

Proposal for amendments to amend UN Regulation No. 157

These are the proposals to clarify certain provisions within the regulation.

Modifications to the existing text of UN-Regulation No. 157 are underline for new or ~~striketrough~~ for deleted characters.

1. Proposal

Paragraph 2.5, amended to read:

“2.5. “Unplanned event” is a situation which is unknown in advance, but assumed as very likely in happening, ~~e.g. road construction, inclement weather, approaching emergency vehicle, missing lane marking, load falling from truck (collision)~~ and which requires a transition demand. This may include: road construction, inclement weather, approaching emergency vehicles/enforcement vehicles, missing lane markings, load falling from truck.”

Paragraph 5.1.1 and 5.1.2, amended to read:

- “5.1.1. The activated system shall perform the DDT shall manage all situations including failures, and shall be free of unreasonable risks for the vehicle occupants or any other road users.

The activated system shall not cause any collisions that are reasonably foreseeable and preventable. If a collision can be safely avoided without causing another one, it shall be avoided. When the vehicle is involved in a ~~detectable~~ significant collision with another road user while ALKS is active, the ~~vehicle control strategy shall be brought to bring the vehicle to a standstill.~~
- 5.1.2. The activated system shall comply with traffic rules relating to the DDT in the country of operation, including responding to emergency/enforcement vehicles.”

Annex 5, Paragraph 5.2 (table), amended to read:

“...

Reference in main text	Test/Check
...	...
5.1.1.	System reaction in case of a detectable <u>significant collision</u>
...	...”
