**Economic Commission for Europe**

Inland Transport Committee

**World Forum for Harmonization of Vehicle Regulations**

**Working Party on Noise and Tyres**

**Seventy-second session**

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Item 3 of the provisional agenda

**UN Regulation No. 51 (Noise of M and N categories of vehicles)**

 Proposal for a Supplement 10 to UN R51.03

Submitted by the Informal Working Group on Additional Sound Emission Provisions[[1]](#footnote-1)\*

 The text reproduced below was prepared by the experts from the Informal Working Group on Additional Sound Emission Provisions (IWG ASEP) in order to improve the current wording for better clarification. Changes as proposed are based on the Supplement 6 to the 03 Series of amendment to the Regulation No.51.

The modifications are marked in bold for new or strikethrough for deleted characters.

1. Proposal

 *Main Body, Paragraph 2.8.*, amend to read:

2.8. "*~~Rated~~* *Maximum net power, Pn*" means the engine power **available for propulsion** expressed in kW and measured **dependent on the drive train concepts** ~~pursuant to UN Regulation No. 85~~.

**Applicable power sources are those, which provide drive power for forward motion to the vehicle.**

**2.8.1.** ~~If two or more sources of propulsive power operate at the conditions of test specified in Annex 3 to this Regulation, the total engine power, P~~~~n~~~~, shall be the arithmetic sum of parallel propulsive engines on the vehicle.~~

~~Applicable parallel propulsive engines are those power sources, which provide forward motion to the vehicle in combination at the conditions of test, specified in Annex 3 to this Regulation.~~

~~The specified power for non-combustion engines shall be the power stated by the vehicle manufacturer.~~

**For vehicles with combustion engine(s) only (ICE)**

**The maximum engine power is the net power Pn of the combustion engine(s) measured at full engine load pursuant to UN Regulation No.85 paragraph 5.2.**

**2.8.2. For battery electric vehicles (BEV) or fuel cell electric vehicle (FCEV) that have only one propulsion energy converter**

**The net power Pn of the electric motor of the electric drive train is determined pursuant to UN Regulation No.85 paragraph 5.3.**

**2.8.3. For hybrid electric vehicles (HEV) [where at least one electric machine contributes to propulsion], or pure electric vehicles that have more than one propulsion energy converter**

**The maximum engine power is the "vehicle system power rating" according to the arithmetic sum of parallel propulsive engines on the vehicle or GTR 21, paragraph 6.9.1.(b) “sustained vehicle system power”.**

*Main Body, Paragraph 2.24.*, amend to read:

2.24. Table of symbols

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| […] |  |  |  |  |
| k | — | Annex 3 | 3.1.2.1.4.1. | gear ratio weighting factor; value to be reported and used for calculations to the second decimal place |
| **nMAX** | **1/min** | **Annex 3** | **3.1.2.1.4.1.** | **Maximum engine rotational speed permitted for M1, N1, and M2 less than 3500 kg; value to be reported and used for calculations to a precision of 10 min-1 (xxx0)** |
| S | 1/min | Annex 3 | **3.1.2.1.4.1** | rated engine rotational speed in revs per minute, synonymous with the engine rotational speed at maximum power |
| nBB' | 1/min | Annex 3 | 3.1.2.2. | engine rotational speed of the vehicle, when the reference point passes BB'; value to be reported and used for calculations to a precision of 10 min-1 |
| […] |  |  |  |  |
| nBB' | 1/min | Annex 3 | 3.1.2.2. | engine rotational speed of the vehicle, when the reference point passes BB'; value to be reported and used for calculations to a precision of 10 min-1 |
| ~~S~~ | ~~1/min~~ | ~~Annex 3~~ | ~~3.1.2.2.~~ | ~~rated engine rotational speed in revs per minute, synonymous with the engine rotational speed at maximum power~~ |
| ntarget BB' | 1/min | Annex 3 | 3.1.2.2.1.1.(a) | target engine rotational speed of the vehicle when the reference point has to pass line BB' (see 2.11.2. for definition of reference point) |
| […] |  |  |  |  |

*Main Body, Paragraph 6.1.*, amend to read:

6. Specifications

6.1. General specifications **for durability and against manipulation**

6.1.1. The vehicle, its engine and its sound reduction system shall be so designed, constructed and assembled as to enable the vehicle, in normal use, despite the vibration to which it may be subjected, to comply with the provisions of this Regulation.

6.1.2. The sound reduction system shall be so designed, constructed and assembled as to be able to reasonably resist the corrosive phenomena to which it is exposed having regard to the conditions of use of the vehicle, including regional climate differences**, and against manipulation**.

 *Annex 3, Paragraph 2.1.2.*, amend to read:

2.1.2. Test Site Indoor

Test Site Indoor requirements shall be as specified below.

1. The test room dimensions are described in paragraph 7.2. of ISO 362-3:2016 **or later**. All room dimensions may be adjusted to meet the specific application for the products being tested according to Annex 8, paragraph 4.
2. The test facility shall meet the requirements of ISO 26101:2012 **or later** with the qualification criteria and measurement requirements appropriate to this test method as described in ISO 362-3:2016 **or later**, paragraph 7.3.
3. Condition of the floor is described in ISO 362-3:2016 **or later**, paragraph 7.4.
4. Cooling, ventilation, and exhaust gas management are described in ISO 362-3:2016 **or later**, paragraph 7.5.
5. Dynamometer requirements are described in ISO 362-3:2016 **or later**, paragraph 8.
6. Vehicle fixing system is described in ISO 362-3:2016 **or later**, paragraph 9.3.

 *Annex 3, Paragraph 3.*, amend to read:

3. Methods of testing

Outdoor tests shall be performed according to paragraph 3.1.

Indoor tests shall be performed according to paragraph 3.1. using the specifications of ISO 362-3:2016 **or later**, variant A. For indoor application, the manufacturer shall provide to the technical service, documentation according to Annex 8, paragraph 1. Variant A is a combination of indoor testing (power train sound) and outdoor testing (tyre/road sound).

 *Annex 3, Paragraph 3.1.1.*, amend to read:

3.1.1. General conditions of test

 For outdoor testing, two lines, AA' and BB', parallel to line PP' and situated respectively 10 m ± 0.05 m forward and 10 m ± 0.05 m rearward of line PP’ shall be marked out on the test runway.

For indoor testing, the virtual line AA' indicates the beginning of the test track, PP' indicates the virtual position of the two pass-by microphones, and BB' indicates the end of the test track. The simulated vehicle speed at AA', *vAA'*, or vehicle speed at PP', *vPP'*, is defined by the roller speed when the reference point of the vehicle passes the virtual line AA' or PP', respectively. The simulated vehicle speed at BB', *vBB'*, is defined when the rear of the vehicle passes the virtual line BB'.

 At least four measurements shall be made on each side of the vehicle and for each gear. Preliminary measurements may be made for adjustment purposes, but shall be disregarded.

 The microphone**s** shall be located **on both sides of the pathway** at a distance of 7.5 m ± 0.05 m from the reference line CC' of the track and 1.2 m ± 0.02 m above the ground.

 The reference axis for free field conditions (see IEC 61672-1:2002) shall be horizontal and directed perpendicularly towards the path of the vehicle line CC'.

 *Annex 3, Paragraph 3.1.2.1.4.1.*, amend to read:

3.1.2.1.4.1. Vehicles with manual transmission, automatic transmissions, adaptive transmissions or CVTs tested with locked gear ratios

 The following conditions for selection of gear ratios are possible:

(a) If one specific gear ratio gives an acceleration in a tolerance band of ±5 per cent of the reference acceleration *a****wot\_ref***, not exceeding 2.0 m/s2, test with that gear ratio.

(b) If none of the gear ratios give the required acceleration, then choose a gear ratio i, with an acceleration higher and a gear ratio i+1, with an acceleration lower than the reference acceleration. If the acceleration value in gear ratio i does not exceed 2.0 m/s2, use both gear ratios for the test. The weighting ratio in relation to the reference acceleration *awot\_ref* is calculated by:

 k = (awot\_ref – awot**\_**(i+1))/(awot**\_**(i) – awot**\_**(i+1))

(c) If the acceleration value of gear ratio i exceeds 2.0 m/s2, the first gear ratio shall be used that gives an acceleration below 2.0 m/s2 unless gear ratio i+1 (or i+2, or i+3 or …) provides acceleration less than *aurban*. In this case, two gears, i and i+1 (or i+2, or i+3 or …) shall be used, including the gear i with acceleration exceeding 2.0 m/s2. In other cases, no other gear shall be used. The achieved acceleration *a****wot\_test*** during the test shall be used for the calculation of the part power factor kP instead of *awot\_ref*.

(d) If **maximum** ~~rated~~ engine speed ***nMAX*** is exceeded in a gear i before the vehicle passes BB' the next higher gear i+1 shall be used. If the next higher gear i+1 results in an acceleration below *aurban*, the vehicle test speed, *vtest*, in the gear ratio i shall be reduced by 2.5 km/h and the gear ratio selection shall proceed as specified by the options given in this paragraph. In no case shall the vehicle test speed be reduced below 40 km/h.

If the **maximum** ~~rated~~ engine speed ***nMAX*** is exceeded in gear ratio i before the vehicle passes BB' and the vehicle test speed is equal to 40 km/h, the higher gear ratio i+1 is allowed even if *awot\_test* does not exceed *aurban*.

The vehicle test speed in the higher gear ratio i+1 shall be 50 km/h.

**The maximum engine speed *nMAX* is given by the formula below:**

$n\_{MAX}=1.56 ×PMR^{-0.227}×S$**, but not more than 80% of S.**

(e) If no gear ratio is available with an acceleration below 2.0 m/s², the manufacturer shall, if possible take measures to avoid an acceleration value *awot\_test* greater than 2.0 m/s².

Table 1 in Appendix to Annex 3 provides examples for valid measures to control the downshift of gears or to avoid accelerations beyond 2.0 m/s². Any measure used by manufacturer for the above-mentioned purposes shall be documented in the test report.

 *Annex 3, Paragraph 3.1.2.1.4.2.*, amend to read:

3.1.2.1.4.2. Vehicles with automatic transmission, adaptive transmissions and CVTs tested with non-locked gear ratios:

 **Manufacturers may take measures to lock discrete gear ratios by electronic or mechanical measures and follow the gear selection previsions of paragraph 3.1.2.1.4.1. above. If so selected, this shall be stated in the test report.**

**Otherwise, t**he gear selector position for full automatic operation shall be used.

 The acceleration value *awot\_test* shall be calculated as defined in paragraph 3.1.2.1.2.2.

 The test may then include a gear change to a lower range and a higher acceleration **or a higher engine speed**. A gear change to a higher range and a lower acceleration is not allowed. A gear shifting to a gear ratio which is not ~~used in~~ **representative for** urban traffic shall be avoided.

 Therefore, it is permitted to establish and use electronic or mechanical devices, including alternate gear selector positions, to ~~prevent a downshift to a gear ratio which is typically not used for the specified test condition in urban traffic~~ **avoid:**

**- accelerations beyond 2.0 m/s². Any measure used by manufacturer for the above-mentioned purposes shall be documented in the test report.** The achieved acceleration *awot\_test*shall be greater or equal to *aurban*.

**- a test engine speed exceeding *nMAX* (see Appendix 1, figure 4f).**

**o Therefore, the vehicle test speed *vtest* may be reduced in steps by 2.5 km/h. In no case the vehicle test speed shall be reduced to a vehicle speed below 40 km/h, or**

**o The engine load is reduced to avoid** a downshift to a gear ratio **where *nMAX* is exceeded**.

 If possible, the manufacturer shall take measures to avoid an acceleration value *awot\_test* greater than 2.0 m/s2.

 **If possible, the manufacturer shall take measures to avoid an engine speed higher than *nMAX*.**

 Table 1 in Appendix to Annex 3 provides examples for valid measures to ~~control the downshift of gears or to avoid accelerations beyond 2.0 m/s²~~ **enable a test condition within the above specified boundaries**. Any measure used by manufacturer for the above-mentioned purposes shall be documented in the test report.

The achieved acceleration *awot\_test* is then used for the calculation of the partial power factor kP (see paragraph 3.1.2.1.3.) instead *awot\_ref*.

*Annex 3, Paragraph* ***3.1.2.1.6.***, amend to read:

3.1.2.1.6. Constant speed test

The constant speed test shall be carried out with the same gear(s) specified for the acceleration test and a constant speed of 50 km/h with a tolerance of ±1 km/h between AA' and BB', or if applicable at the speed determined for the acceleration test according 3.1.2.1.4.1. (d) **or 3.1.2.1.4.2.** with a tolerance of ±1 km/h between AA' and BB'.

During the constant speed test, the acceleration control shall be positioned to maintain a constant speed between AA' and BB' as specified. If the gear is locked for the acceleration test, the same gear shall be locked for the constant speed test.

The constant speed test is not required for vehicles with a PMR < 25.

 *Annex 3, Paragraph 3.1.3.1.*, amend to read:

3.1.3.1. Vehicles of categories M1, N1 and M2 ≤ 3,500 kg technically permissible maximum laden mass

 The calculated values for the acceleration test and the constant speed test are given by:

 Lwot rep = Lwot (i+1) + k \* (Lwot(i) – Lwot (i+1))

 Lcrs rep = Lcrs(i+1) + k \* (Lcrs (i) – Lcrs (i+1))

 Where k = (awot ref – awot (i+1))/(awot (i) – awot (i+1))

 In the case of a single gear ratio test the values are the test result of each test.

 The final result is calculated by combining Lwot rep and Lcrs rep. The equation is:

 Lurban = Lwot rep – kP \* (Lwot rep – Lcrs rep)

 The weighting factor kP gives the part power factor for urban driving. In cases other than a single gear test, kP is calculated by:

 kP = 1 – (aurban / awot ref)

 If only one gear was specified for the test, kP is given by:

 kP = 1 – (aurban / awot test)

 In cases where awot test is less than aurban:

 kP = 0

 **In case of a vehicle with a PMR < 25, the final result** ***Lurban* is equal to *Lwot\_rep*.**

*Annex 3 - Appendix, Figure 4b*, amend to read:

Figure 4b

**Flowchart for vehicles tested according to paragraph 3.1.2.1. of Annex 3 to this Regulation -
Gear selection using locked gear PART 1**

Select Gear

Is acceleration stable according to 2.26.2.?

Calculate test acceleration according to 3.1.2.1.2.1.

Select Pre-acceleration and entry speed

Yess

No

Is acceleration within *awot\_ref* **tolerance** band?

Yess

No

Is acceleration less than or equal 2,0 m/**s**2? and engine speed less than ***nMAX*** *~~S~~*prior to BB'?

Use gear and compute *k*P according to 3.1.3.1.

Compute *Lwot\_rep*using results of valid runs

No

Select gears to obtain gear *i* with stable acceleration above

*awot\_ref* and gear *i*+1 with stable acceleration below *awot\_ref*

See Case 2 in Figure 4c

See Case 1 in Figure 4c

Yess

Testing locked gears according to 3.1.2.1.4.1.

*Annex 3 - Appendix, Figure 4c*, amend to read:

Figure 4c

**Flowchart for vehicles tested according to paragraph 3.1.2.1. of Annex 3 to this Regulation –
Gear selection using locked gear PART 2**

Yess

No

Is acceleration of gear *i* less than or equal 2,0 m/**s**2? and engine speed less than ***nMAX*** *~~S~~* prior to BB’?

Use both gears *i* and *i*+1, (*i*+2, *i*+3, or*…* ) and compute *kP* according to 3.1.3.1. and *k* by 3.1.2.1.4.1.

Compute *Lwot\_rep*using results of valid runs

Case 1:

 Two gears, gear *i* with stable acceleration above *awot\_ref* and gear *i*+1 with stable acceleration below *awot\_ref*

Case 2:

 One gear with stable acceleration above 2,0 m/**s**2 or engine speed greater than ***nMAX*** *~~S~~* prior to BB'

Determine first gear *i* + n (n=1, 2…) with stable acceleration less than or equal to 2,0 m/**s**2 and engine speed less than ***nMAX*** *~~S~~* prior to BB'

Is acceleration of gear *i* +n more than *aurban*?

Yess

Use gear and compute *kP* according to 3.1.3.1.

No

Use both gears *i* with acceleration higher than 2,0 m/**s**2 and *i*+1, (*i*+2, *i*+3, or*…*) with acceleration less than *aurban*

Is engine speed of gear *i* more than ***nMAX*** ~~S~~ prior to BB’?

See Case 3 in Figure 4d

No

Yess

*Annex 3 - Appendix, Figure 4d*, amend to read:

Figure 4d

**Flowchart for vehicles tested according to paragraph 3.1.2.1. of Annex 3 to this Regulation –
Gear selection using locked gear PART 3**

Yess

No

Yes

Determine first gear *i* + n (n=1, 2, …) with stable acceleration less than or equal to 2,0 m/s² and engine speed less than *S* prior to BB’. Test with this gear at a speed, *vtest*, of 50 km/h

Reduce test speed *vtest* by 2,5 km/h with gear *i*

Test locked gears according to 3.1.2.1.4.1. with new test speed

Is engine speed of gear *i* less than ***nMAX*** *~~S~~* prior to BB’?

No

Case 3:

 No gear with acceleration more than *aurban* and engine speed less than ***nMAX*** *~~S~~* prior to BB’

Is test speed *vtest* 40 km/h?

*Annex 3 - Appendix, Figure 4e*, amend to read:

Figure 4e

**Flowchart for vehicles tested according to paragraph 3.1.2.1. of Annex 3 to this Regulation –
Gear Selection using non-locked gears**

**engine speed greater than *nMAX* prior to BB'**

**Yes**

Yess

No

Compute *Lwot\_rep*using results of valid runs

Calculate test acceleration according to 3.1.2.1.2.2. Pre-acceleration is not allowed

Compute *kP*according to 3.1.3.1.

Can measures be taken to control downshifts?

Is acceleration stable? i.e. there is no delay.

Calculate test acceleration according to 3.1.2.1.2.2.

Select Pre-acceleration and entry speed

No

Yess

If possible, control downshift to obtain acceleration less than or equal to 2,0 m/s2 or *awot\_ref*, whichever is lower. If not possible, run higher than 2,0 m/s2 is valid.

Testing unlocked gears according to 3.1.2.1.4.2.

Select entry speed

**No**

**See flowchart 4f.**

*Annex 3 - Appendix, new Figure 4f*, to read:

**Figure 4f**

**Flowchart for vehicles tested according to paragraph 3.1.2.1.4.2. of Annex 3 to this Regulation –
Gear Selection using non-locked gears**

**Possibility 2**

**Test according to 3.1.2.1.4.2. with specified engine load**

**Possibility 1**

**Yess**

**No**

**Yes**

**Not valid test condition.**

**Reduce test speed *vtest* by 2,5 km/h**

**Test according to 3.1.2.1.4.2. with new test speed**

**Is engine speed less than *nMAX* prior to BB’?**

**No**

**Engine speed exceed *nMAX* prior to BB’**

**Is test speed *vtest* 40 km/h?**

**Reduce engine load (by using partial load) such that *nBB’* is between 95 % *nMAX* and *nMAX***

**Yess**

*Annex 8, Introduction*, amend to read:

Annex 8

 Indoor testing

 **Indoor testing is only for Annex 3 and Annex 7 measurements.**

1. Documentation for indoor application

*Annex 8, Paragraph 2.2.*, amend to read:

2.2. Power train sound

It shall be ensured that there is no remaining tyre/road sound affecting the measurements. In any case it shall be ensured that the remaining tyre/road sound shall be at least 10 dB below the maximum A-weighted sound pressure level produced by the vehicle under test. If this condition cannot be fulfilled, a correction shall be carried out. This correction procedure is described in ISO 362-3:2016 **or later** Annex B, paragraph B.6.

The vehicle shall be measured according to the operating condition specified in paragraphs 3.1.2.1. or 3.1.2.2. of Annex 3 of this Regulation.

*Annex 8, Paragraph 2.4.*, amend to read:

2.4. Calculation of the total vehicle sound

The total vehicle sound is the energetical sum of tyre/road sound and power train sound. This calculation shall be carried out for each single run as describe in ISO 362-3.2016 **or later**, paragraph 10.2.4.

*Annex 8, Paragraph 3.*, amend to read:

3. Procedure for measurement, evaluation, and calculation of tyre/road sound when using variant A

All conditions for evaluation of tyre/road sound, free rolling sound, and torque influence are described in ISO 362-3:2016 **or later**, Annex B.

*Annex 8, Paragraph 4.*, amend to read:

4. Adjustment of room dimensions

To cater for the smaller size test rooms, the maximum levels shall be evaluated with caution though to avoid missing them according to ISO 362-3:2016 **or later**, Annex E.

**II. Justifications**

1. Paragraph 2.8 - " *Maximum net power, Pn*": for better clarity, the definition has been adjusted to each propulsion technology (ICE, BEV, HEV, FCEV).
2. Paragraph 2.24 – Table of symbols: addition of the symbol nMAX for Maximum engine rotational speed permitted for M1, N1, and M2 less than 3500 kg used for simplification in Annex 3 as 80% of S.
3. Provisions for durability and against manipulation have been introduced through: Paragraph 6. has been amended to clarify that the sound reduction system shall be designed, also against manipulation.
4. The amendment of the UN-R51-03 Supplement 6 introducing 20m behind the line BB’ is not yet taken into account in the current ISO362-3:2016. It is proposed to amend the reference to ISO as “ISO362-3:2016 **or later**” to make possible to use ISO as soon as it will be updated.

Annex 3, paragraphs 2.1.2., 3., 3.1., 3.3.3., and Annex 8, paragraphs 2.2., 2.4., 3., 4. have been amended accordingly.

1. Annex 3, Paragraph 3.1.: clarification related to the 2 microphones to be installed on the test track in line PP’ instead of 1 microphone as allowed in the past, for measurements in one run of both sides left/right. This change will allow to be more accurate.
2. Annex 3, Paragraph 3.1.2.3.4.1. (d): introduction of nMAX for simplification in Annex 3 as 80% of S.
3. Annex 3, Paragraph 3.1.2.1.4.2.: rewording related to non-locked gear ratio for clarification.
4. Annex 3, Paragraph 3.1.2.1.6.: update of numbering with addition of reference to Paragraph 3.1.2.1.4.2. mentioned above.
5. Annex 3, Paragraph 3.1.3.1.: clarification for the result of vehicles with PMR less of 25.
6. Annex 3, figures 4b to 4f updated according to the introduction of “nMAX” mentioned above.
1. \* In accordance with the programme of work of the Inland Transport Committee for 2020 as outlined in proposed programme budget for 2020 (A/74/6 (part V sect. 20) para 20.37), the World Forum will develop, harmonize and update UN Regulations in order to enhance the performance of vehicles. The present document is submitted in conformity with that mandate. [↑](#footnote-ref-1)