

Heavy-duty industry adaptation of gtr22 on invehicle battery durability: key issues

EVE IWG - Session 69 -Seoul-April 16th&17th, 2024

A monitoring phase is needed verifying MPRs

Global HDV Electrification

The HD BEV is under development. Currently, sales of HD BEVs worldwide are still extremely low (13k units: 2,7% of market share (EU 2022: 1.5% for trucks > 3.5 ton, and 0,9% for trucks > 16 ton), with very narrow applications, with dedicated customers (mostly with closed working place and customer owned charging infrastructure) for trying out the technology

Challenges with Transformation of HDV sector

- It is worth to point out that the battery capacity/range of HD vehicle is always the customer's choice in firsthand (a comprise of total costs of ownership, application use case and electric range)
- The business mode of BEVs is under development, OEMs need to develop a complete business solution (both technical and financial) for our customers to have a beneficial TCO
- Without knowing the future battery technologies, without a wide scale application of BEVs in HDV sector, without knowing the infrastructure development, we need to keep all doors open for future expansion of HD BEV

Conclusion

A monitoring phase is needed in order to be able to regulate battery durability for HDV, setting correct(ed) MPRs, due to different decarbonization roadmaps and technical solutions in different regions.

A monitoring phase is needed for the following decisions

- Usable battery capacity vs Usable battery energy
- Measurements from charging and discharging
- Statistical pass/fail criteria
- Energy throughput
- > MPR

Proposals

- During the monitoring phase, all the key points above will be measured/monitored. OEMs will provide more data than
 required by the draft to help making the final decision.
- A monitoring phase of minimum 5 years is needed to collect enough customer data from the field.

A monitoring phase is needed verifying MPRs

MPR for GTR22b

If CP wants to introduce the MPR (regulatory value) within the HDV GTR22b, OICA proposes that it should be used as a provisional value until the monitoring is completed and that there will be an opportunity to reconsider grouping (based on HDV types and use-cases) after the monitoring is completed.

Table 1 Battery Energy based (SOCE) MPR for N2, N		Table 3 Battery Energy based (SOCE) MPR for M2						
Vehicle age/km/ <u>MWh_for</u> N2,N3<16t	HD-OVC-HEV	HD-PEV	Vehicle age/km/MWh for M2	HD-	OVC-HEV HD-PEV			
From start of life to [x] years or [xxx]km or [xxx]kWh, whichever comes first	[xx] per cent	[xx] per cent	From start of life to [x] years or [xxx]km or [xxx]kWh, whichever comes first	[xx] pe	er cent [xx] per cent Table 5 Battery Energy based (SOCE) M	PR for M3>	7.5t	
Table 2 Battery Energy based (SOCE) MPR for N3> <u>1</u>		Table 4 Battery Energy based (SOCE) MPR for M3<7.5	Vehicle age/km/MWh for M3>7.5t HD-OVC-HEV HD-PE					
Vehicle age/km/MWh for N3>16t_Grp 3	HD-OVC-HEV	HD-PEV	Vehicle age/km/MWh for M3<7.5t	HD-	From start of life to [x] years or [xz [xxx]kWh, whichever comes first	xx]km or	[xx] per cent	[xx] per cent
From start of life to [x] years or [xxx]km or [xxx] MWh, whichever comes first	[xx] per cent	[xx] per cent	From start of life to [x] years or [xxx]km or [xxx]kWh, whichever comes first	[xx] pe	er cent [xx] per cent			
						·		

Conclusion

For HDV industry, use-case and vehicle type dependent MPR are key for fair treatment and to meet feasible customer needs. Oversized MPRs may lead to oversized batteries just to fulfill the law, to the drawback of customers due to increased vehicle weights, less payload etc. (we will not comment prizing due to competitional law)

ODraft placeholders for MPR decisions

> Example; Years or Mileage or Energy throughput, whichever comes first

EU 2019/<u>1242 CO</u>2 standards (incl. review), vehicle groups >16t. :

Vehicle group	Annual mileage (km)	Long Haul		rban Municipa livery lutility	Construction n	Typical annual energy throughput (MWh)	Vehicles specified for the purpose of urban delivery and regional	Battery Energy based (SOCE) MPR for N3>16t						
4-UD	60 000			х		55	delivery typically has an annual energy throughput < 100 MWh	Battery energy based MPR for N3>16t	HD-OVC-HEV	HD-PEV				
4-RD	78 000		х			78								
4-LH	98 000	х				140	Vehicles specified for the purpose							
4v	60 000			х	×	150	of long-haul transport, municipal utility and construction typically	From start of life to [XX] years or [XX] km, or	[YY] per cent	[ZZ] per cent				
5-RD	78 000		х			85	has an annual energy throughput	[XX] MWh whichever comes first and						
5-LH	116 000	х				150	> 140 MWh							
5v	60 000			x	X	150								
9-RD	73 000		x			90	Basic VECTO output from	Main Lifetime	[YY] per cent	[ZZ] per cent				
9-LH	108 000	х				210	 « standard » BEV configuration as A first approach 		[11]per com	[DD] per cent				
9v	60 000			х	x	160	(no sensitivity analysis on vehicle	From start of life to [XX] years or [XX] km, or						
10-RD	68 000		х			80	components / simulations conditions to analyze spread)	[XX] MWh whichever comes first and						
10-LH	107 000	х				150	conditions to analyze spread)							
10v	60 000	Groups	Description	Capacity / Energy Throughpu	Years	MPR (socc)		Additional Lifetime	[YY] per cent	[ZZ] per cent				
			53,54, 1s, 1, 1v, 2, (N2)	2v X ₁	Y ₁	Z ₁		From start of life to [XX] years or [XX] km, or						
		2	3, 3v (12t. <r4x2 <16t<="" td=""><td>.) X₂</td><td>Y₂</td><td>Z₂</td><td></td><td>[XX] MWh whichever comes first and</td><td></td><td></td></r4x2>	.) X ₂	Y ₂	Z ₂		[XX] MWh whichever comes first and						
		3	4-UD, 4-RD, 5-RD, 9 10-RD, 11, 12 (urban & regional del	, X ³	Y ₃	Z ₃								
			4-LH, 4v, 5-LH, 5v, 9- 10-LH, 10v, 11v, 12v, 1 (long-haul, municipal u	6, 16v v	Ya	Z ₄		• Other tables; N2, N3	-16t M2	M3				

Table 2

The metrics; mileage/ET/CT/FCE and [SB] are going to be determined in minimum 5 years for monitoring phase.

RESULTING FCE FROM ENERGY THROUGHPUT VS. MILEAGE AND YEARS FOR DIFFERENT CASES

lbs	kg	USA vehicle Class	tonnes	EU vehicle group	vehicle category	UN categories		tonnes	JPN Truck group	JPN Tractor group	JPN Route Bus group	JPN Bus group	Energy Throughput MPR Differentiation
6000	2,722	1		N.A.	N1,M1 and M2<3.5t	categories 1-	UN						20%
8500	3,856	2		N.A.	3.5t <m2<5t< td=""><td>1, 1-2 and category 2</td><td>GTR22</td><td></td><td>30%</td></m2<5t<>	1, 1-2 and category 2	GTR22		30%				
10000	4,536	3	3.5	N.A.	N2<12t 5t < M3 <7.5t M3>7.5t	Category 2 vehicles		35/5	TATO		BR1	B1 -	40%
14000	6,350	4	7	N.A.					T1/T2/ T3/T4				50%
16000	7,257	5	7.4	1s					10/14	TT1		B2	50%
			7.5	1		not exceeding 16		8	T5		DIXI	UZ	50%
19500	8,845	6	10	2		tonnes		10	T6		BR2	B3	52%
26000	11,793	7	12	3	12t <n3<16t M3>7.5t</n3<16t 			12	T7		BR3	B4 B5	52%
33000	14,969	8	12	5				14	T8		BR4		5270
60000	27,216	8		4,5,9,10,11,12,16	N3>16t M3>7.5t	Category 2 vehicles exceeding 16 tonnes		16	T9			B6	
			>16					20 20<	T10 T11	TT2	BR5	B7	100%

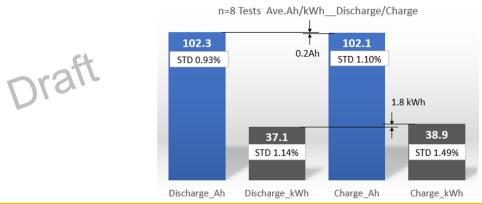
Observation

- Different use-cases resulting in different energy throughput, whilst years stay same
- Mileage and FCE do not correlate linearly
- For smaller trucks with small batteries c-rate increases. Thus, smaller trucks with lower installed battery energy cycled more often

OUBC vs. UBE. OICA compromise proposal: keep both in parallel – monitoring

Results(2) Comparison UBE vs. UBC

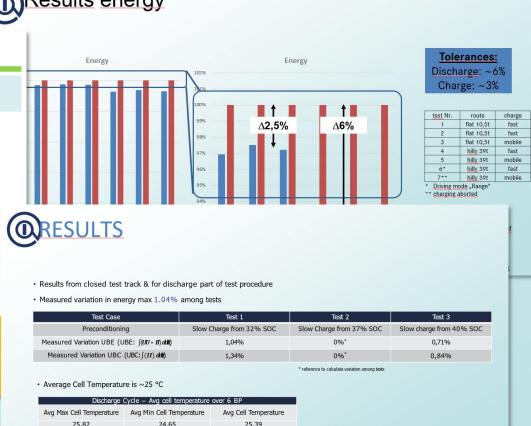
> RTE test results of discharging up to On-Board discharge and charging with DC/AC for each method.
> Compare average UBE(kWh) and UBC(Ah)



<Result>

- > UBE(kWh) ; Due to internal resistance, discharge is Δ1.8kWh compared to charging. The variation is 1.14-1.49% which is much larger than UBC due to voltage multiplication.
 > UBC(Ah) ; Measured using DC charging and AC charging, The values are almost same,
 - the difference is $\Delta 0.2$ Ah. Variation are 0.93 1.10 %.

Conclusion



- Capacity is the same in the charging and discharging phase (e.g. Coulomb efficiency approximately 100%)
- Capacity is more reproducibly measurable, since only the current sensor with very high accuracy (e.g. error << 1%) is used.
- Capacity can be measured easily and reproducibly as well as technology neutral during the charging process at the charging station. Easy to replicate by third-party organizations or even by customers. Which leads to given transparency and possible validation at all time.

Keep charging results from type approval and in-service

Procedure for non-BiDi vehicles

Unlike WLTP which has a defined reference drive cycle, the current proposal for HD to drive on the road with an average speed has a lot of uncertainties during test, eg. driver behaviors, road conditions, brake etc.

Energy_{discharged}=Energy_{charged}+Energy_{regenerated}

Metrics:

Charging process is more static and controllable which eliminates the uncertainties from road test

The customers care charging as much as discharging as operation cost is the key

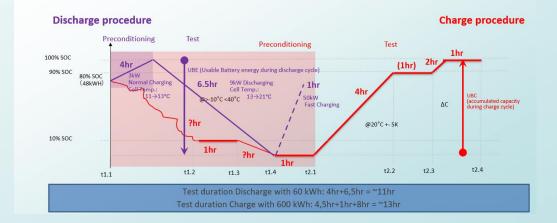
Proposal:

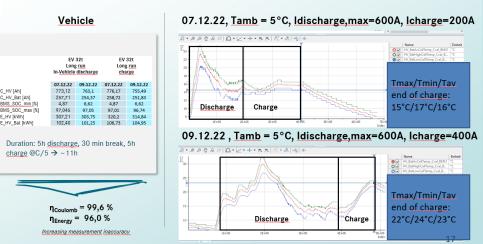
Report and monitor measurements from charging(following the discharge procedure) as a complement to discharge measurements $SOCE_{measured}$ shall be calculated by UBE/UBC from both charge and discharge measurements for the monitor verification.

Bottom line:

Results from charging cycle shall be reviewed and compared to results from discharging cycle and to be discussed within phase II of HDV GTR22b whether to this should be reflected within the procedure itself

@TEST PROCEDURE DISCHARGE & CHARGE





COMPARING SINGLE CELL VS. PACK VS. IN-VEHICLE DISCHARGE AND CHARGE RESULTS, EFFICIENCIES ARE ALMOST SAME

Keep charging results from type approval and in-service

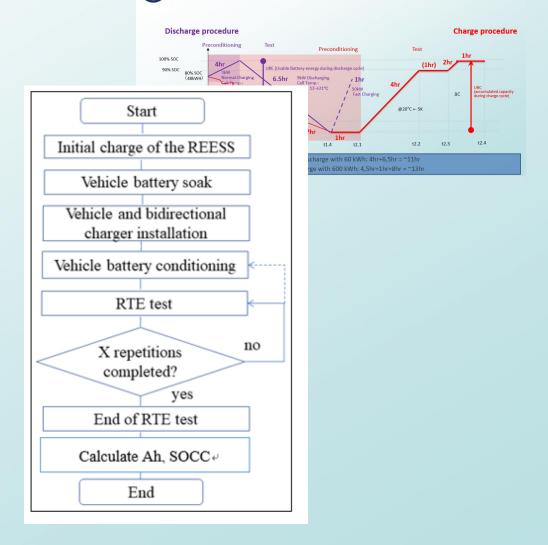
For BiDi vehicles

Bidi vehicles also require charging results. Especially during the monitoring phase.

It is necessary to confirm the validity of the Bidi test (again, especially during monitoring phase) due to a lack of experience with it in HDV industry.

Proposal:

Different procedure and by this test flow chart to 1a/b: confirming the accuracy of the test at RTE (Round Trip Efficiency).

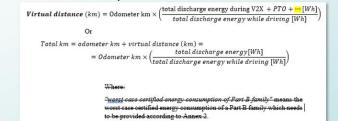


(O) TEST PROCEDURE DISCHARGE & CHARGE

DEnergy/Capacity throughput

OPOSITION ON VIRTUAL MILEAGE

Based on real-world data, we request EVE IWG to rethink the virtual mileage proposal and to consider energy throughput as additional lifetime requirement.



At the option of the manufacturer, instead of using the worst case certified energy consumption value of the Part B family, the manufacturer may be allowed to use any higher energy consumption value.

The total distance used for confirming the compliance with the minimum performance requirements will consist of the sum of the distance driven and the virtual distance. The total virtual distance shall be recorded and monitored

Considering the unique configurations and/or functionalities of HD vehicles:

Based on expert discussions and real-world data, it is not feasible to differentiate all the seperate electric vehicle-internal energy flows 1)

2) OICA prefers to apply the whole battery energy/capacity throughput instead of mileage for MPR criteria.

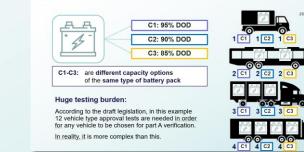


8

 $(\mathbf{0})$



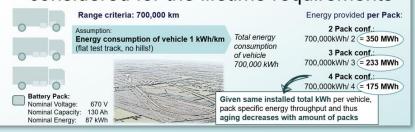
One battery pack - many applications



EU-VII ANTI-TAMPERING

The manufacturer shall prevent the possibility of exploiting vulnerabilities referred to in paragraph 7 to the fullest extent possible based on the best available knowledge at the time of type approval. When such a vulnerability is found, the manufacturer shall take all the possible measures taking into account the state of technology to remove the vulnerability, by software update or any other appropriate means.

Installed system capacity must be considered for the lifetime requirements



Conclusion

- Virtual mileage and with this Part C odometer needs to be deleted.
- To the customer it adds no value and is not feasible for HDV OEMs to distinguish all the different energy flows from battery to the systems as PTO and so on...

External on-board verification for Method 1a/b



Repetition of tests can only check the precision, accuracy of tests can only be checked via reference
 Measurement accuracy can not be verified by repetition of tests

•Unlike WLTP which has a defined reference drive cycle and stable environmental conditions for the use of external measurement equipment (not on-road), the current proposal for HD to drive on the road with an average speed has a lot of uncertainties, thus the tests can not be checked for either precision or accuracy

Conclusion

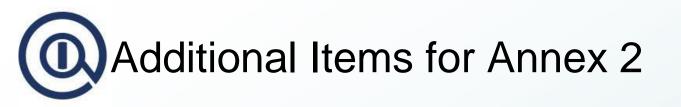
- The accuracy of on-board sensors and energy counter could be verified during type approval through a test-rig based component test combined with a parent vehicle test verification. Declared values can be verified.
- Accuracy verification: value from charging station vs. accuracy of external measurement equipment vs. ...

Monitor field data before setting statistical pass/fail criteria

- The pass/fail criteria for light-duty GTR22 has been established on a large amount of field data and has based on the assumption of homogeneity in the customer usage
- Assuming the same statistical model can equally be applied for LD and HD vehicles need to be verified but most likely adaptions need to be made

Proposal

Pass/fail criteria shall be set after the monitoring phase



Annex2 Values to be read from vehicles:

Proposal:

OICA proposes to add the following non-exhaustive item-list to **Annex 2 from the Method1a/b & 2 studies** and the statistical analysis of MPR metrics during this period in order to to be able to adapt the procedures accordingly after monitoring phase.

- Total soak and driving time (sum of the time driven as reported by the odometer and the other (i.e., PTO/V2X) time) (hours)
- Total charging time (sum of the hour driven as reported by the odometer and the other (i.e., PTO/V2X/charging) time) (hours)
- > Total discharging time that C-rate was more than or equal to C/2 (hours)
- Total time for test preparation

Conclusion

 It is important for OICA-HD to present factors that are expected to be relevant to be collected by monitors in order to consider MPR metrics for HD battery degradation.

SUPPORTING DRAFTING ACTIVITIES AND SUMMARY: 4-COLUMNS DOCUMENT

OICA worked out 110 pages of comments!

- 1) Expressed within a "4-column document", commenting on the draft text
- 2) Taking into consideration state of the art technology and outlook
- 3) Focussing on metrics, test methods, definitions, feasibility and regional differences for electric HDV vehicles

Basic principles:

- 1) Non-invasive measurement procedures: customer vehicles in service must be operated safely and without damaging the customers' property
- 2) External equipment while driving very problematic (robust measurement, non-invasive, vehicle hardware only for regulation): Homologation of internal current sensor (high accuracy anyways basis for good battery performance) and checkup via repeated in-service measurements
- 3) Measurement procedure options charging and discharging: to recognize different infrastructures and vehicle types
- 4) Flexibilities on metrics capacity vs. energy: taking different accuracies and allowed tolerances into account

14

- 5) Additional lifetime requirement: Energy Throughput more meaningful than mileage in heavy duty business.
- 6) Modularity: family concept must consider number of same packs. MPRs must consider vehicle configuration.