Proposal for an Approach to Defining Rules of the Road: United Kingdom Proposal

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Motivation

FIRST PART: ADS Safety Topics

FRAV DDT Workstream

The ADS should drive safely

- 1. The ADS should be capable of performing the entire Dynamic Driving Task (DDT)
- 2. The ADS should recognize the ODD conditions and boundaries of the ODD of its feature(s)
- 3. The ADS should detect and respond to objects and events relevant for the DDT
- 4. The ADS should comply with traffic rules
- 5. The ADS should interact safely with other road users

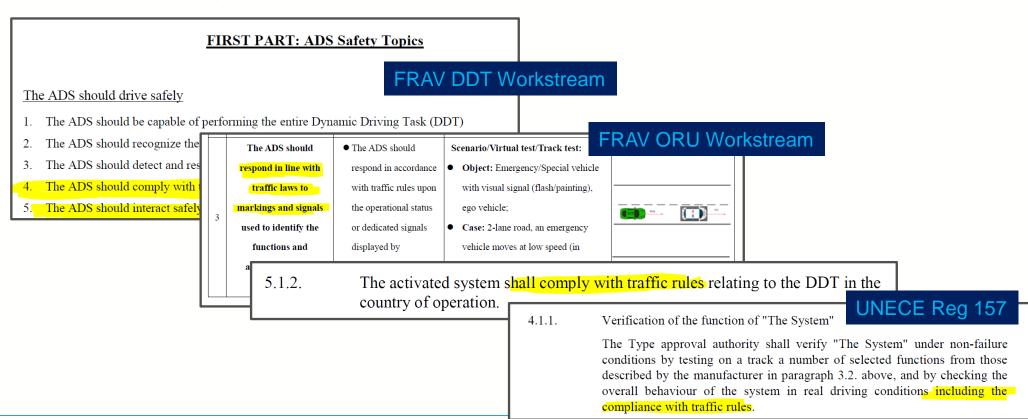


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FIRST PART: ADS Safety Topics FRAV DDT Workstream The ADS should drive safely The ADS should be capable of performing the entire Dynamic Driving Task (DDT) FRAV ORU Workstream The ADS should recognize the The ADS should • The ADS should Scenario/Virtual test/Track test: The ADS should detect and res respond in line with respond in accordance • Object: Emergency/Special vehicle The ADS should comply with with traffic rules upon with visual signal (flash/painting), traffic laws to 5. The ADS should interact safely markings and signals the operational status ego vehicle; used to identify the or dedicated signals • Case: 2-lane road, an emergency displayed by vehicle moves at low speed (in functions and emergency/enforceme operational state) ahead while test authorizations of vehicle drives in the same lane. ORUs. nt vehicles.



Motivation



Rules of the Road (for human drivers)

- UK Highway code (for human drivers) rule defines:
 - Doing some behaviour somewhere
 - NOT doing some behaviour somewhere
- Doing/not doing: Behaviour competency library
- Somewhere: ODD instantiation

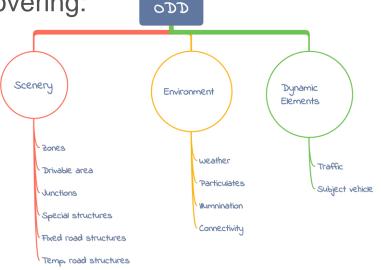


Rules of the Road (for human drivers)

Understanding ODD

■ BSI PAS 1883 provides an ODD taxonomy covering:

- Scenery
- Environmental conditions
- Dynamic elements





When reaching the roundabout you should

- give priority to traffic approaching from your right, unless directed otherwise by signs, road markings or traffic lights
- check whether road markings allow you to enter the roundabout without giving way. If so, proceed, but still look to the right before joining
- watch out for all other road users already on the roundabout; be aware they may not be signalling correctly or at all
- look forward before moving off to make sure traffic in front has moved off.



Rule 185: Follow the correct procedure at roundabouts

Behaviour

ODD



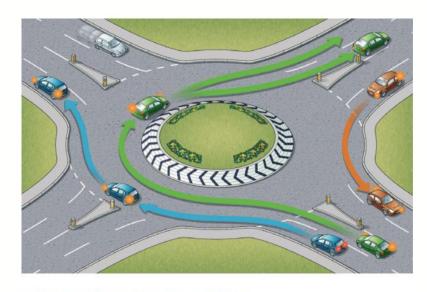
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- ASSUMPTIONS: by the driver or from the driver



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Weather?

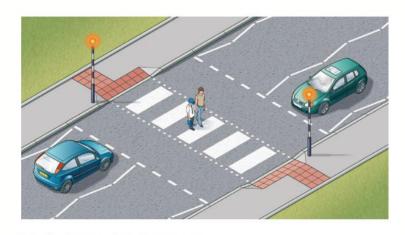
Behaviour

ODD

Assumptions



"As you approach a zebra crossing: look out for pedestrians waiting to cross and be ready to slow down or stop to let them cross; you MUST give way when a pedestrian has moved onto a crossing"



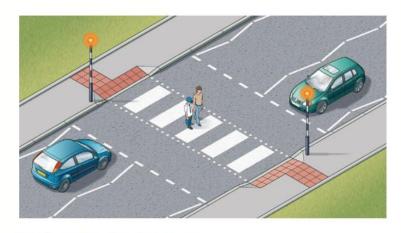
Rule 19: Zebra crossings have flashing beacons

Behaviour

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"As you approach a zebra crossing: look out for pedestrians waiting to cross and be ready to slow down or stop to let them cross; you MUST give way when a pedestrian has moved onto a crossing"



Rule 19: Zebra crossings have flashing beacons

How long to wait?

Behaviour

ODD

Assumptions



- Doing/not doing: Behaviour competency
 - Possible to create a behaviour competency library (e.g. Singapore, Waymo, NHTSA, WMG etc.)
- Somewhere: ODD instantiation
 - Current highway code (for human drivers) rules have lot of assumptions (e.g. weather, connectivity, traffic density, waiting time etc.)
 - These will need to be reflected explicitly into a codified rules of the road for ADS



Current Rules of Road (for human drivers) = f(Operating condition, Behaviour competency, Assumptions)



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Codified
Rule of the Road

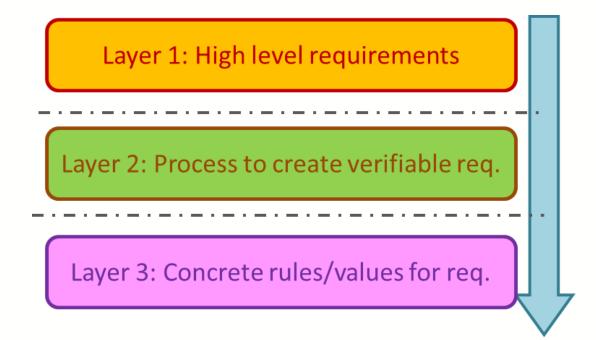
= f(Operating condition, behaviour competency, driving characteristics)



Steps

- Identification of elements: ODD and Behaviour competency
- Consolidation
- Formalisation to make the "assumptions" explicit







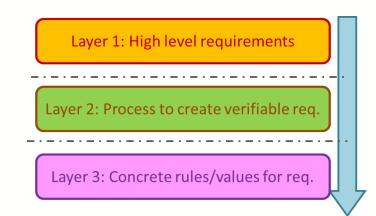
Layer 1: High Level FRAV requirements (harmonised)

FIRST PART: ADS Safety Topics

FRAV DDT Workstream

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FRAV DDT Workstream

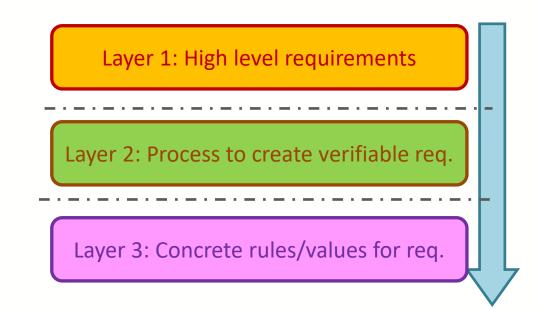
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- Scenario/Virtual test/Track test
 - FRAV ORU Workstream Object: Emergency/Special ve with visual signal (flash/painting), ego vehicle:
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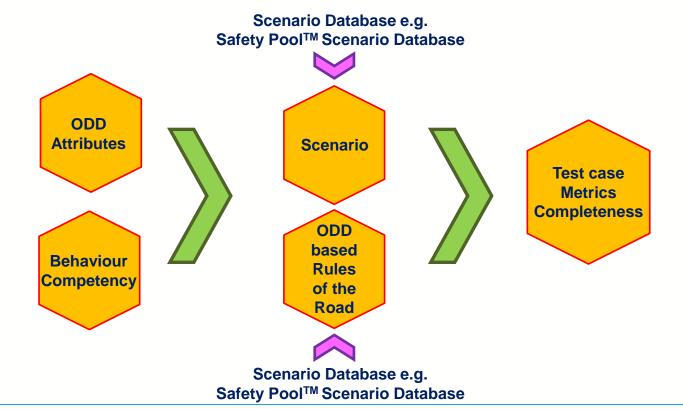
Layer 3: Concrete rules/values for req.



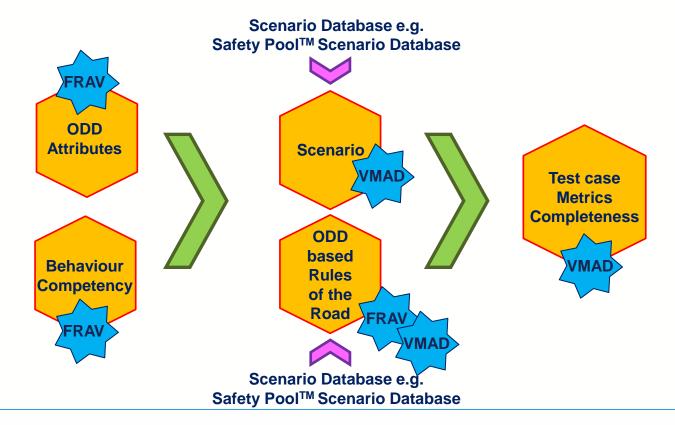
- Layer 1: High Level FRAV requirements (harmonised)
 - DDT
 - DDT relevant safety requirements
 - ORU related general safety requirements
- Layer 2: Process for creating detailed verifiable requirements from Layer 1 requirements
 - Proposal to harmonise
- Layer 3: Concrete rules or values for requirements
 - May not be harmonised due to diverse ODDs and behaviours













Advantages of this approach

- Comprehensive approach to define "rules of the road"
 - Rules themselves may differ (depending on country, ODDs, local factors), but the approach for creating the rules can be harmonised
- Guidance on interplay between FRAV and VMAD activities
 - For FRAV: for deriving functional requirements (detailed from rules of road)
 - For VMAD: define pass/fail criteria for scenarios (linking with ODD and behaviour)
- Being an ODD based approach, it is scalable across variety of ODDs
- The UK would like to make the proposed process (and the outputs) open source with all material openly accessible for all stakeholders





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