.

Reference and Acknowledgement



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Thanks for your attention



Web site: www.catarc.org.cn

