Proposal to amend the draft FRAV interim submission to GRVA/WP.29

Modifications to the existing text are marked in **bold** for new or ~~strikethrough~~ for deleted characters.

3.**8**.   "Dynamic Driving Task (DDT)" means the real-time operational and tactical functions required to operate the vehicle in on-road traffic. ~~(See Section I.A. for general background and especially Section I.B., paragraphs 25-29, for application to ADS.)~~

The DDT excludes strategic functions such as trip scheduling and selection of destinations and waypoints.

The operational and tactical functions of the DDT can be logically grouped under three general categories:

> **Sensing and perception, including:**
>
> > **Monitoring the driving environment via object and event detection, recognition, and classification.**
> >
> > **Perceiving other vehicles and road users, the roadway and its fixtures, objects in the vehicle's driving environment and relevant environmental conditions.**
> >
> > **Sensing the ODD boundaries, if any, of the ADS feature.**
> >
> > **Positional awareness.**
>
> **Planning and decision, including:**
>
> > **Prediction of actions of other road users.**
> >
> > **Response preparation.**
> >
> > **Manoeuvre planning.**
>
> **Control, including:**
>
> > **Object and event response execution.**
> >
> > **Lateral vehicle motion control.**
> >
> > **Longitudinal vehicle motion control.**
> >
> > **Enhancing conspicuity via lighting and signalling.**

Justification

Reinserts full DDT text from FRAV-30-05/Rev.1 into the interim draft.