

# **Study on Camera Monitor Systems**

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**Informal Group on Camera Monitor Systems in Reg. No. 46**

Berlin, 27.03.2014

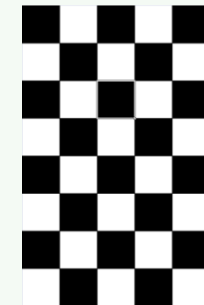
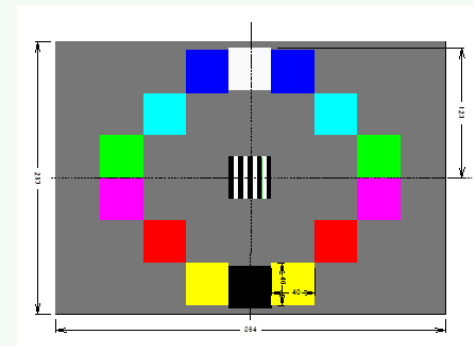
## Background

- Camera Monitor Systems may replace classical outside rearview mirrors...
  - ...allowing new design concepts / reduction of vehicle width
  - ...allowing a reduction of aerodynamic drag
- Evaluation of technical aspects as well as aspects concerning human machine interaction (HMI) in **comparison to a conventional outside rearview mirror** necessary

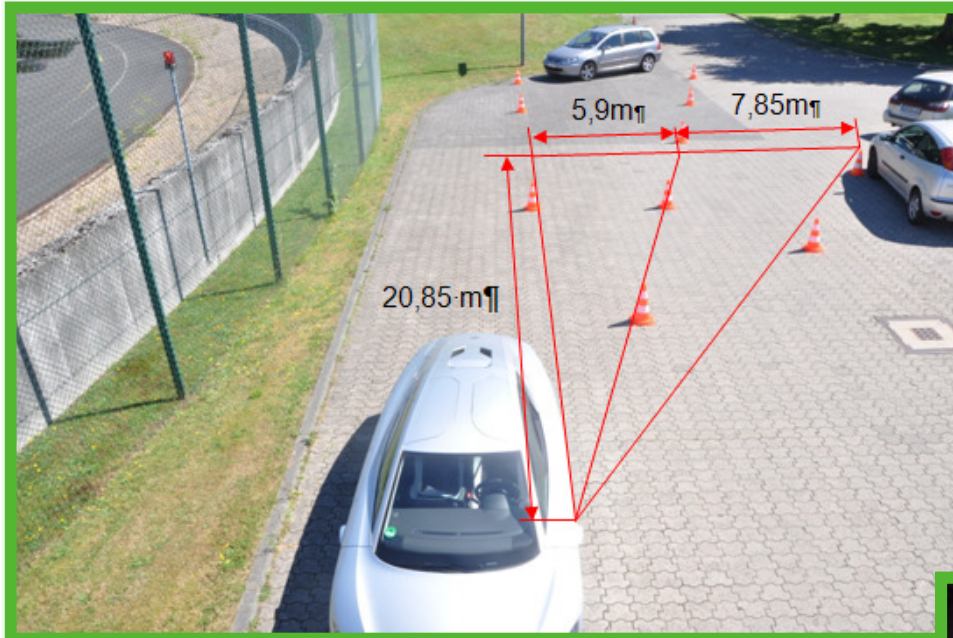


## Technical Aspects

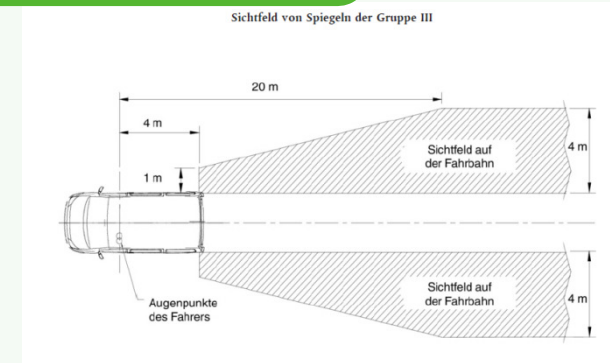
- Field of vision
- General day and night characteristics
- Image properties
- Glare
- Adjustability of camera and display
- Reliability
- Weather
- Robustness
- Exchangeability
- Energy Consumption



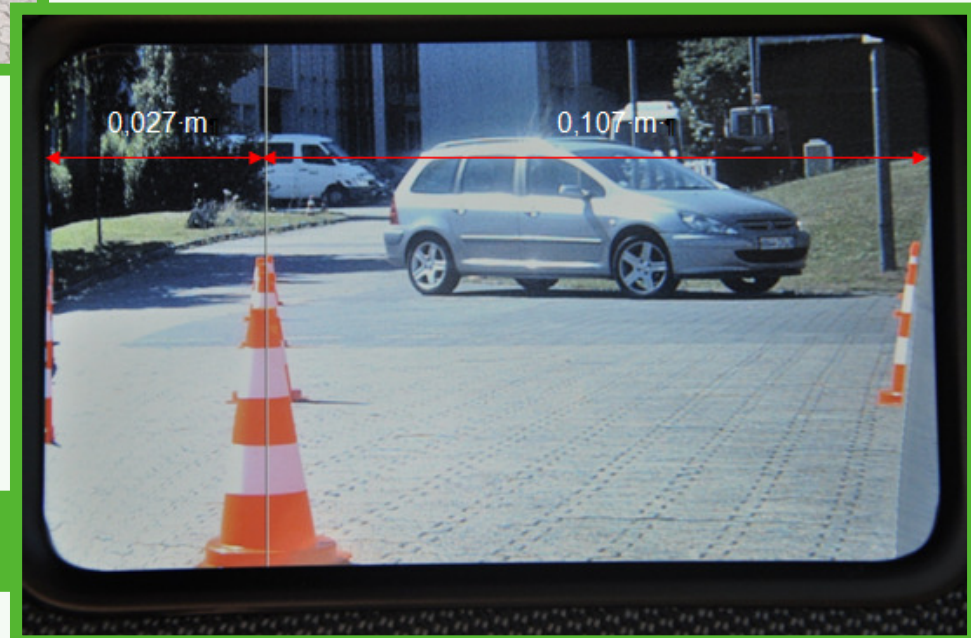
# Field of vision (XL1)



The required field of vision is met



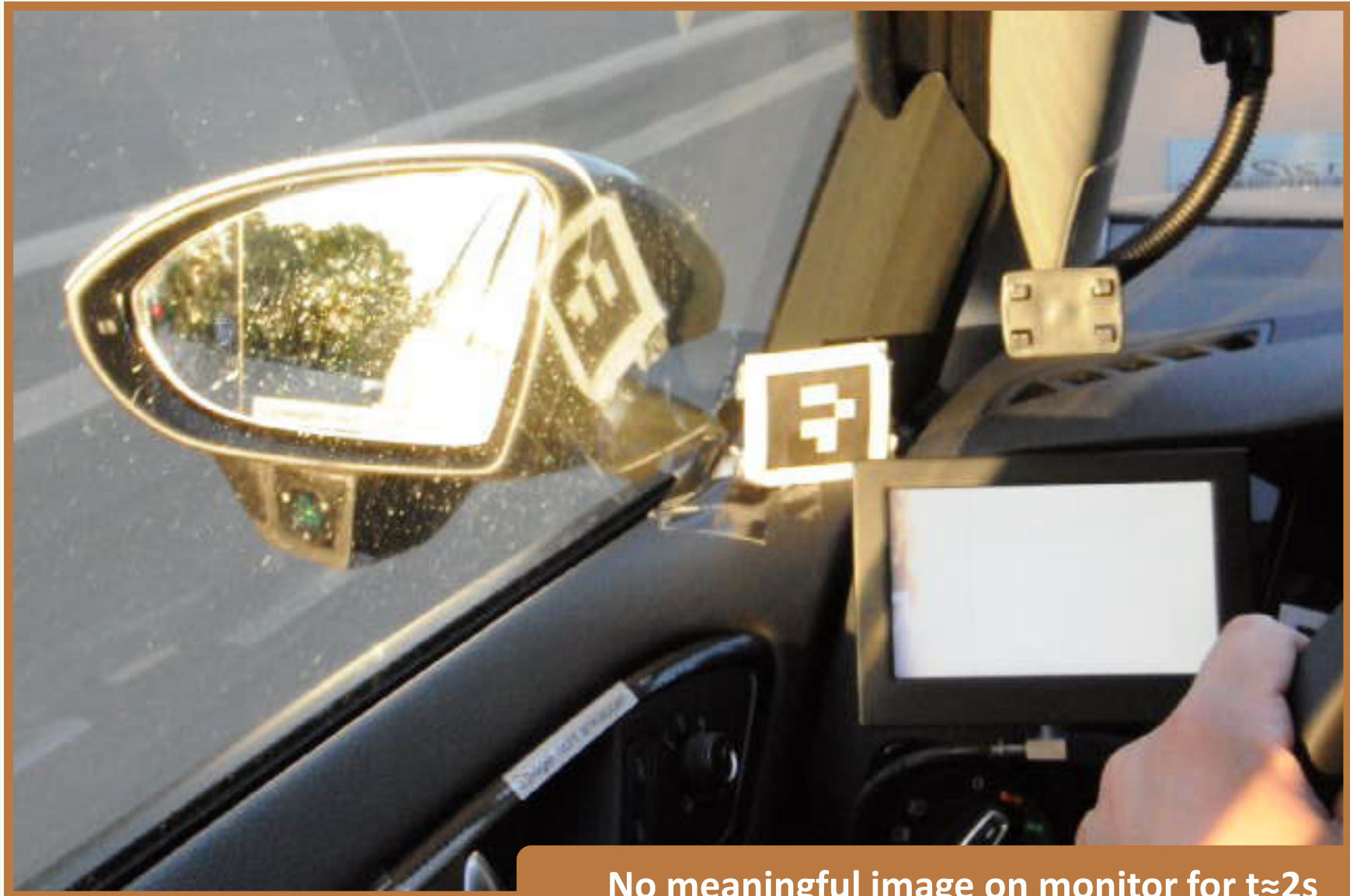
Blind spot is reduced





Vehicle „disappears“ for  $t \approx 1s$

# Direct sunlight

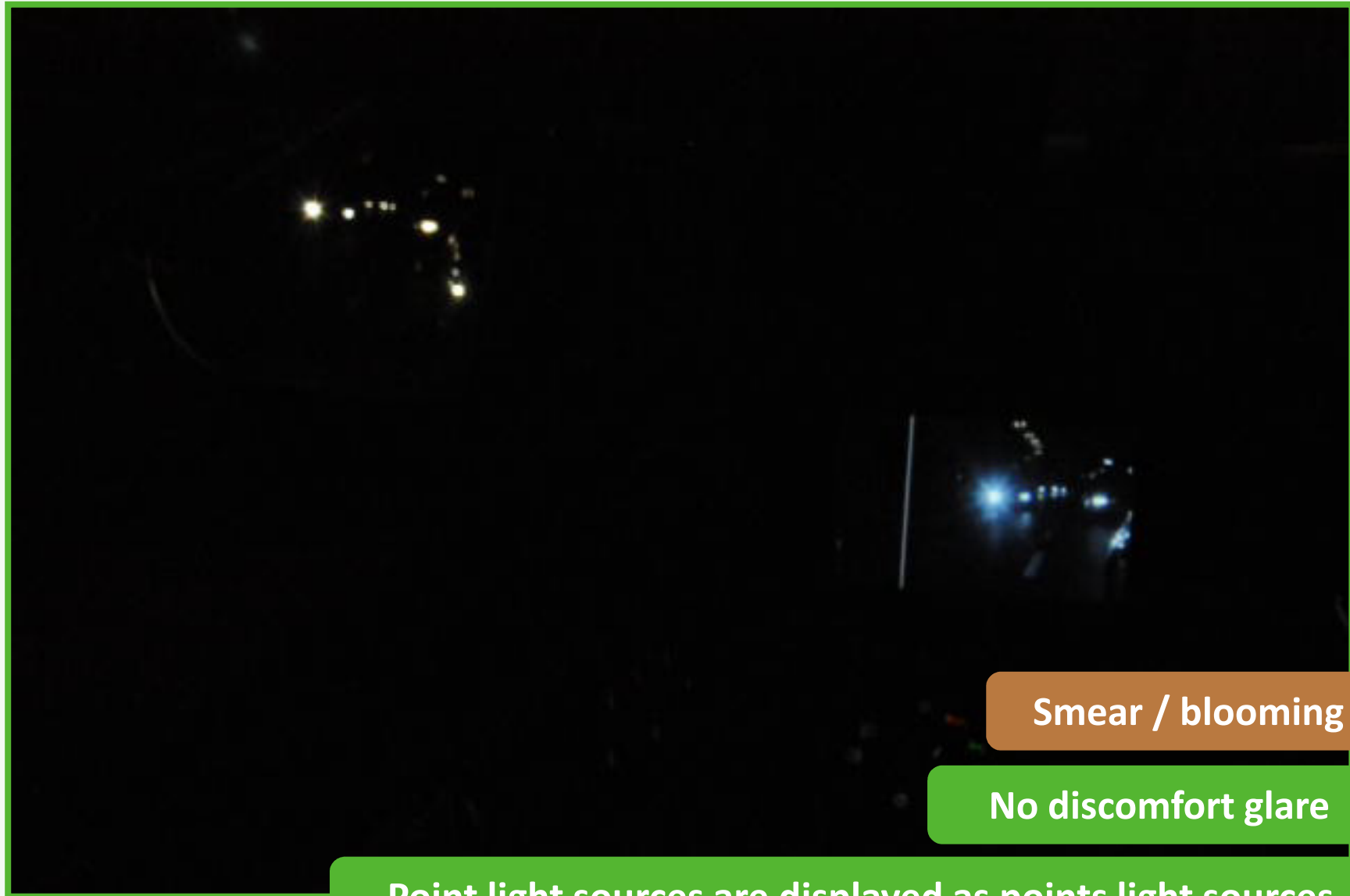




No discomfort glare







Smear / blooming

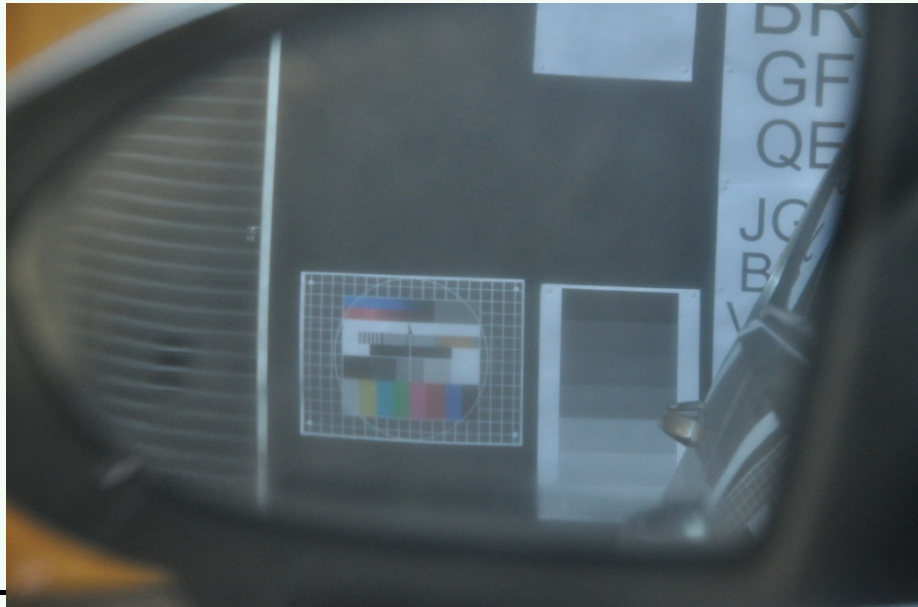
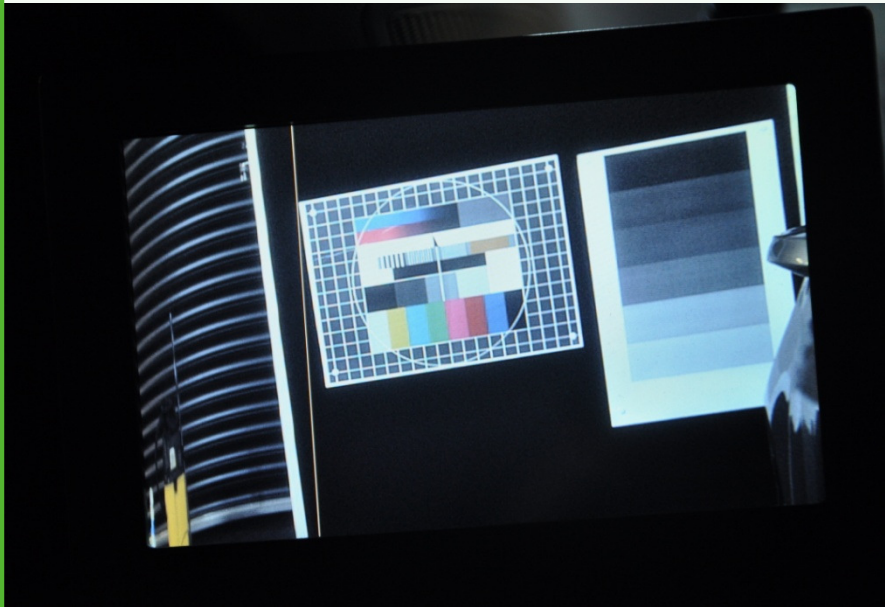
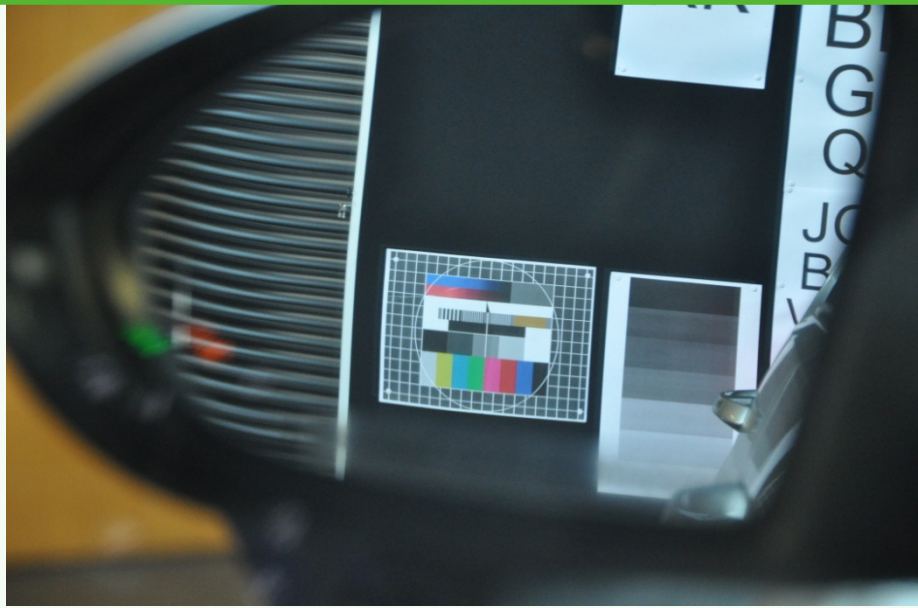
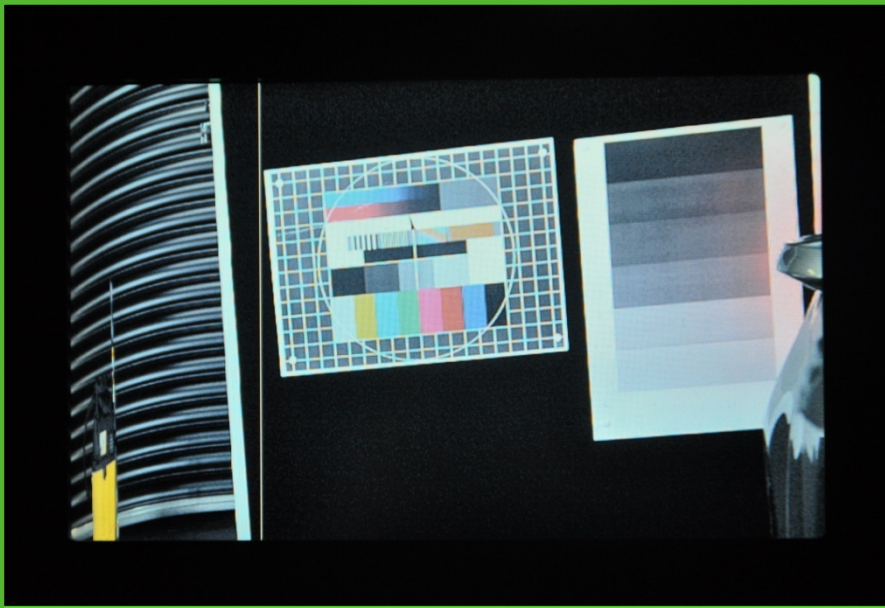
No discomfort glare

Point light sources are displayed as points light sources



Reflection of display should be reduced

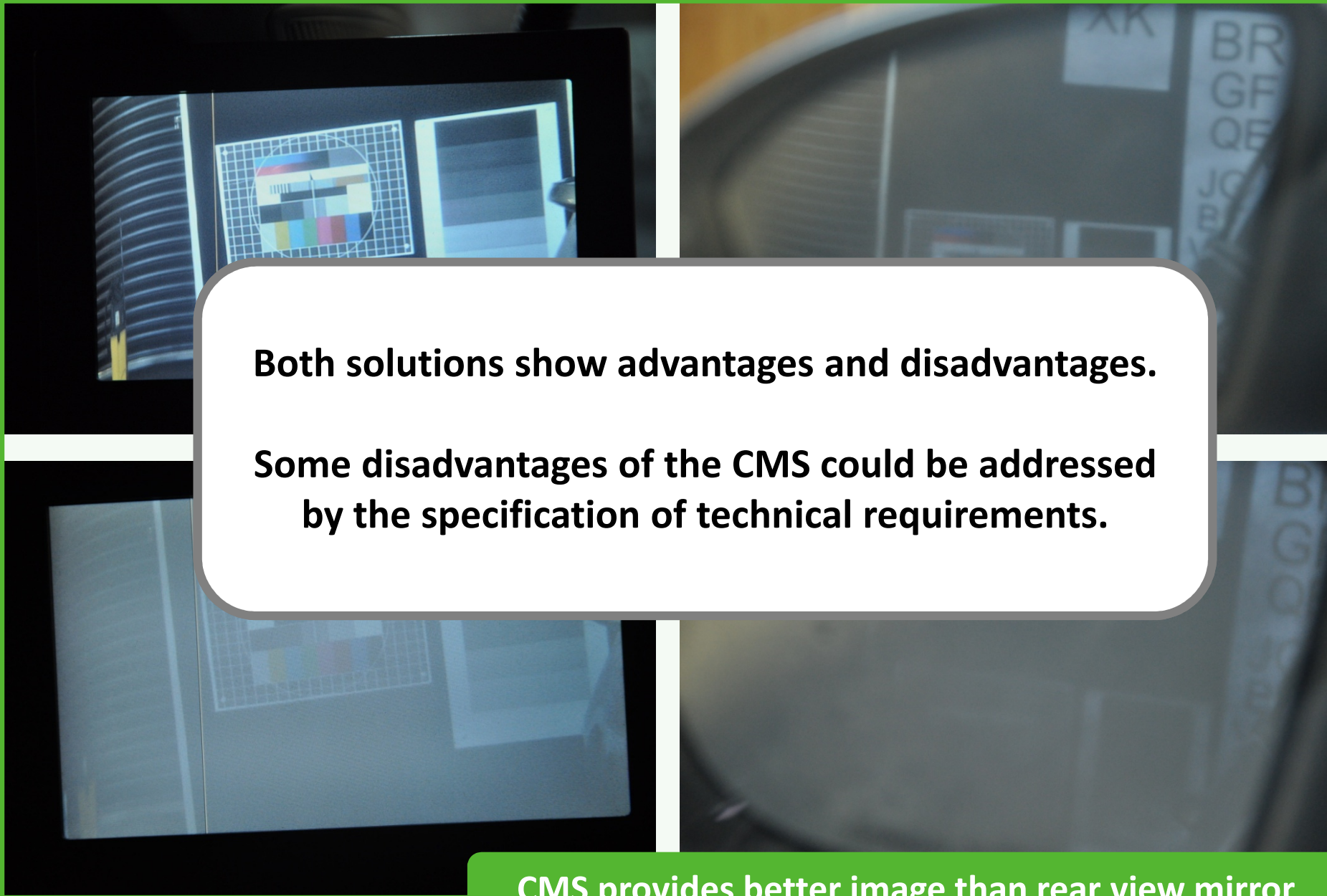
# Dirt



Folie Nr. 11

27.03.2014

Schmidt - IG CMS



**Both solutions show advantages and disadvantages.**

**Some disadvantages of the CMS could be addressed by the specification of technical requirements.**

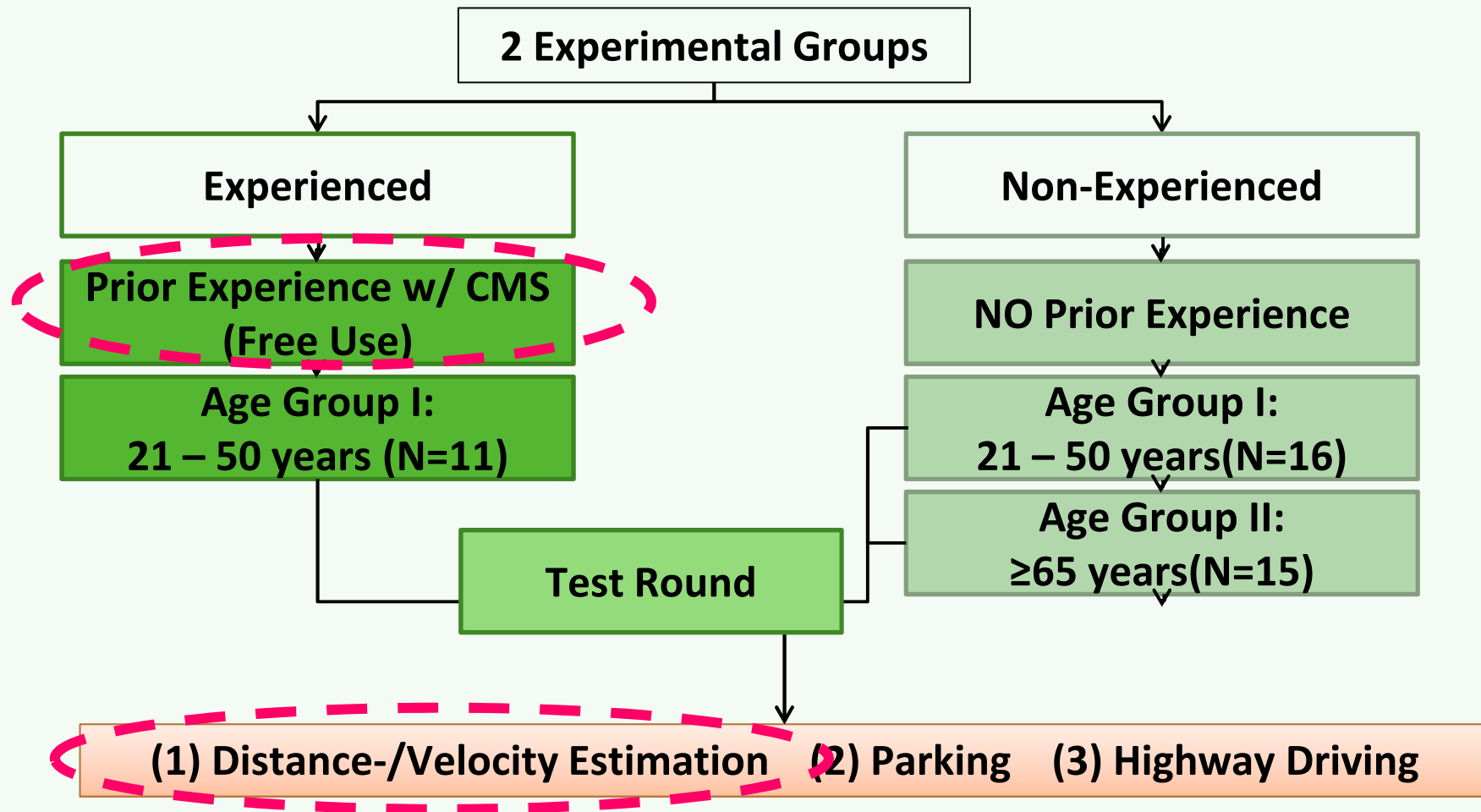
**CMS provides better image than rear view mirror**

## Aspects of Human Machine Interaction

- **Field of vision tailored to traffic situation**
- **Individualization possible**
- **Option to highlight objects or persons**
- **Reduction of discomfort glare**

## Aspects of Human Machine Interaction

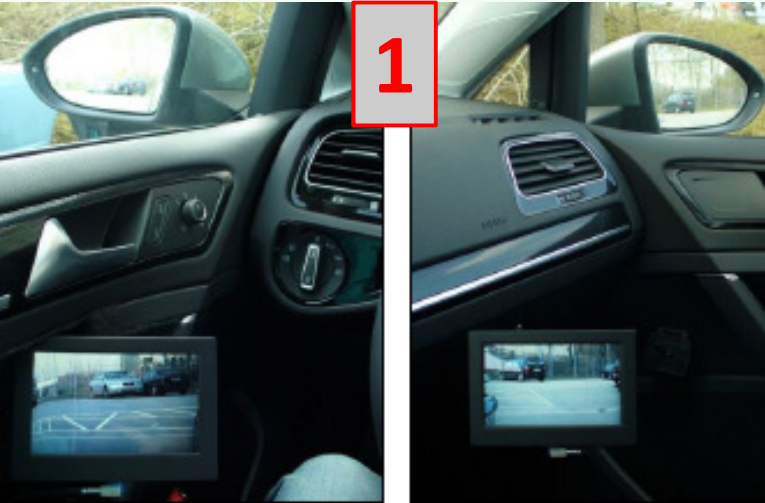
- Effect of varying display position on drivers' situation awareness (Endsley, 1995) not known:
  - Information closer to the central field of view
  - **Change of highly automated use patterns may have impact on assessment of relevant information**
- **Depth information is reduced**
- **Accommodation to closer distance necessary**
- **No possibility to adapt field of view by head movements**



*Subjective:* Acceptance; Situational Awareness; Distraction

*Objective:* Performance Measures; Gaze Behavior; Speed Behavior

# Display Positions





# Evaluation by „experts“ after free use



**0.1 FAHRTENPROTOKOLL – FREINUTZUNG**

Datum: \_\_\_\_\_ VPN Code: \_\_\_\_\_

*Lieber Nutzer,  
hier finden Sie einige Verkehrssituationen, die Sie in der freien Nutzung befahren können. Sie können diese Liste natürlich auch durch weitere Verkehrssituationen erweitern, die Sie in der Erprobung befahren haben. Gleichzeitig müssen Sie auch nicht jede der hier aufgeführten Situationen erproben. Bitte bewerten Sie nicht das Fahrzeug, sondern primär die Nutzung des Kamera – Monitor Systems in der Situation.*

Verkehrssituation	(1) Wie empfanden Sie die Nutzung des Kamera-Monitor-Systems? (2) Ist Ihnen etwas Besonderes aufgefallen? (3) Gab es einen Einfluss der Lichtverhältnisse (z.B. Tag/Nacht/Dämmerung) oder der Witterungsverhältnisse (z.B. Regen/Nebel/Sonnen)?
Aus dem Stand in den fließenden Verkehr einfädeln	
Abbiegen nach rechts	
Abbiegen nach links	
Kreisverkehr	
Tunnelfahrt	
Auffahren auf die Autobahn	
Fahren/Überholen auf der Autobahn	
Autobahnfahrt mit hoher Geschwindigkeit	

**0.1 FAHRTENPROTOKOLL – FREINUTZUNG**

Datum: \_\_\_\_\_ VPN Code: \_\_\_\_\_

Fahrstreifenwechsel	
Fahrt auf Landstraße	
Rückwärts in beleuchtete/unbeleuchtete Garage einparken	
Rückwärtsfahren	
Signallichter (z.B. Ampel, Polizei/Feuerwehr, Blinker usw.)	
Einparken (rückwärts Quer/ Längsparken)	
Motor anlassen/ abstellen	
aus dem Fahrzeug aussteigen	

Weitere


\_\_\_\_\_ gefahren Kilometer, davon \_\_\_\_ % Innerorts  
 \_\_\_\_ % Landstraße \_\_\_\_ % Autobahn auf eine Gesamtdauer von  
 \_\_\_\_\_ Stunden.

VIELEN DANK!

## Evaluation by „experts“ after free use

### Non-critical or rather unspecific statements:

- Driving on rural road
- Highway driving
- Turning
- Reversing
- Signal lights
- Start/stop of engine
- Leaving / entering vehicle
- Rain

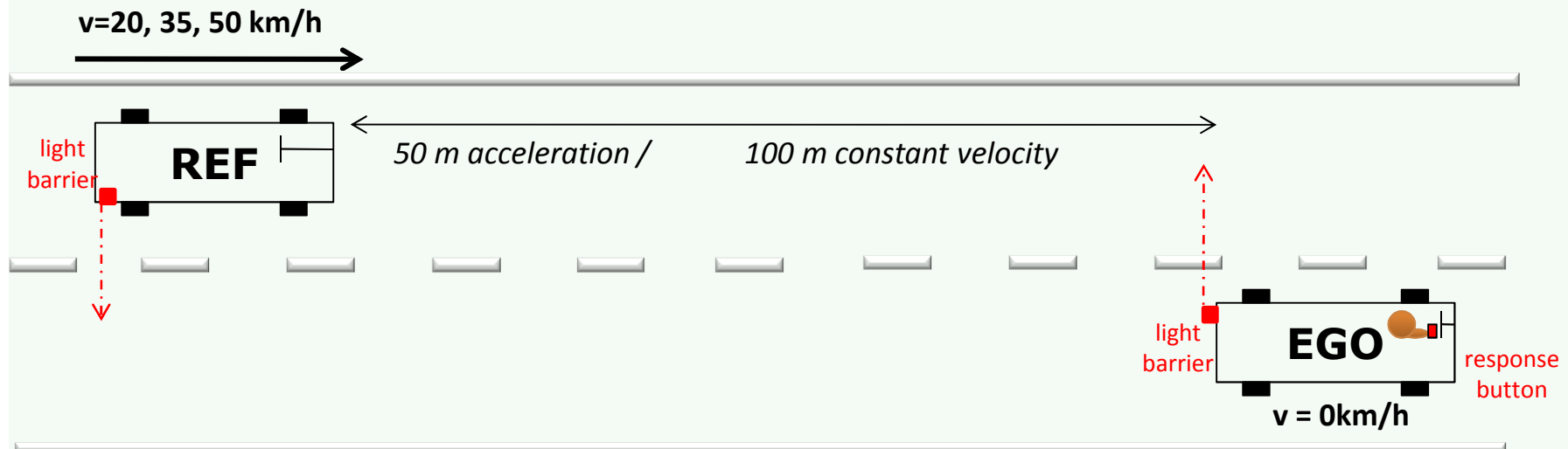
## Evaluation by „experts“ after free use

### „Rather critical“ categories:

- **P**
  - 
  - 
  - 
  -
- The „experts“ ratings generally reflect the technical properties of the system

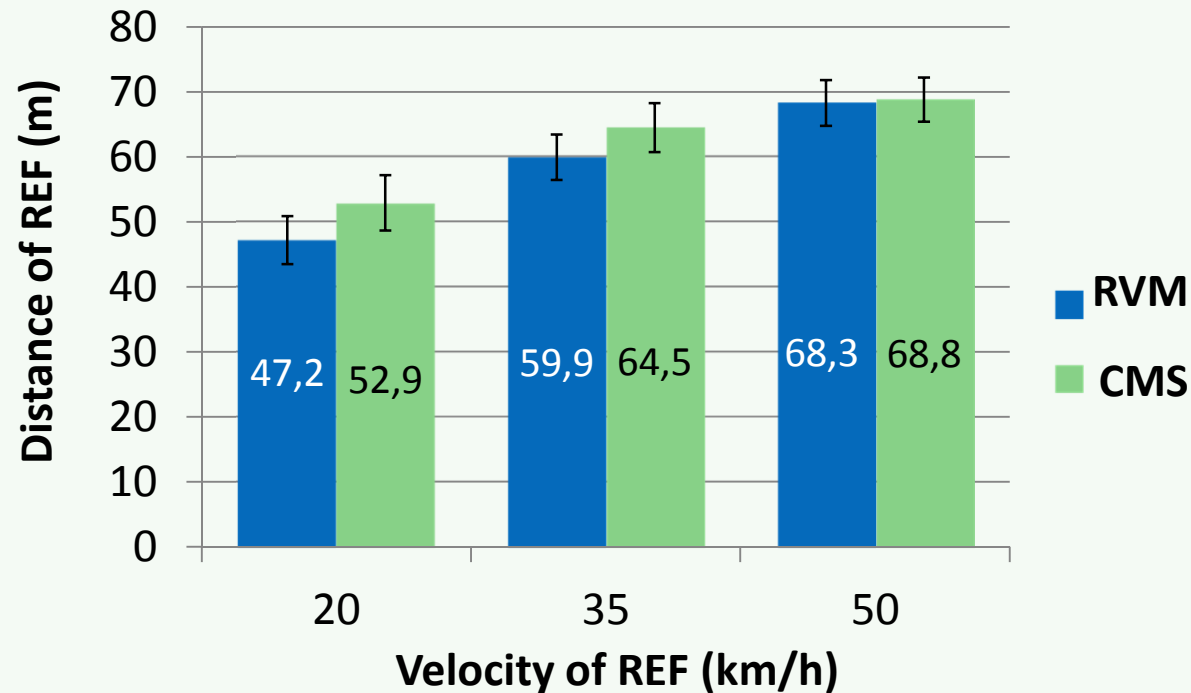
Question: Is there an objective effect on distance and velocity estimation?
- y)

## Distance- and Velocity Estimation („Last Safe Gap-Method“)



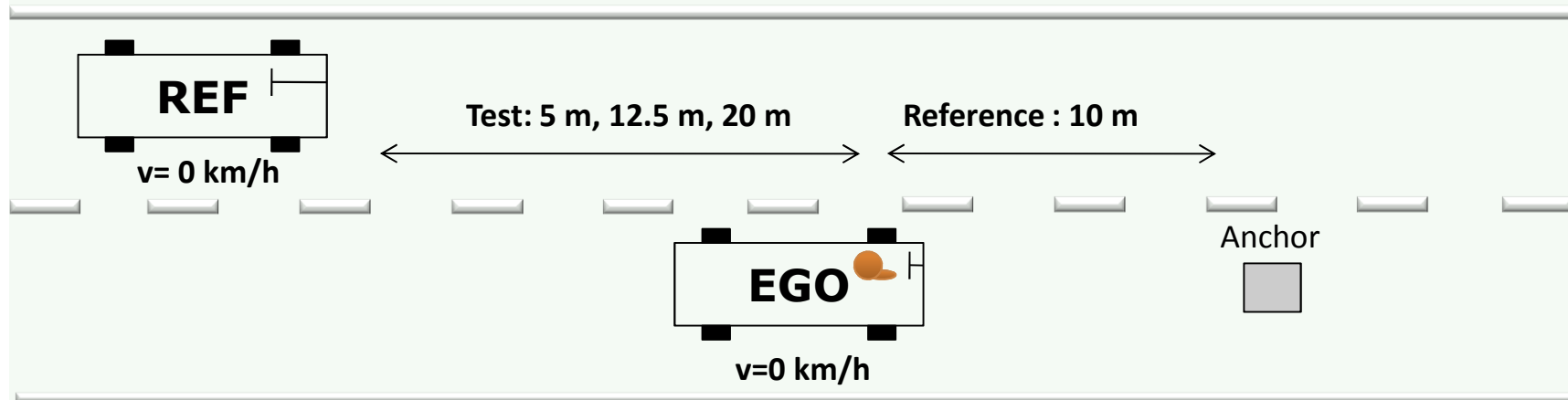
- Drivers (EGO) observe approaching vehicle (REF) through outside rearview mirror (RVM) or camera monitor system (CMS)
- Button press at the **latest moment where it is considered safe to pull out** in front of the approaching vehicle

## Results: „Last Safe Gap-Method“ (N=34, within subject)



- The faster the REF-vehicle, the larger the „last safe gap“ ( $F(2;66) = 39.752, p = .000$ )
- Tendency of larger gap using CMS ( $F(1;33) = 3.646, n.s. [p = .065]$ )
- No interaction between velocity and used device ( $F(2; 66) = 1.187, n.s. [p = .310]$ )

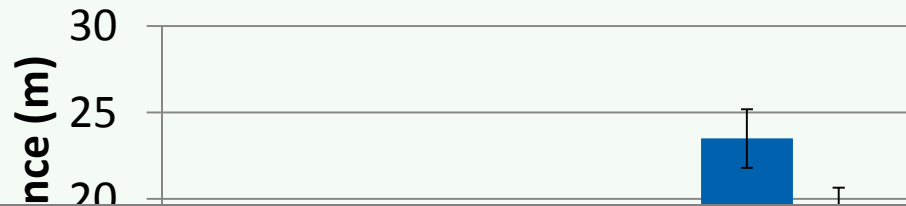
## Distance Estimation („Magnitude Estimation Method“)



- Drivers (EGO) observe vehicle positioned in the back (REF) through RVM or CMS
- Estimation of distance to relative to frontal „anchor“ distance („100“)



## Results: „Magnitude Estimation“ (N=40, between-subject)



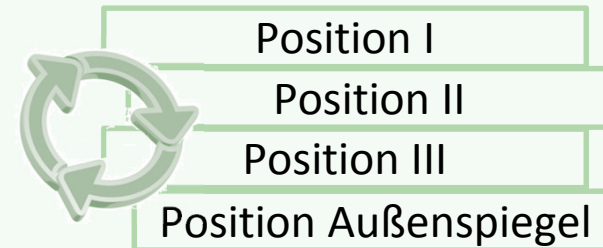
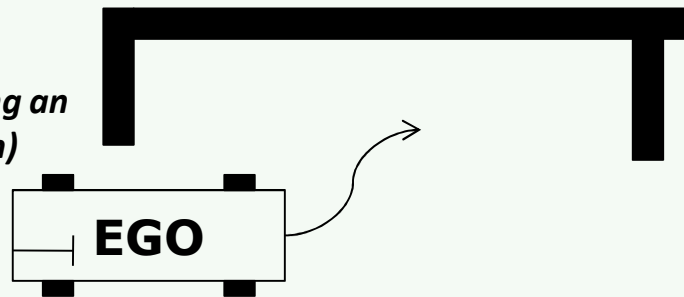
**In general distances and velocities can be estimated by using the camera monitor system**

**There is no significant difference in comparison to using an outside rearview-mirror**

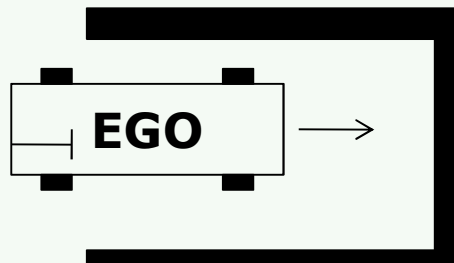
- The ... (F(1; 39) = 5.203, p = .028)
- Shorter distances are estimated using CMS (F(1; 39) = 5.203, p = .028)
- No interaction between distance and used device (F(2,78) = 1.65, n.s., p = .207)

## Reversing / Parking

*Parallelparken und  
parallele Annäherung an  
Hindernis (Randstein)*



*Querparken und  
orthogonale Annäherung  
an Hindernis*





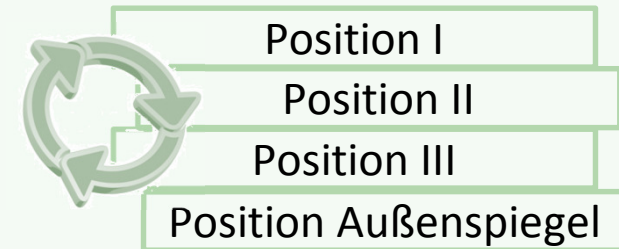
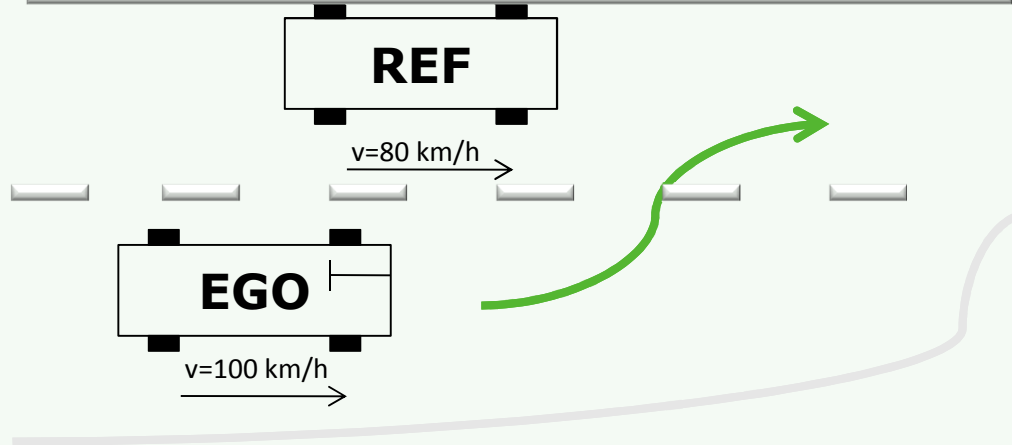
## Parking

- There was no significant influence of the used system on the number of reversals and the subjective judgement neither for parallel nor for orthogonal parking
- There is a tendency that especially elderly drivers tend to need more reversals when using display position 1 (lowest position). This is also reflected in the general judgement.



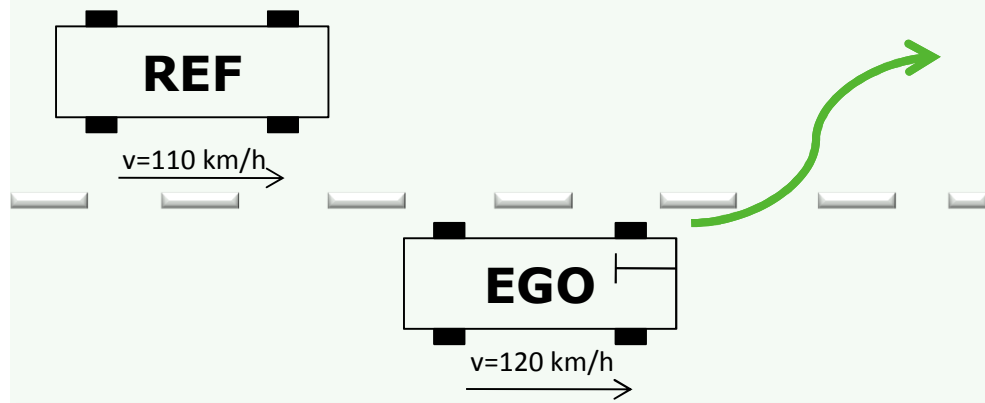
*Auffahren auf die Autobahn*

**Auswertung: -15s**



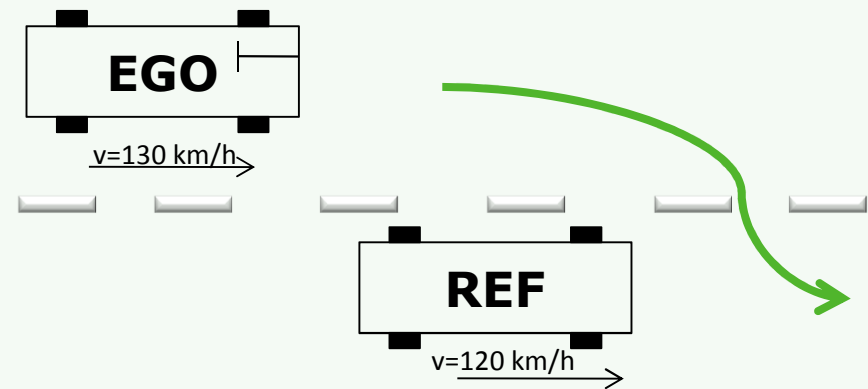
*Ausscheren zum Überholen*

**-10s**

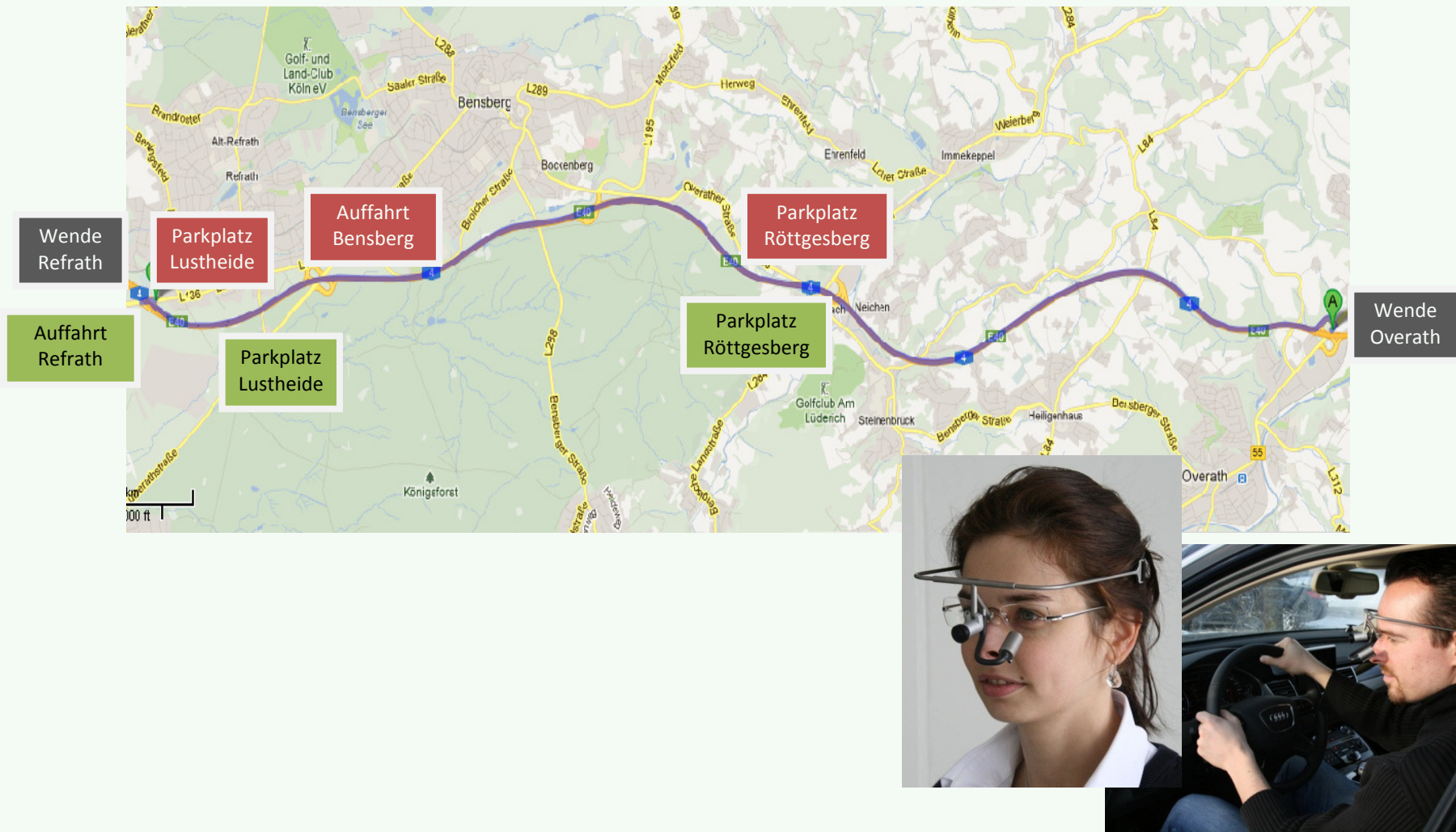


*Einscheren nach Überholvorgang*

**-10s**

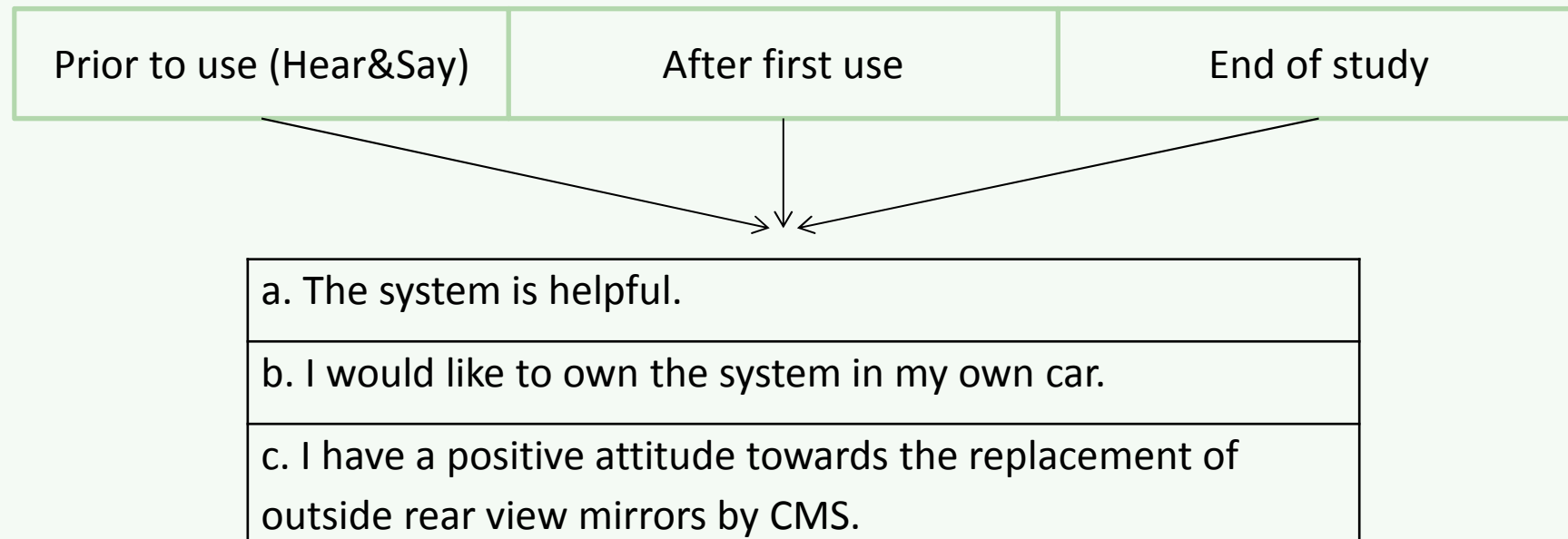


# Highway track Refrath – Overath (filtering situations)

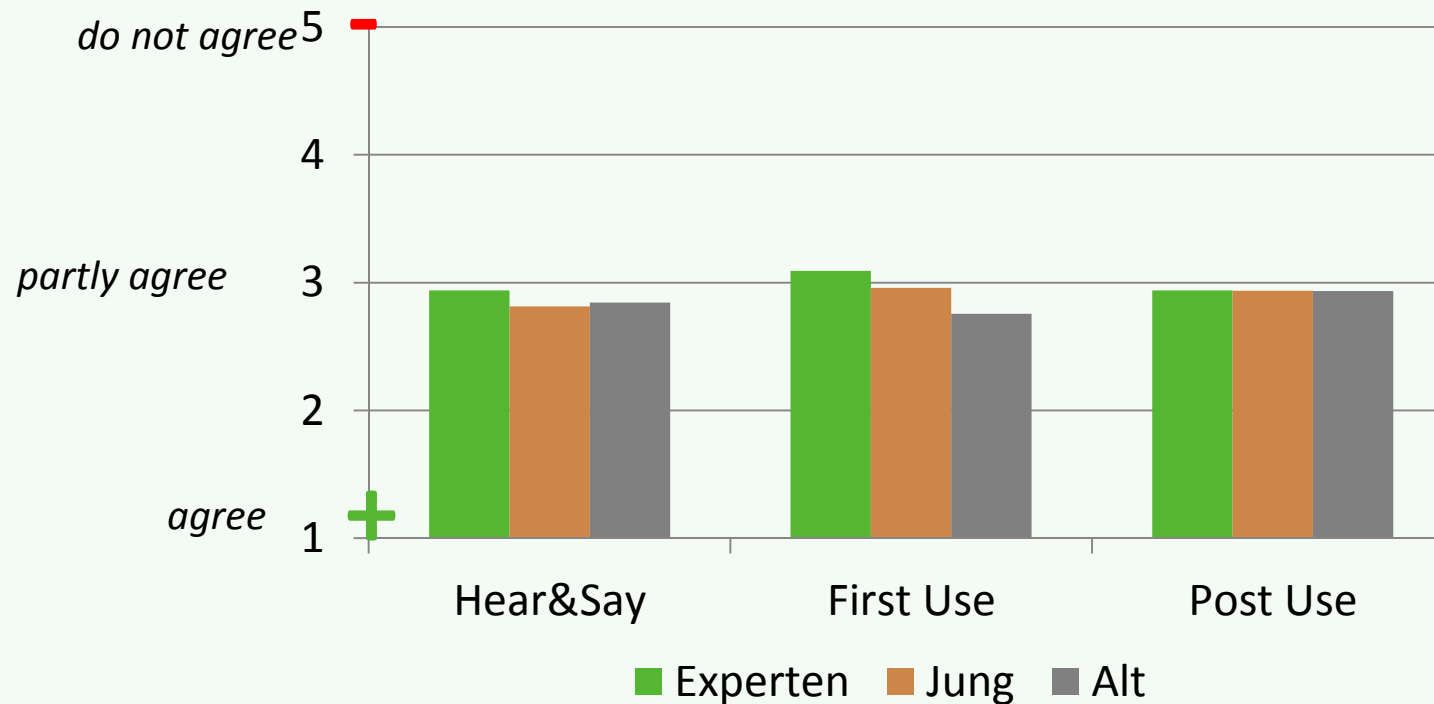


## Acceptance

*Does system acceptance change with continuous use?*



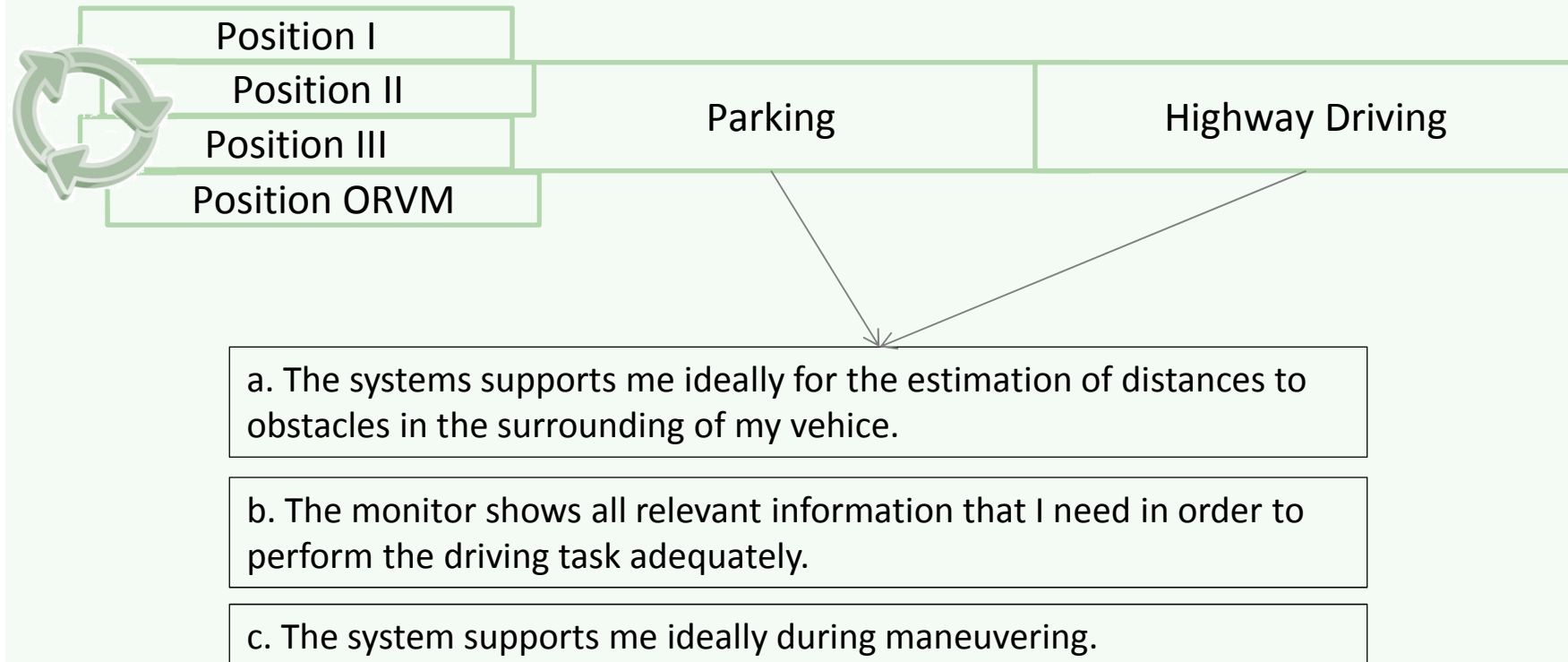
## Acceptance

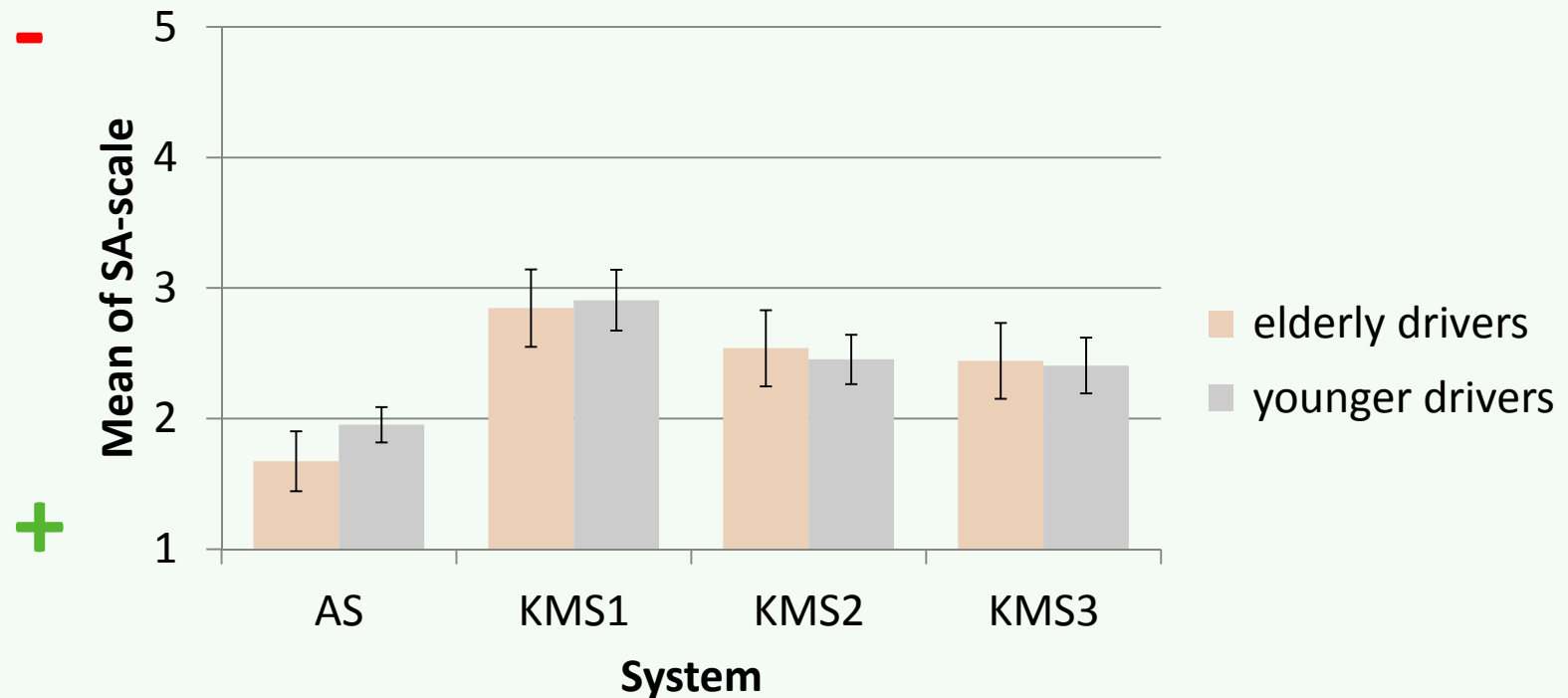


- The system shows a moderate acceptance which does not change significantly with increasing experience. (HE Erfahrung,  $F(2,38) = .330$ ,  $p = .721$ )
- No difference between the three groups („experts“, young, elderly)

## Situation awareness

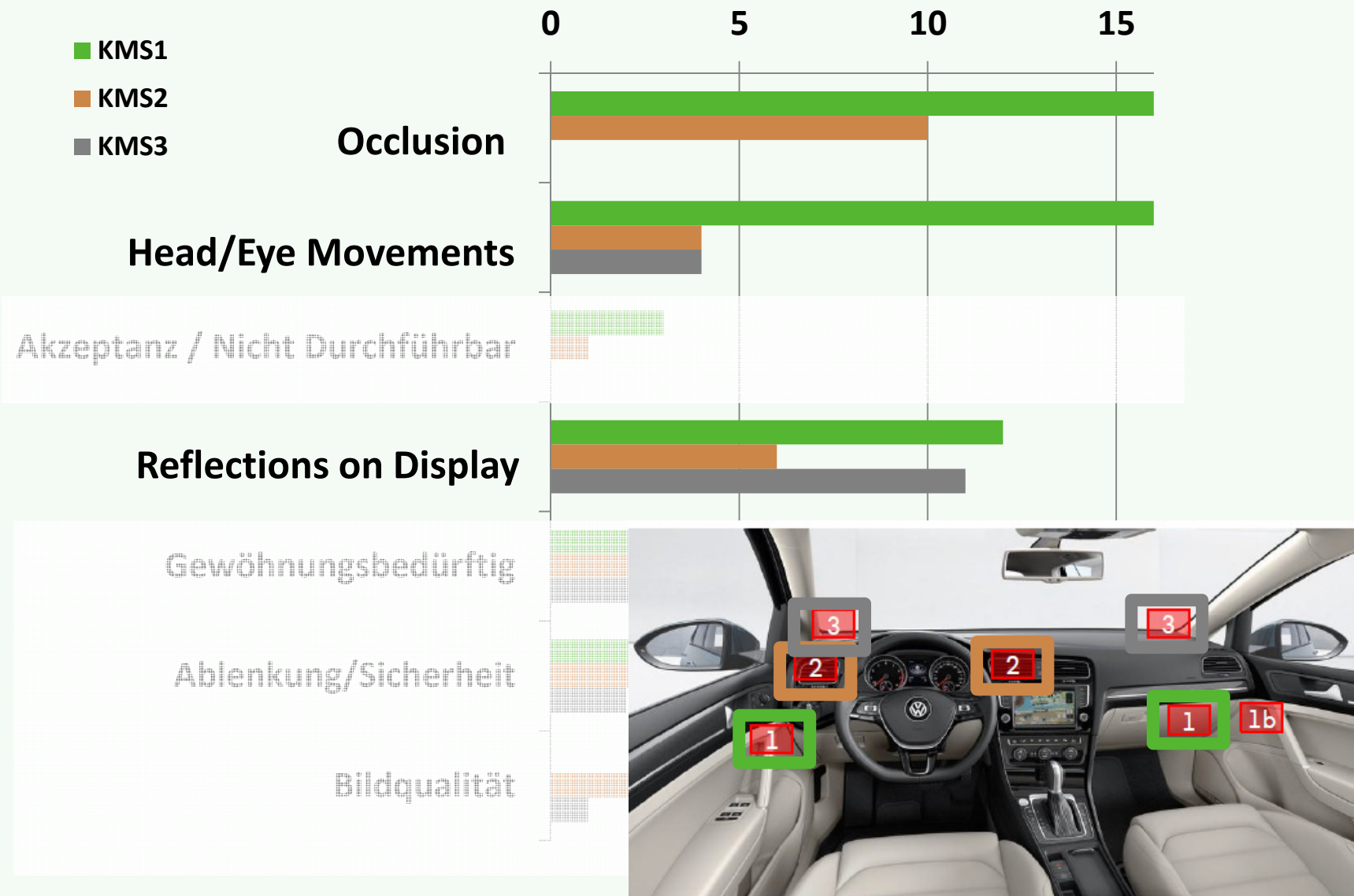
*Is it possible to form an adequate situation awareness by using the CMS?*





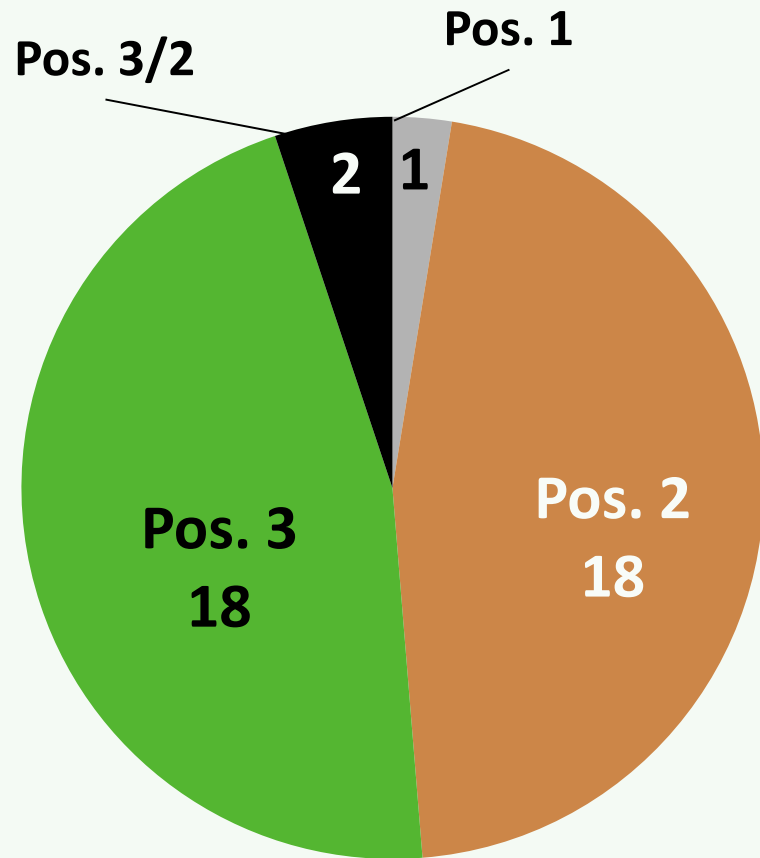
- The CMS is perceived to perform somewhat worse than the outside rearview mirror (AS) [HE System ( $F(3;81) = 12,516, p = .000$ )], especially for position 1
- No age-effect

# Comments on display position





# Preferred display position



## Next steps

- Finalisation of analysis
- Study on influence of visual abilities on use of CMS (e.g. hyperopia)
- Study on the use of CMS in heavy goods vehicles (technical and HMI)
- Support of discussion in IG CMS
- Final report expected in summer 2014 (will be translated into English language)



**Thank you for your attention!**

