

	Stakeholder position	JNCAP	JASO
Definition	<p>(CP1:J) Acceleration control Industry: ACPE = system able to inhibit acceleration when a potential pedal error is detected (CP2: DE) System that is able to prevent collision with a wall, vehicle, vulnerable road user, in case a pedal misapplication has been detected.</p>	Acceleration control	Acceleration control
Vehicle categories	<p>(CP1:J) M1 and N1. After initial discussion M1/N1, we can discuss application and modification to other vehicle categories. Industry: M1N1 (CP2: DE) M1/N1 sufficient accidentology available. For other categories, accident data as motivation needs to be provided to further define DE position.</p>	Pass car $\leq 9P$ Track $\leq 2.8t$	M1 and N1
Collision obstacle (Working direction)	<p>(CP1:J) Wall, vehicle and pedestrian, but no obstacles operation[※] can be accepted as alternative Industry: <ul style="list-style-type: none"> Clarify “no obstacles operation[※] can be accepted as alternative” → systems only reacting on actuation speed of the accelerator pedal would still be accepted, right? See next slide (CP2:DE): Wall, vehicle and VRU. Collisions should be prevented for initial distances above [1.5m] and initial speeds below [10 km/h]. <i>Technology neutrality: if detection using actuation speed fulfils the requirements, this should be allowed.</i></p>	Vehicle(2018~) Pedestrian(2023~) (front and rear)	vehicles or walls (front and rear)