

AEBS HDV IWG

Comparison of AEBS complexity of PCs vs HDVs

AEBS-HDV-SP-02
January 25-27, 2021

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- ❑ AEBS complexity (comparison of PCs and HDVs)
- ❑ Intermediate Conclusions
- ❑ Strategic views
- ❑ Industry recommendations

AEBS Legislated Applications

Vehicles primarily used in
“urban driving conditions”

Medium
range



Low speed

Collision with
Vehicles and VRU

PCs

HDVs

Vehicles primarily used on
“monotonous Highway conditions”

**AEBS on PC and AEBS on HCVs
only shares the same acronym,
all the rest differs*:
use case, applications,
strategy, functionality...**

High (Cruise)
speed

Collision with
Vehicles

(* note: this led to making 2 different regulations)

Long
range



AEBS complexity

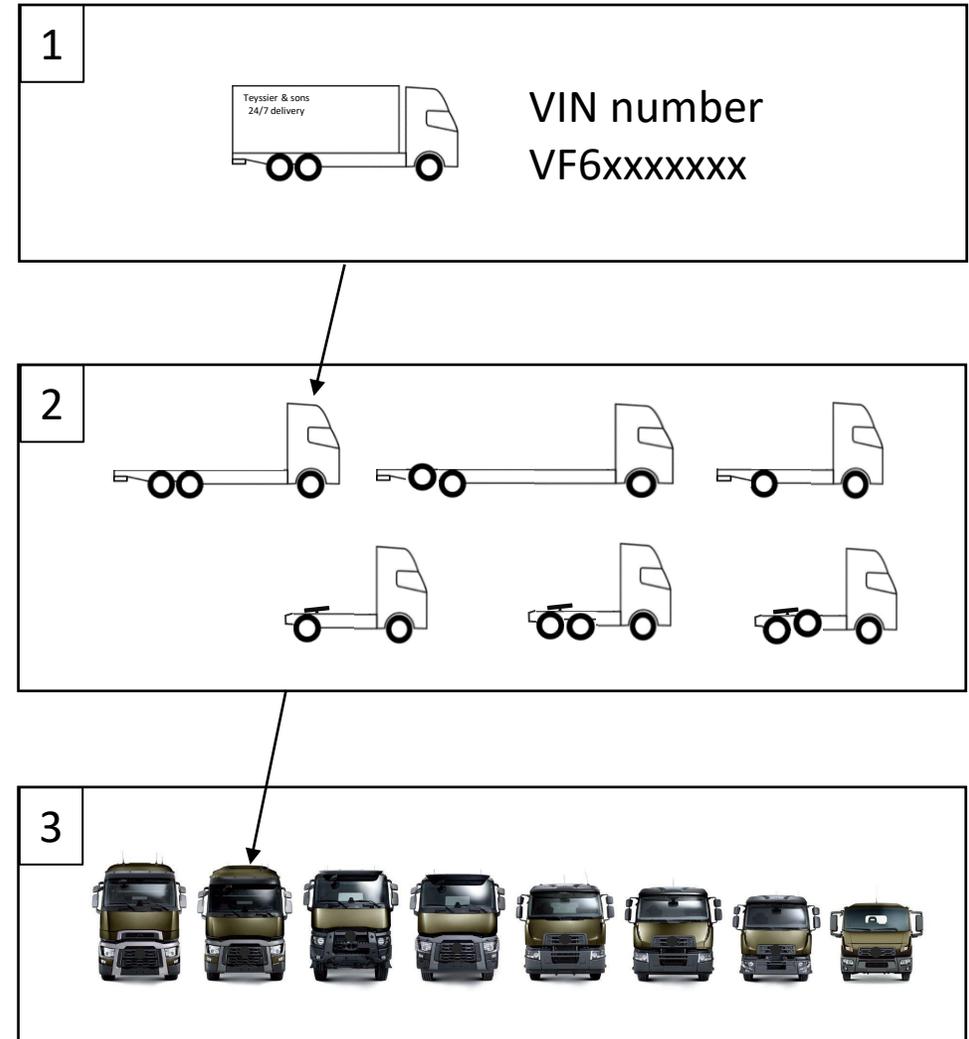
(comparison of PCs and HDVs)

AEBS complexity

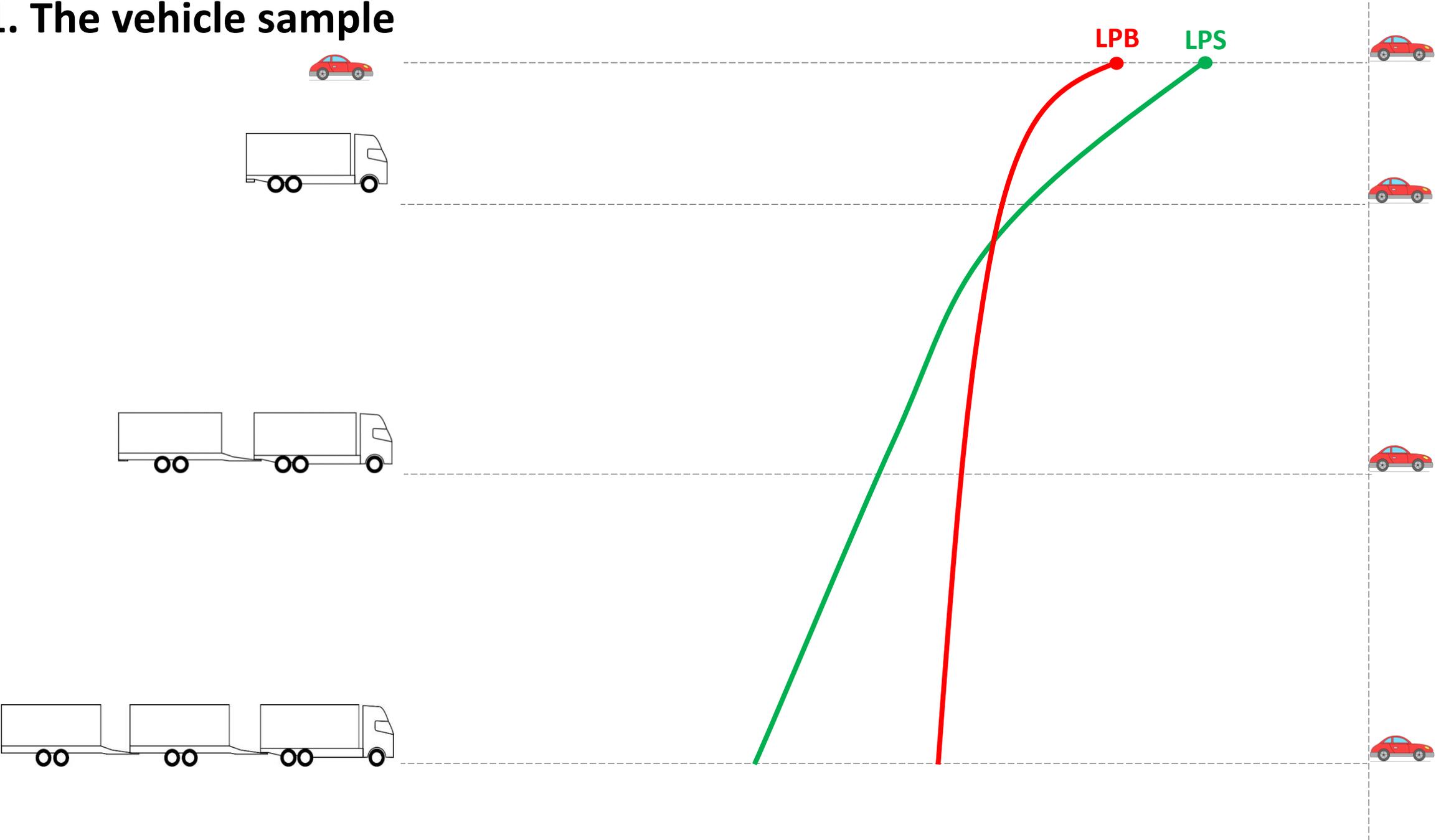
(comparison of PCs and HDVs)

Different levels to be considered for the comparison:

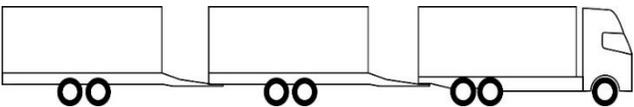
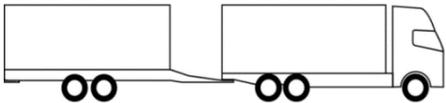
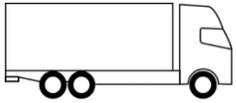
1. The vehicle sample (the individual)
2. The model
3. The range of models



1. The vehicle sample



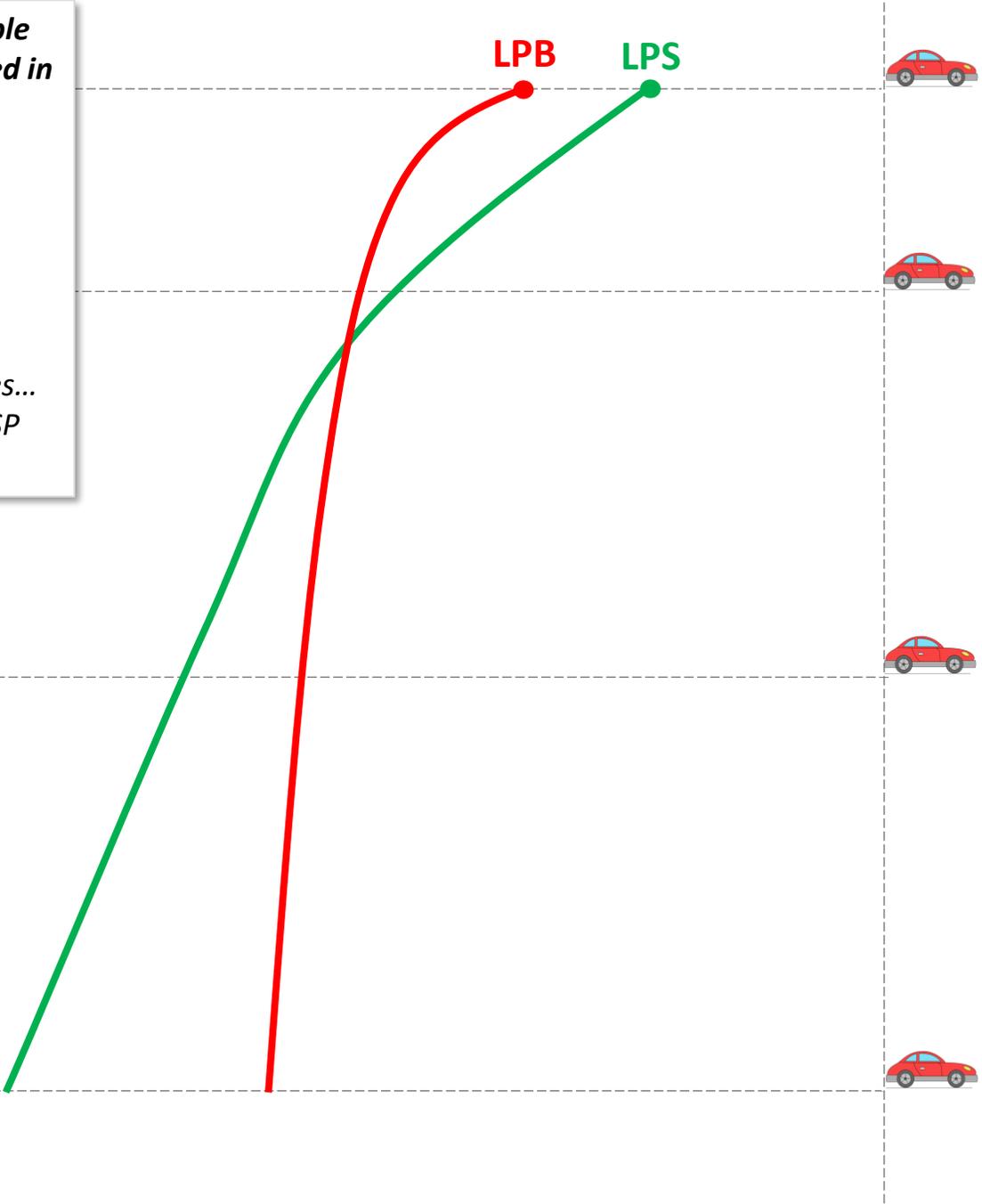
1. The vehicle sample



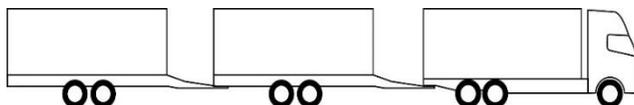
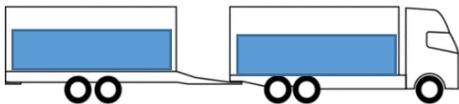
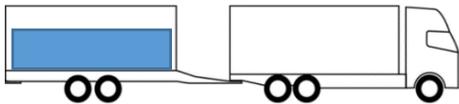
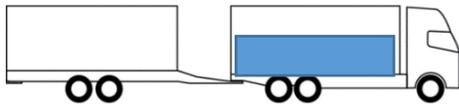
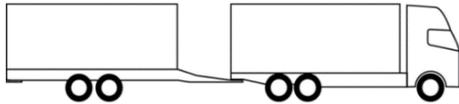
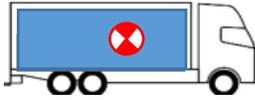
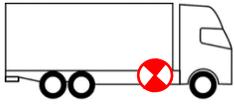
The very same vehicle sample (i.e. a given VIN) will be used in a number of different configurations / situations.

Some impacting factors:

- Load, COG height,
- Speed,
- Road adhesion,
- Number of trailers:
 - Trailer type, brake, axles...
 - actual Status of ABS/ESP
- ...



1. The vehicle sample

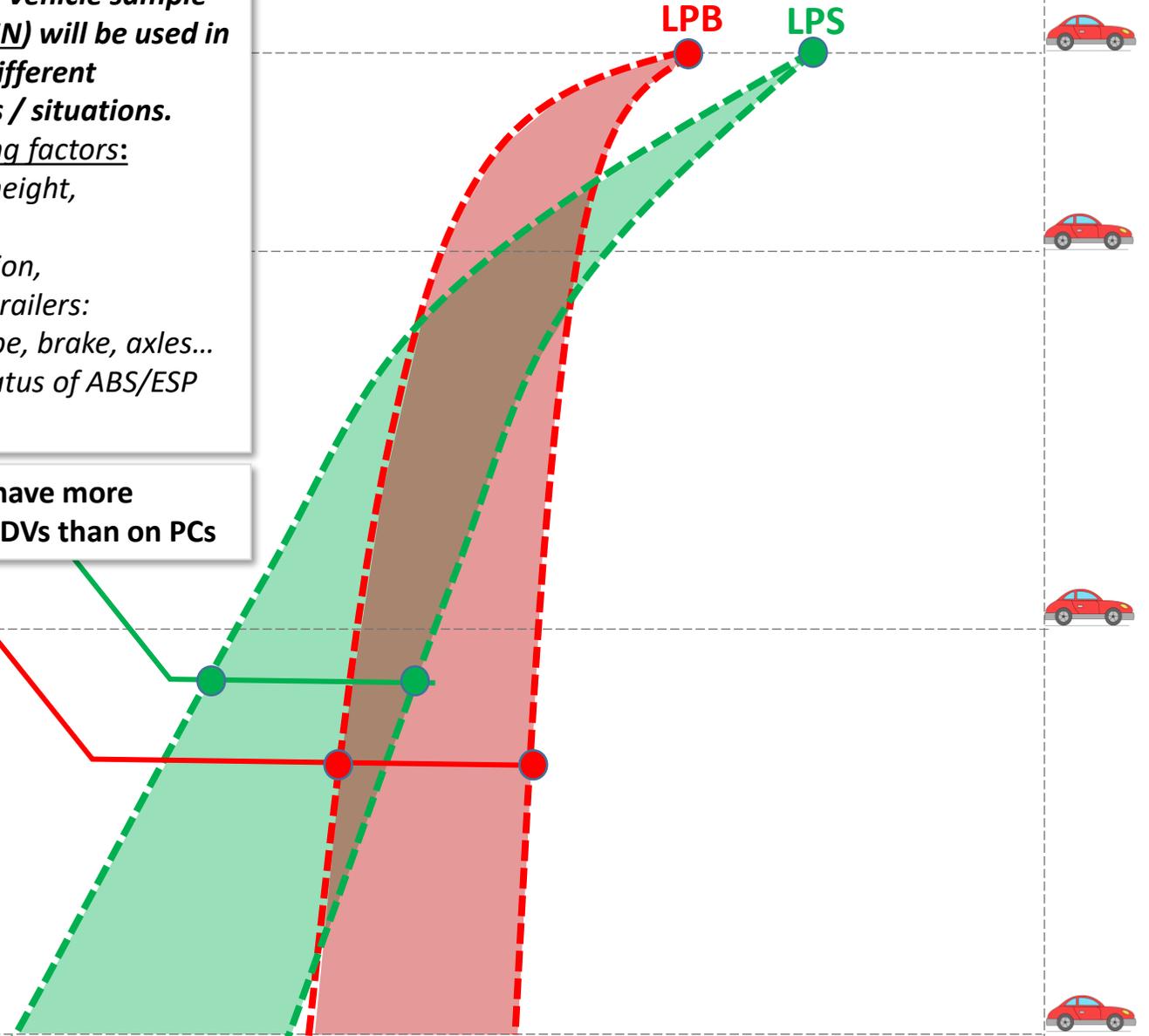


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Some impacting factors:

- Load, COG height,
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These factors have more influence on HDVs than on PCs

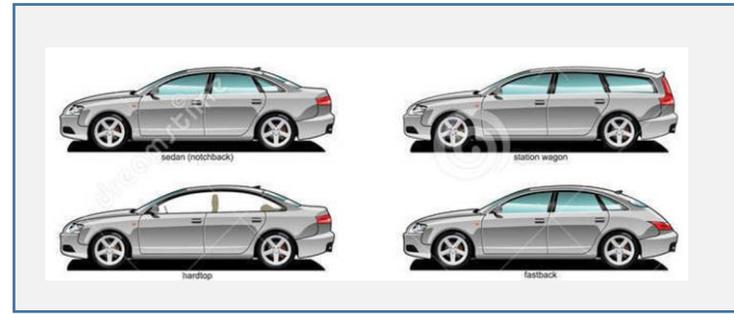


One AEBS strategy that "fits to all" is a challenge..

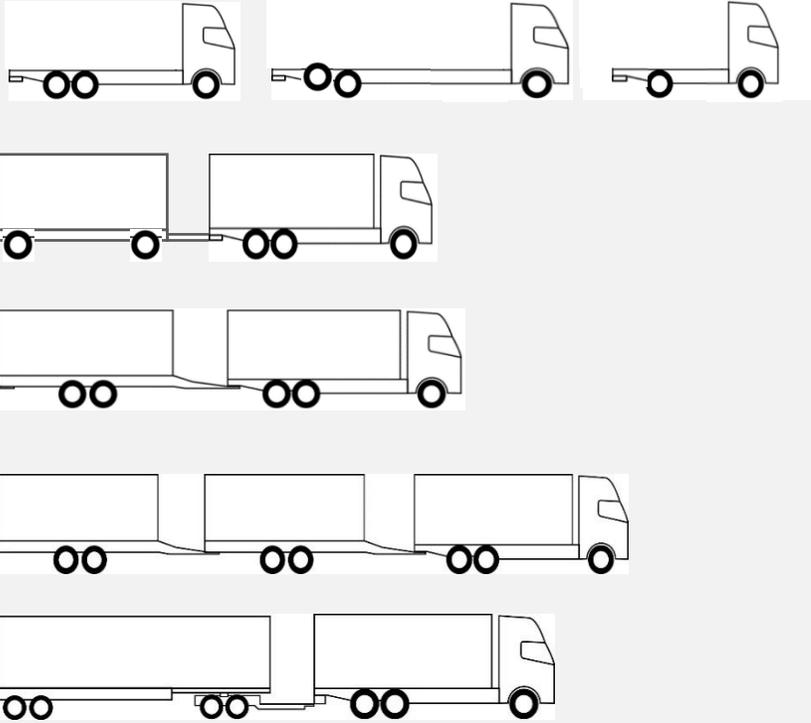
2. The model

HDVs

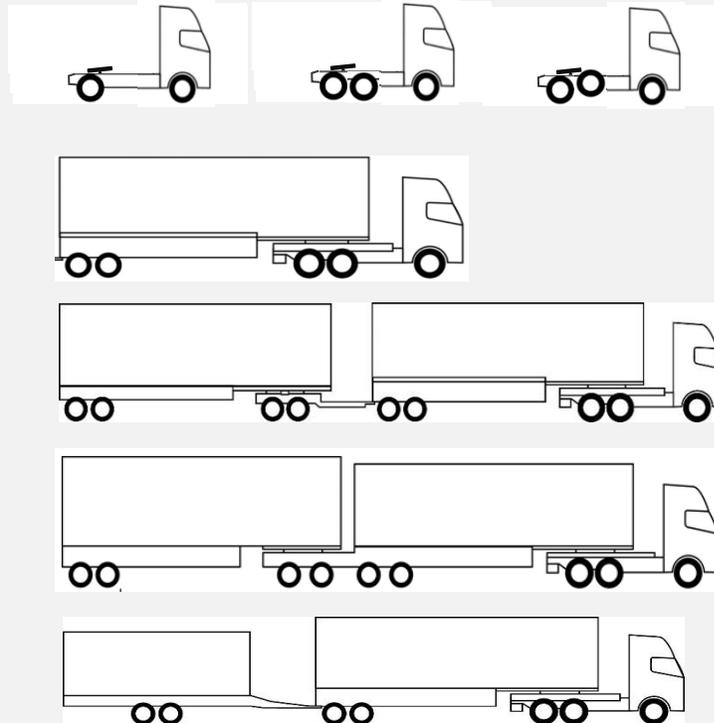
PCs



Trucks



Tractors



Huge variety of applications:

- Tippers,
- Refuse,
- Tankers,
- Snowplough, cranes,
- Weight Transport,
- Volume Transport...

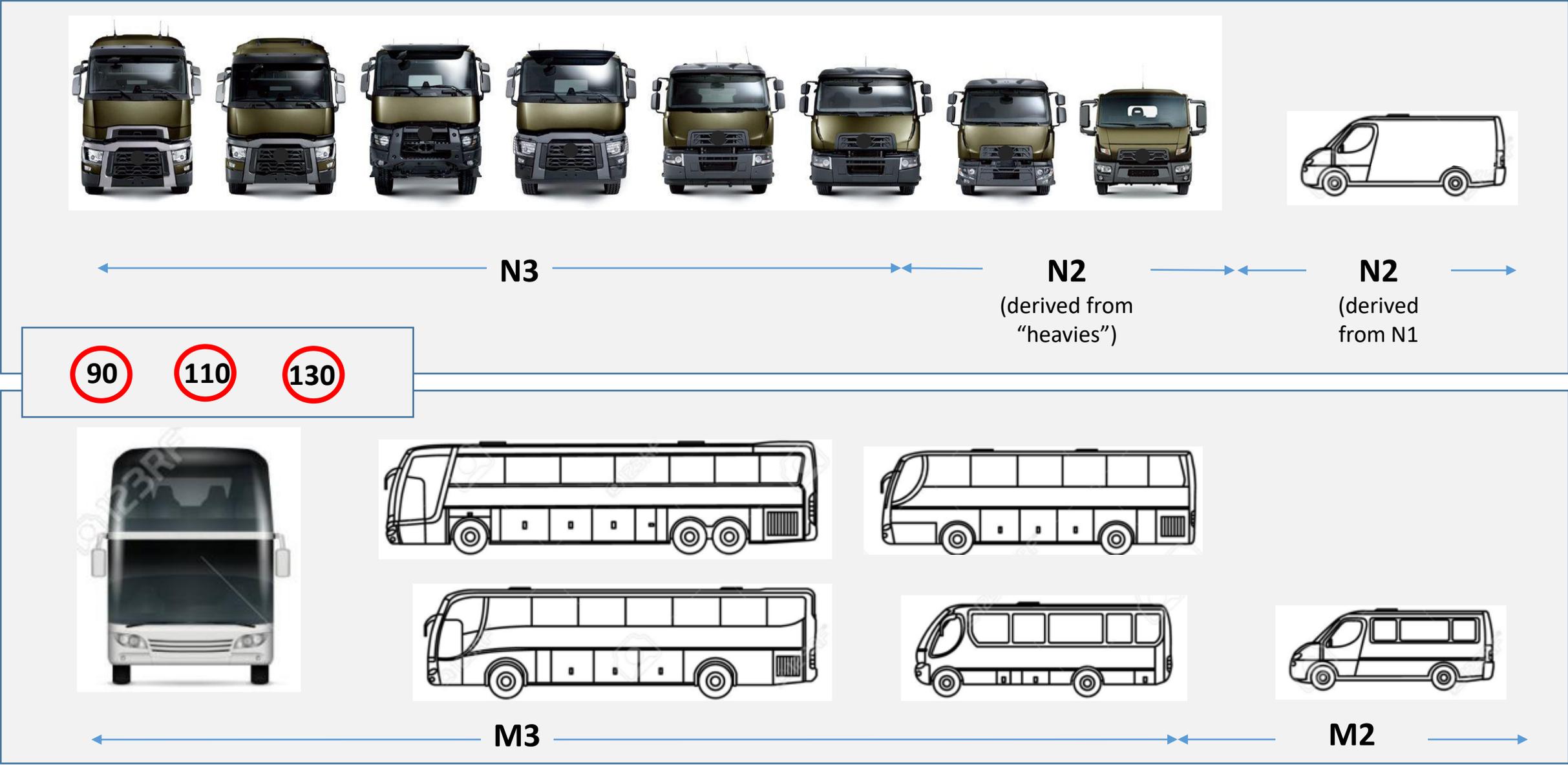
Infinite combination of variants:

- Suspension
- Brake type
- Cab/chassis height
- Tyre/wheel size
- Wheel base
- Cab suspension
- Tag / pusher / Liftable / steerable axles

A given model requires a number of different AEBS applications (strategies, tunings, validation, type approval...)

3. The range of models

Each model have a specific architecture (construction), i.e. a different AEBS application

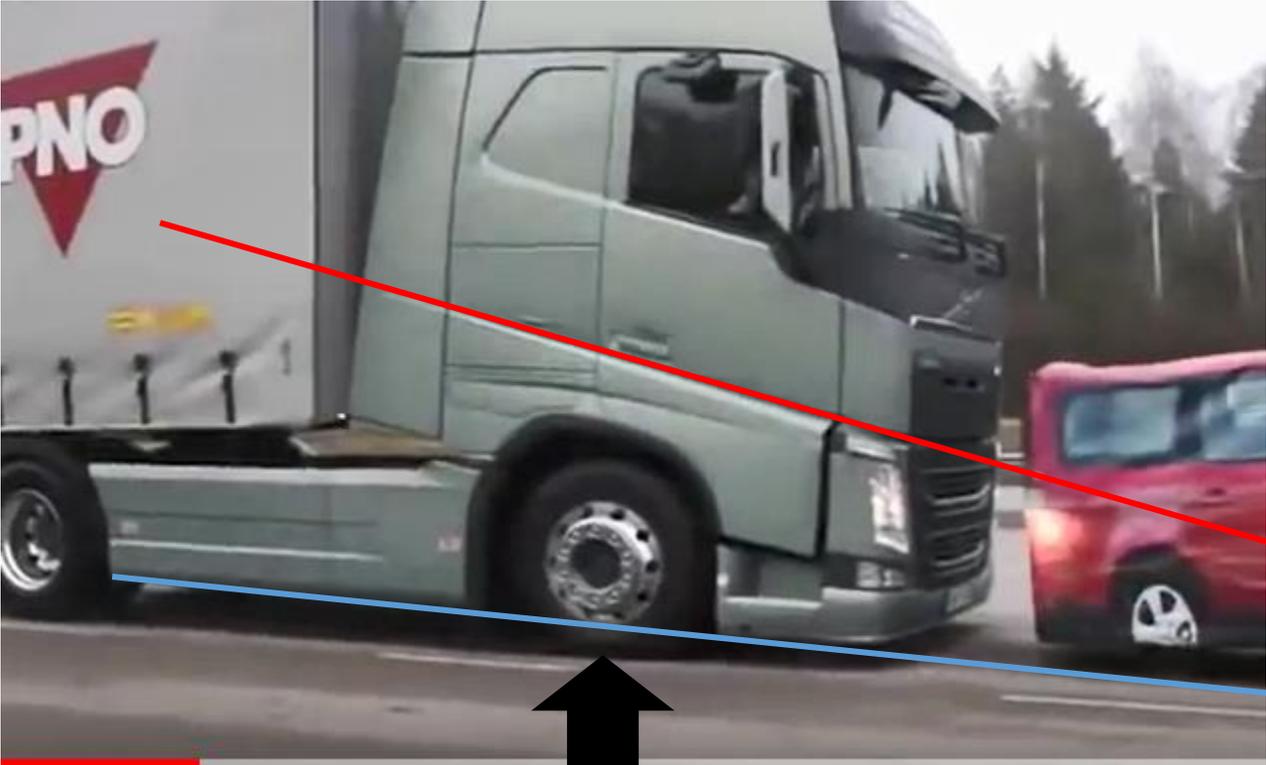


4. The example of “Chassis-Cab angle dynamic variation”

<https://www.youtube.com/watch?v=ridS396W2BY>

t = 18s

1

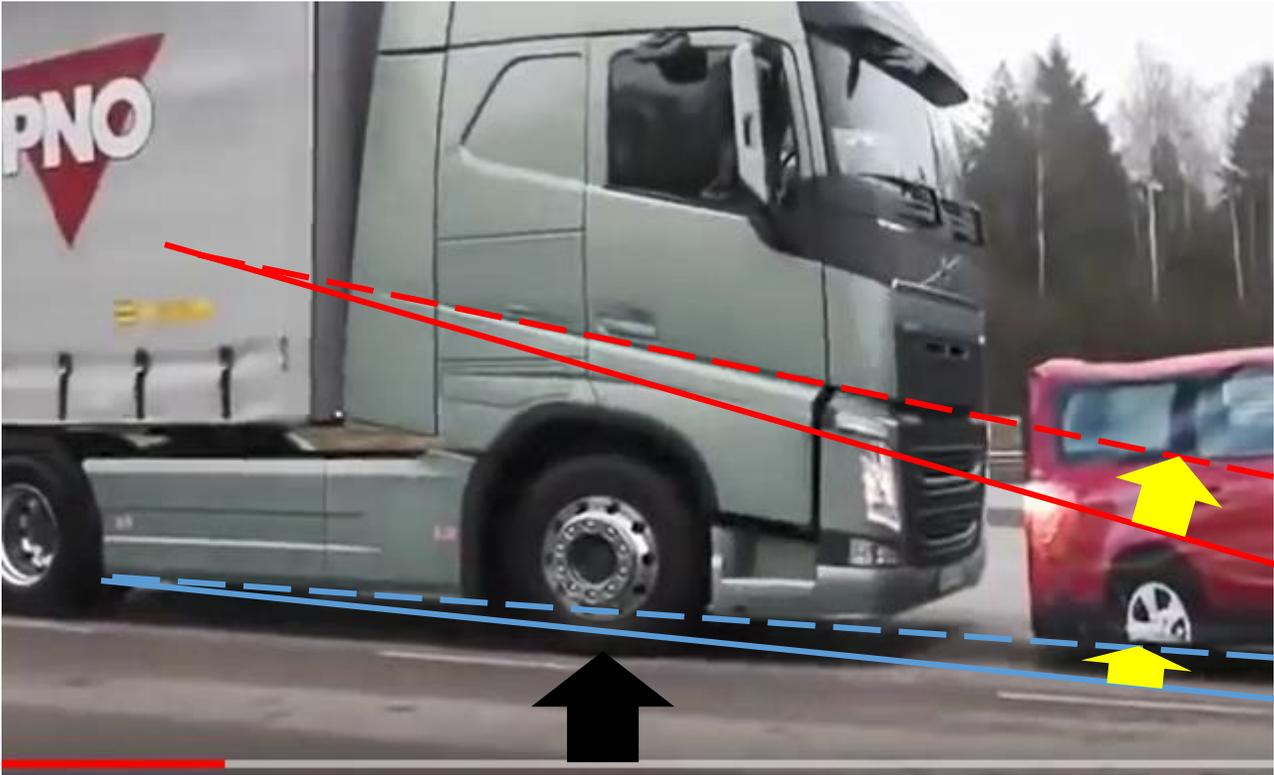


Dynamic variation of cab angle (camera)

Dynamic variation of chassis angle (radar)

4. The example of “Chassis-Cab angle dynamic variation”

2

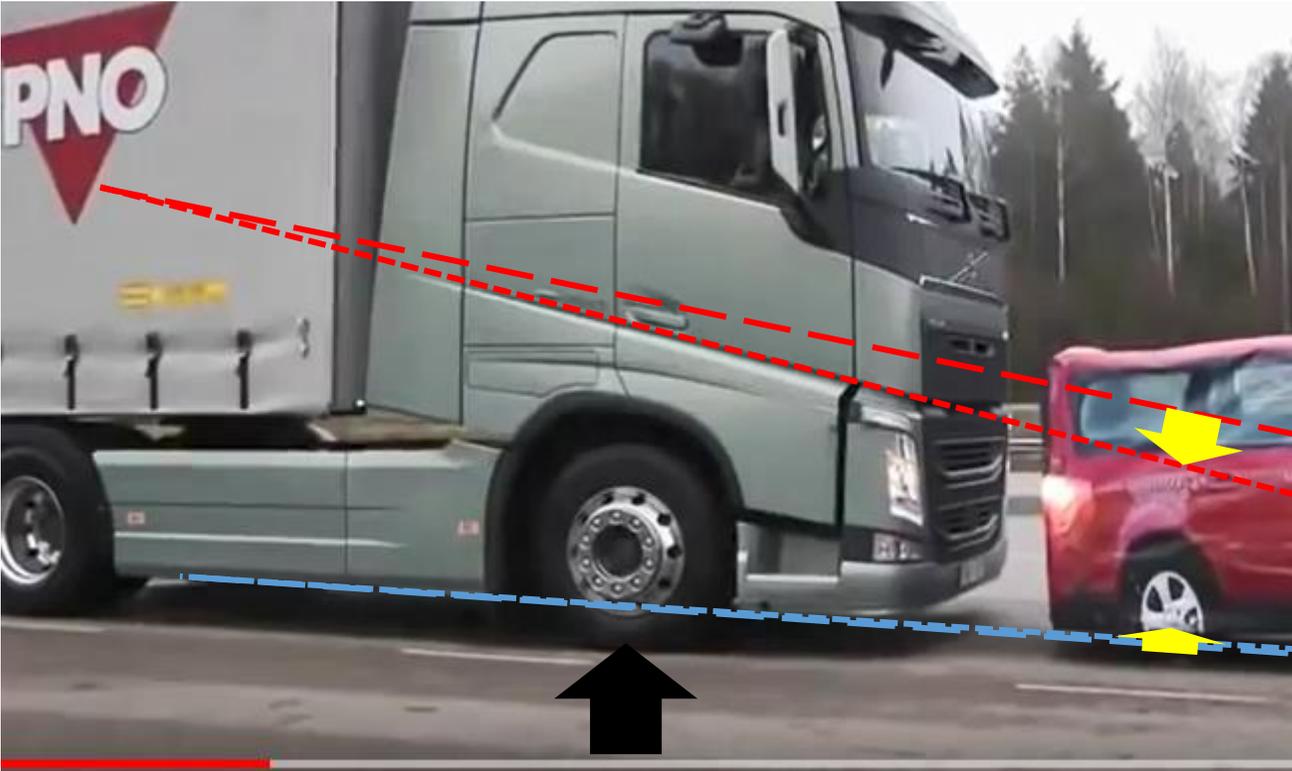


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3

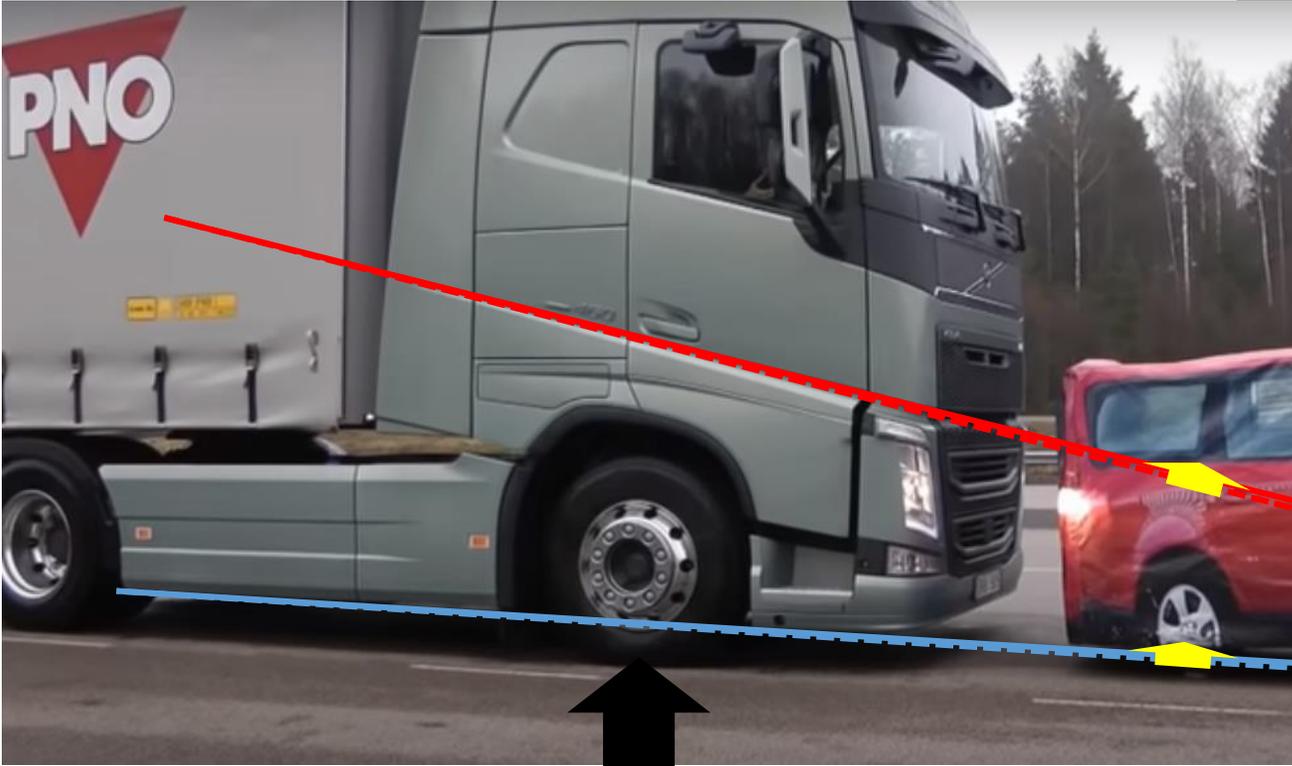


Dynamic variation of cab angle (camera)

Dynamic variation of chassis angle (radar)

4. The example of “Chassis-Cab angle dynamic variation”

4



Dynamic variation of cab angle (camera)

Dynamic variation of chassis angle (radar)

This construction affects the quality and speed of the detection

Intermediate Conclusions

- Complexity of HDVs, with comparison to PCs
 - High diversity of technical variants / models / ranges
 - High variability of usages (e.g. load, COG height, trailer(s))
 - Complex construction (e.g. chassis/cab suspensions)
 - Multi-stage built (add-on of axles, lengthening of wheelbase..., after the production line)
- The more complex the product...
The more efforts to fine-tune AEBS for each and every variants / usage
 - To find the right balance between “intrusive” and “necessary” interventions
 - To ensure robustness of the performance

Strategic views

Strategic views

- First City-AEB appeared on the market around 2010
- UN R152 entered into force in 2020 (with NR dates in 2024 / 26)

Medium range



PCs

HDVs

- First City-AEB appeared on the market around 2010
- UN R131 entered into force in 2013 (NR step 2 2018 in EU)

- **City-AEB ~not available on the market**
- **HDV manufacturers need time to build experience (same way as PCs did)**
- **HDVs cannot challenge the new Electronic and sensor architecture currently under development for VRU Proxi**

Current HDV industry efforts are put on the implementation of VRU-Proxi systems for NT 2022, NR 2024

VRU Direct vision coming in 2026 (NT) / 2029 (NR), in EU

Long range

Medium range

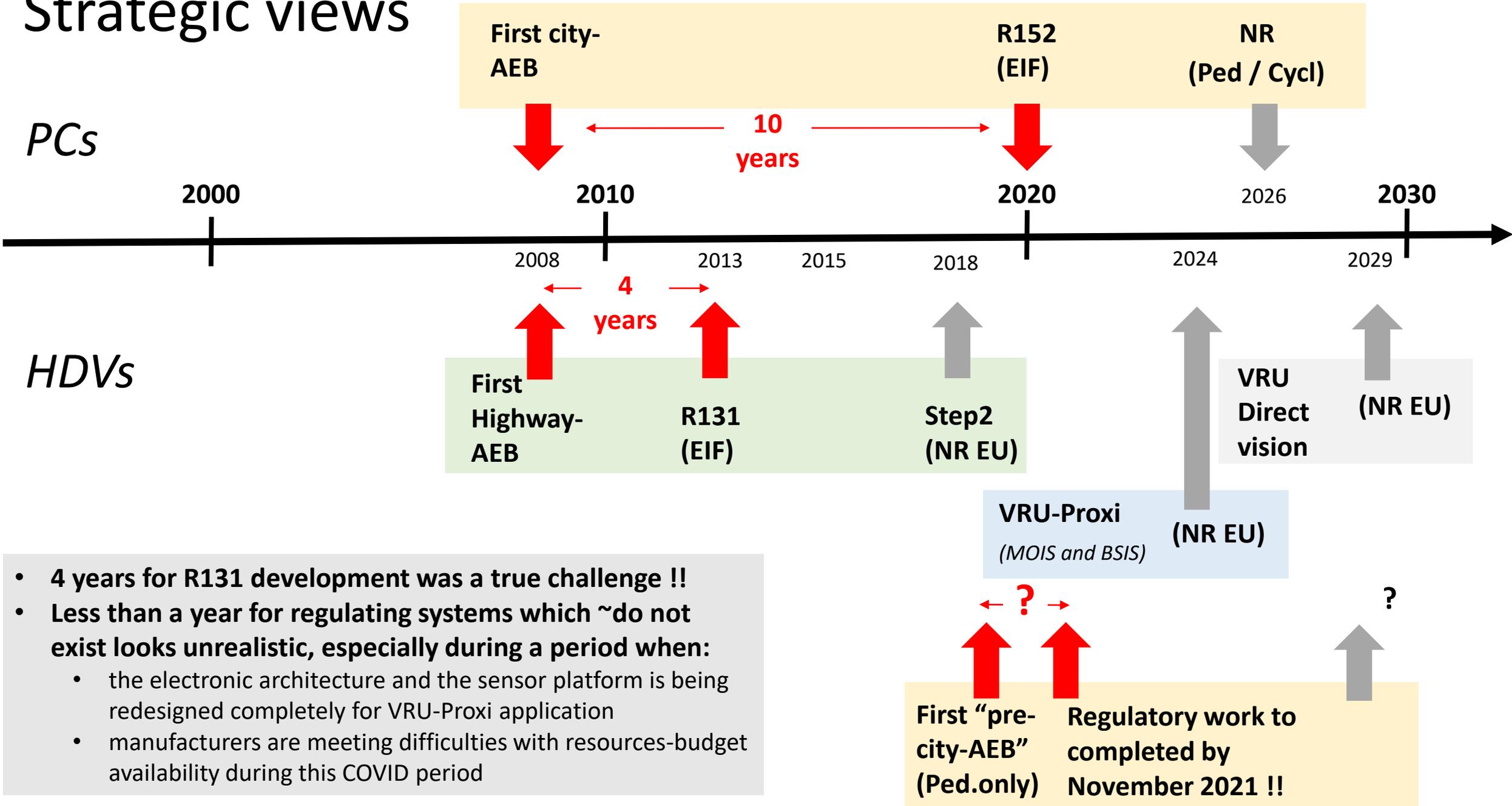
Short range



Strategic views

PCs

HDVs



- **4 years for R131 development was a true challenge !!**
- **Less than a year for regulating systems which ~do not exist looks unrealistic, especially during a period when:**
 - the electronic architecture and the sensor platform is being redesigned completely for VRU-Proxi application
 - manufacturers are meeting difficulties with resources-budget availability during this COVID period

Industry recommendation

Industry recommendation

Stepwise approach needed:

1. Focus on “vehicle to vehicle” collisions (“highway-AEB”) within the proposed timeframe
2. Gain technical experience and complete item 1 before start regulating City-VRU-AEB
3. Group application dates (NT / NR) to avoid multiple changes of the product

Thanks for your attention