### 7.1.1. Forward detection range

The manufacturer shall declare the forward detection range measured from the forward most point of the vehicle. This declared value shall be at least 46 metres for a specified maximum speed of $60 \mathrm{~km} / \mathrm{h}$.

A specified maximum speed above $60 \mathrm{~km} / \mathrm{h}$ shall only be declared by the manufacturer, if the declared forward detection range fulfils the corresponding minimum value according the following table based on deceleration of $\mathbf{5 m} / \mathrm{s} \mathbf{2}$ :

|  | Minimum forward detection |
| :---: | :---: |
| Specified maximum speed / | range / |
| km/h | $m$ |
| $0 . . .60$ | 46 |
| 70 | 50 |
| 80 | 60 |
| 90 | 75 |
| 100 | 90 |
| 110 | 110 |
| 120 | 130 |
| 130 | 150 |
| For values not mentioned in the table, linear interpolation shall be applied. |  |
| It is recognized that the minimum forward detection range and vehicle |  |
| deceleration of $5 \mathrm{~m} / \mathrm{s} 2$ cannot be achieved under all conditions (e.g on slippery roads). The system shall implement control strategies to adapt its |  |
| maximum speed due the actual detection range and the actual |  |
| deceleration capability to comply with paragraph 5.2.4. Those strategies |  |
| shall be demonstrated and approved by the Technical Service. |  |
| The Technical Service shall verify that the distance at which the vehicle sensing system detects a road user during the relevant test in Annex 5 is equal or greater than the declared value. |  |

