Initiatives relating to ITS by Road Bureau, MLIT of Japan

ITS Promotion Office

Road Bureau

Ministry of Land, Infrastructure, Transport and Tourism (MLIT)





- 1. Previous ITS Initiatives
- 2. Next-generation ITS
- 3. Initiatives for automated driving

Previous efforts by MLIT



1990' Car Navigation system

Cumulative Shipments
Approx. 105.31 million (2022.3)

1996 VICS (Vehicle Information Communication System)

Providing traffic congestion and regulatory information to car navigation systems to support safe and smooth traffic

Cumulative Shipments Approx. 75.03 million (2022.3)



2001

ETC(Electronic Toll Collection System)

Nonstop automatic toll collection eliminates congestion at tollbooths

Cumulative new setups
Approx. 78.33 million (2022.3)





2011

ITS Spot

Dynamic route guidance/safe driving support/ETC, etc.



Evolution

2015



- Smart investments based on big data
- Safety Measures Using Big Data
- · A smart toll booth where ETC is basic and stress-free
- Smart logistics management with high productivity

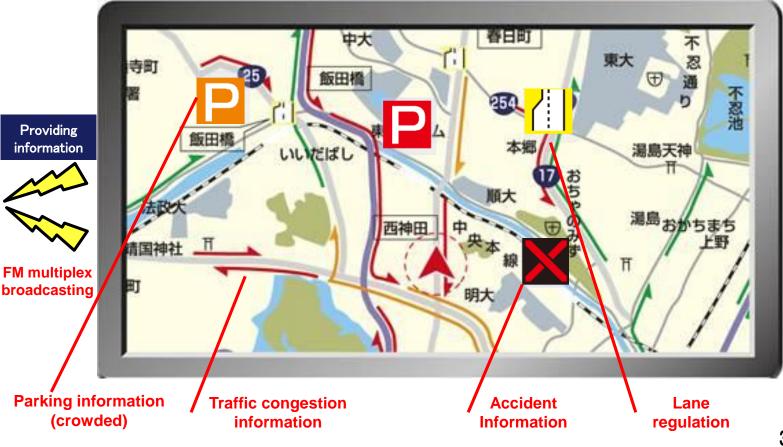
Cumulative new setups Approx. 8 million (2022.3)

VICS(Vehicle Information and Communication System) TILIT

- O The VICS service started in April 1996.
- O Provide real-time information on traffic jams and traffic accidents through car navigation systems.
- O Cumulative VICS shipments exceed 75.03 million units (March 2022)

Car navigation system allows route selection based on traffic conditions



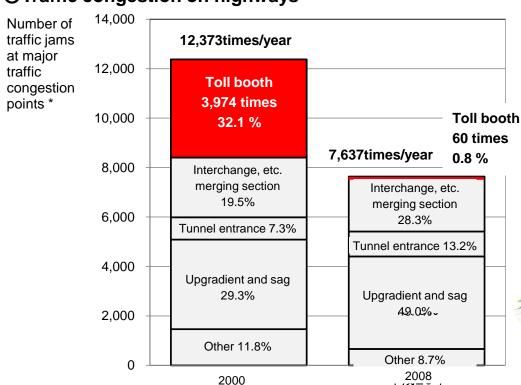


Effect of introduction of Electronic Toll Collection System (ETC)



- O ETC service started in 2001 and gradually expanded, with about 95% usage on highways (April 2023)
- O Tollgate congestion, which used to be the biggest cause of congestion on highways, has been almost eliminated by the spread of ETC.
- O Promoting the development of smart interchanges dedicated to ETC, which can be developed at a lower cost than conventional interchanges, in order to promote the effective use of highways and the revitalization of local communities

OTraffic congestion on highways



(Before ETC)

normal interchange

- A lot of labor needed for toll collection
- Large construction costs (facilities need to be consolidated to control fee collection expenses)

smart interchange

[Direct connection type to main line] [SA/PA type]

- Dedicated to ETC, allows for compact design
- Labor costs associated with fee collection can also be saved
- *In service: 204 (As of 2022, including construction sites)

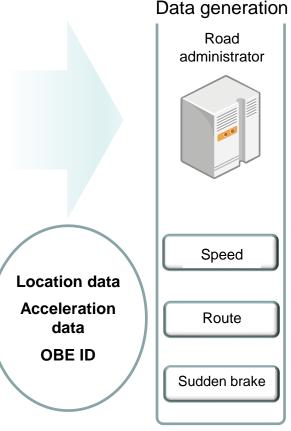
Using big data from ETC 2.0:

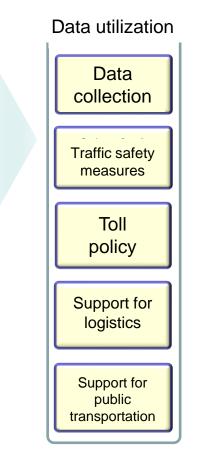
Pinpoint traffic congestion control on highways



- O Started operation of ETC 2.0 in 2015
- O Through two-way communication between vehicles and the road,
 - ✓ Providing information on dangerous situations such as widespread traffic congestion and invisible traffic at the points where accidents frequently occur.
 - ✓ Collect big data on vehicles (Position data, acceleration data, etc.) and use it for road measures such as traffic congestion control and traffic safety







ETC 2.0 Information Service

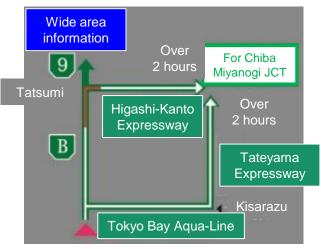


Providing Wide Area Information and Images on Routes



Warnings for dangerous situations such as traffic jams where you can't see the curve ahead in areas where accidents frequently occur

Providing congestion information in a wide area









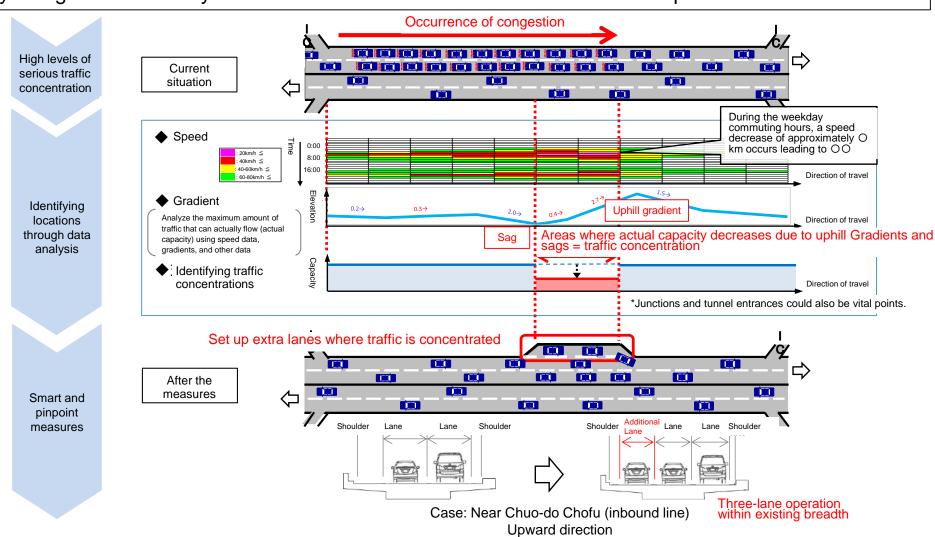
This is the current road surface condition, Okm away.
Please drive carefully because of the snow.

Using big data from ETC 2.0:

Pinpoint traffic congestion control on highways



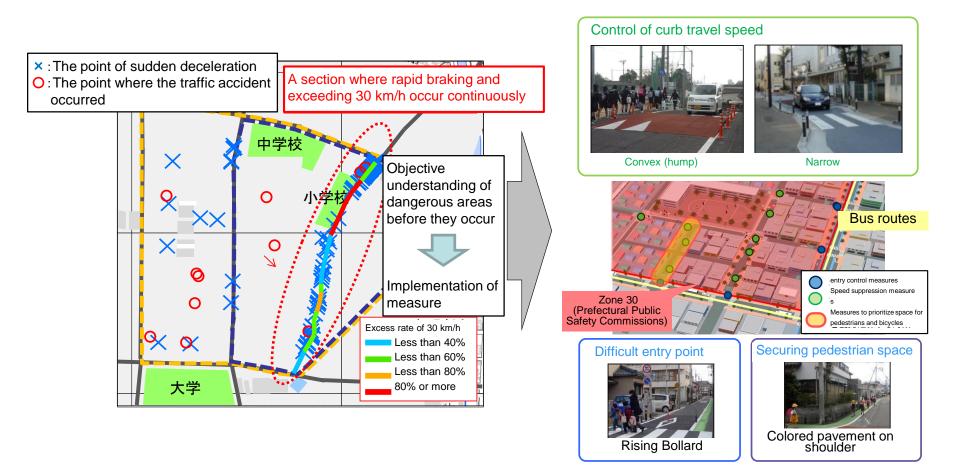
O In an effort to maximize the effectiveness of the existing network at the lowest possible cost, we have implemented measures to effectively address structural factors such as uphills and tunnels by using data to identify areas where traffic is concentrated due to slow speeds.



Using big data from ETC 2.0: Using big data to improve road safety ITTLIT

- O Use of big data to identify potential dangerous areas and implement measures to control speed and approach through traffic
 - ■Using big data from ETC 2.0

 to identify potential hazards
 such as excessive speed, sudden braking, and loopholes
 - Planning and implementation of effective and efficient measures
 [Examples of countermeasure menus]





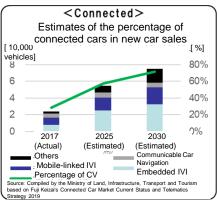
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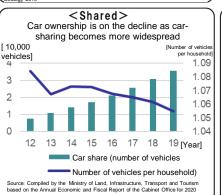
Changing circumstances surrounding road traffic



- O In the future, the advancement of on-board sensors and communication and analysis technologies in response to the progress of CASE is expected to diversify the information that vehicles can collect and to further improve the accuracy, freshness and reliability of the data obtained.
- O In view of the realization of diverse services, it is necessary to work on creating an implementation environment that enables in-vehicle linkage and utilization of data acquired on the vehicle side, and reviewing the communication methods and functions of the roadside system (such as linking with sensors and adding immediate processing functions).

■ Progress of CASE







World's first type designation for automated-driving vehicle (Level 3) Company Goal Electric vehicle TOYOTA 2030 sales: 8 million Electric vehicle **NISSAN** By 2030 sales: 1 million Electric vehicle sales ratio **HONDA** 2030 (in developed countries): 40% 100% of electric VOLVO By 2030 vehicle sold

<Electric>

■ Data diversification

Estimating the vehicle's location and recognizing the surrounding environment

(LiDAR/millimeter-wave radar/camera/gyro/ultrasonic sensor)

Real-time processing
High-speed, high-capacity communications, etc.,
that communicate data to servers in seconds
(Position/Speed/Image/Failure/Abnormal/Acceleration/Deceleration)

Collaboration and distribution of collected data using APIs, etc.

(Parking lot full capacity information/Public transportation service information/Event information)

Mutual complement of acquired data to improve reliability



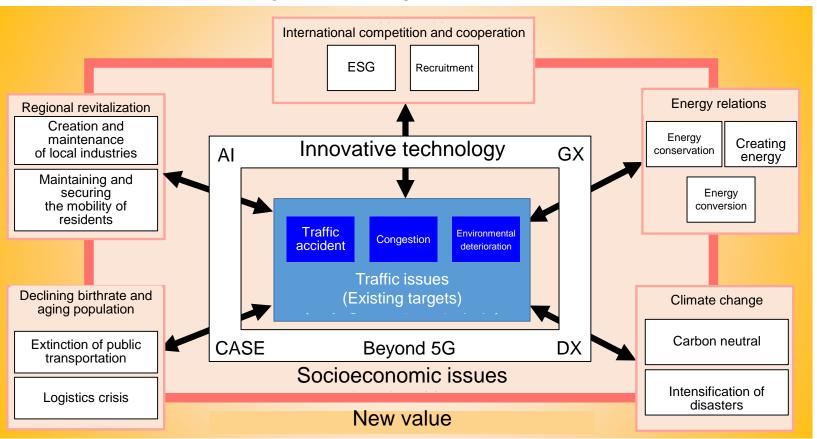
Source: Cabinet Office "SIP Automated Driving Research and Development Plan"

Targeting next-generation ITS



O With the development and spread of innovative technologies and the maturation and complexity of socioeconomic activities, next-generation ITS will not only solve existing traffic issues (congestion, accidents, and the environment) but also contribute to solving socioeconomic issues.

Targets of next-generation ITS

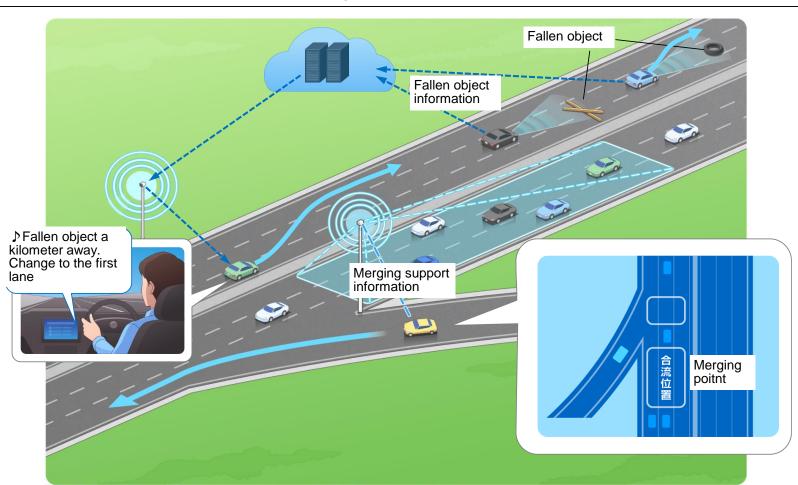


Example 1 of efforts to solve issues:

Support for autonomous driving



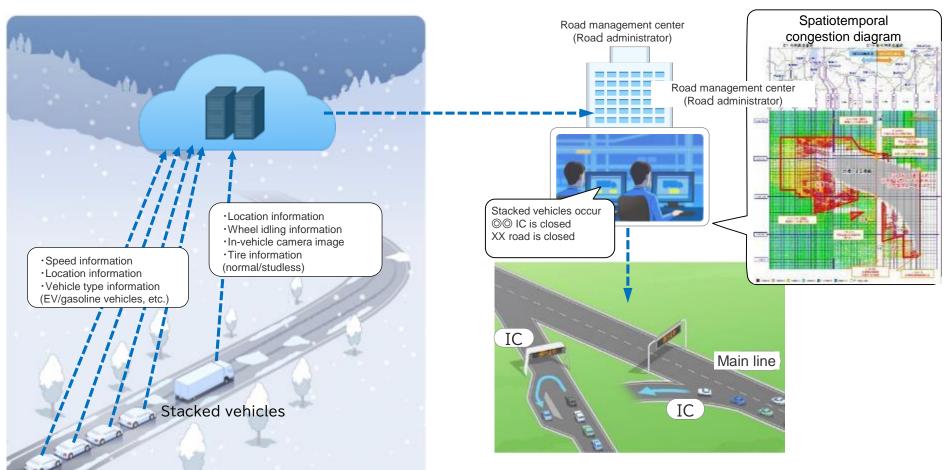
- O By using roadside and vehicle sensors to detect and provide information on road traffic conditions and fallen objects, it will contribute to the realization of autonomous driving by supporting smooth merging and safe driving.
- O This will contribute to solving social issues of logistics and securing passenger transportation that are difficult to maintain due to labor shortages.



Example 2 of efforts to solve issues:

Accurate, prompt grasp and measure to heavy snow

- O When vehicles get stranded during heavy snow, the congestion of vehicles increases, and the longer the measure is delayed, the longer the situation becomes and the more serious it becomes.
- O Prevent the spread of damage by combining information on vehicle location and wheel idling to detect signs of stranded vehicles in snow and to detect and respond quickly to their occurrence.

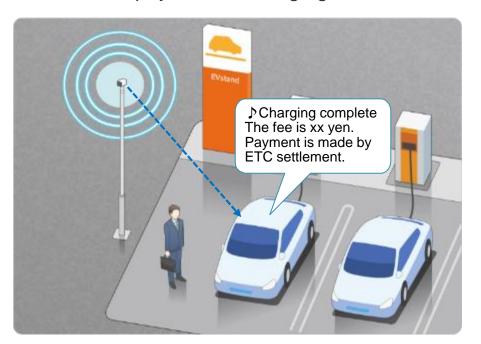


Example 3 of efforts to solve issues:

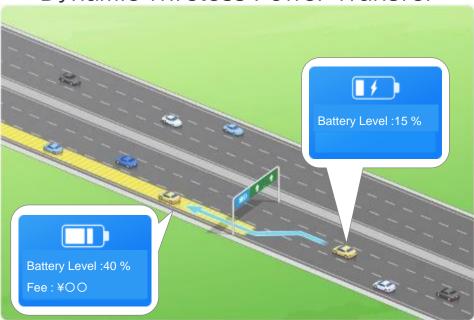
Contributing to GX (Green Transformation) through the spread of EV vehicles

O Increased convenience through the realization of ETC settlement of EV charging fees and charging fees with contactless power supply while driving in the future, thereby supporting the spread of EV vehicles and contributing to carbon neutrality.

ETC payment of charging fees



Support for Dynamic Wireless Power Transfer





Support for merging with expressway interchanges

Information on approach speed and location is provided to enable safe merging by collecting traffic information from roadside vehicles and providing it to merging vehicles at merging sections such as highway interchanges.



Application infrastructure

Data

infrastructure

infrastructure

Roadside unit

0

Narrowband

communication

Next-generation ITS

Implementing a Digital Infrastructure(Image)

(Self-driving truck operation management through public-private data collaboration

(Wide area communications/Wired Lines)

Arguing points of **Next-generation ITS**

- ① Diverse OBE to meet a wide range of vehicles and needs
- Software integration/integration with vehicles
- Ability to expand and update functions
- Diversification of ETC settlement instruments
- ② Easy-to-use data infrastructure for all parties
- Collection of probe data according to purpose
- Build an environment for data linkage and utilization inside and outside vehicles
- 3 RSU compatible with new communication system
- Communication method according to purpose
- Adding sensors and processing functions

Common platform (on board) Installing applications Chipping instead

Application infrastructure

Data infrastructure

Communication

Common

platform

License

Government

Data

of OBE

Private sector

Data

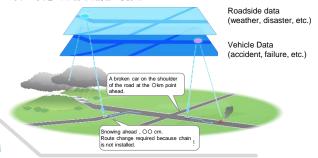


Government

Data

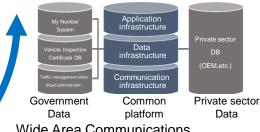


Provision of look-ahead information using road management sensors Integrated use of real-time data from vehicles and roadside systems provides safe and comfortable road traffic information.



Common platform (exterior)





Wide Area Communications

Safe and reliable operation management is achieved by immediately transmitting

information about vehicle malfunctions of self-driving trucks to the operation monitoring room and instructing the operator to inspect the vehicles at the nearest





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Steps to support the spread and expansion of automated driving mobility services (draft)



OTo accelerate automated driving mobility services on ordinary roads,

[Step 0] Support for locating your vehicle on a specific route in a limited traffic environment

X1 : Mobility services based at roadside stations "Michi-no-Eki" in rural areas

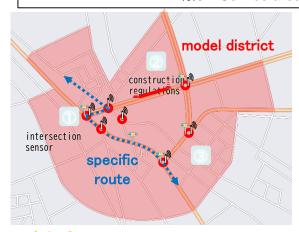
[Step 1] Risk Avoidance Support for Specific Routes in Diverse Traffic Environments

※2 : *Bus routes and others in "Machinaka" including ※1

① Assistance in collecting information at intersections ② assistance in developing and updating map information ③ risk reduction through road maintenance and monitoring

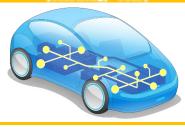
[Step 2] Risk Avoidance Assistance in Model Districts of a Certain Size

※3 : Service areas for demand buses and taxis etc.

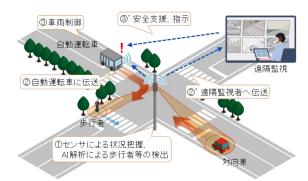




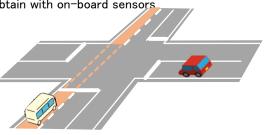
Supporting AI development (learning, etc.)





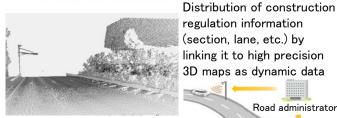


Providing intersection information that is difficult to obtain with on-board sensors



Support automated driving with on-board sensors, such as clear driving locations in intersections

2Maintenance and updating



Create and update high precision 3D maps from point cloud data such as MMS and construction surveys

regulation information (section, lane, etc.) by linking it to high precision 3D maps as dynamic data Road administrators

③Risk reduction through road maintenance and monitoring

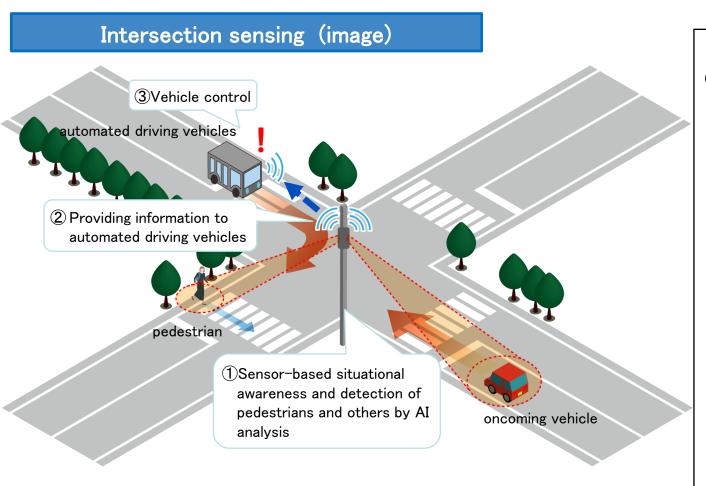
Provide sidewalks and bicycle paths in areas with a high risk of accidents. In addition, exclusive roads for automated driving suitable for vehicles and local conditions will be considered.



Future Initiatives(Support on ordinary roads)



O Verification of a V2I cooperative system that uses roadside sensors to detect and provide information such as the position and speed of oncoming vehicles, pedestrians, and bicycles, in order to improve the smoothness and safety of road traffic at intersections and other locations on ordinary roads



a point of view for consideration

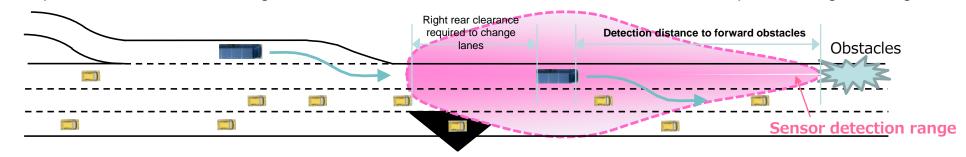
- OBuilding a highly versatile system that can respond flexibly to the development and spread of automated driving vehicles
 - Verification of the possibility of generating necessary information through AI analysis, etc., utilizing existing facilities (such as road management cameras)
 - Verification of the possibility of providing real-time information through V2I communication and stable detection that is not affected by the surrounding environment such as time and weather due to the advancement of sensors

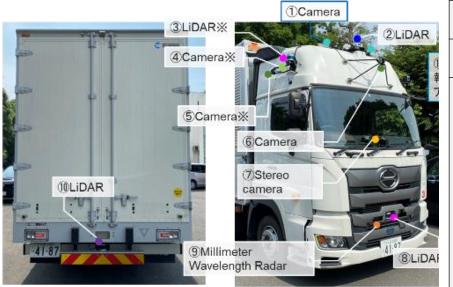
Risks that automated driving trucks find difficult to manage TILLIT on their own



Collaborate with vehicle development to make automated driving trucks a reality and Consider collaborative road vehicle solutions to risks that are difficult to manage alone.

RoAD to the L4 Initiatives Developed a vehicle for evaluating Level 4 automated-driving trucks and identified risks that pose driving challenges





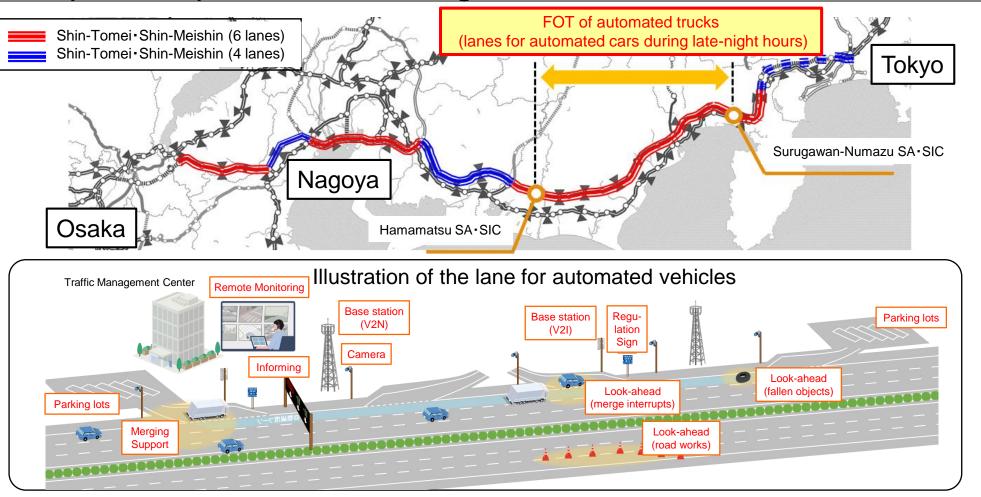
| | Risks that are difficult to deal with by vehicles alone | Support menu with infrastructure (example) |
|-----------|---|---|
| Merging | a confluence of automated-driving vehicles | Providing Main Line Traffic Information |
| Main line | Confluence of general vehicles (interruption) | Notification of approaching automated-driving vehicles by information board |
| | Lane restrictions (construction, etc.) | Providing Regulatory Information (details) |
| | Malfunction cars, fallen objects and accidents | Detecting and providing malfunctioning vehicle information |
| | exit congestion | Generation and provision of congestion information |
| | Weather (bad weather) | Providing road weather information |
| | Vehicle malfunctions (stops, accidents, etc.) | On-site processing (applying accident response) |

Self driving trucks FOT using automated driving vehicle lane TILIT



On the Council for the Realization of the Vision for a Digital Garden City Nation (March 31, 2023), it was shown that a lane will be set up for automated vehicles on the New Tomei Expressway (between Surugawan-Numazu SA and Hamamatsu SA) during the late night hours in fiscal 2024.

The function of the lane for automated vehicles should be considered based on the situation of development and spread of automated driving vehicles.



Desired functions for automated vehicle lane (draft)



[Merging Support]

Support the merging of automated driving cars onto the main line



[Collecting and Providing look-ahead information] Collecting and providing information to support the smooth running of automated-driving vehicles (e.g., prior lane changes)





Road works

Fallen Objects

[Notification]

Notification for road users by road information board, signboard, etc.



[Automated-driving trucks parking lots]

Parking lot for arrival and departure of automated vehicles on SA/PA



Overview of the V2I cooperative system



O V2I cooperative system will provide Level 4 automated trucks with look-ahead information such as merging support information, fallen objects information and road works information on the FOT.

