



EVE IWG 72nd session pilot phase

June 17th

-online-



Pilot Phase location and timing

- confirmed -

	CW25	CW26	CW27	Point of contact	Method	Confirmation	Vehicle	Participants
Volvo			Sweden, Hällered Proving Ground, 1st July	Elie Garcia, Elie.garcia@volvo. com	1a	Yes	N3 Truck, >16t Tractor	EPA , James Sanchez
Scania		Sweden, Södertällje, 27.-28. June		Rong Sun, Rong.sun@scania. com	1a	Yes	N3 Truck, >16t (Rigid/Tractor)	JRC , Elena Paffumi, Gian Luca
Daimler Truck	Germany, Stuttgart, 19.-21. June	Germany, Stuttgart, whole week	Germany, Stuttgart whole week	Axel Trentzsch, axel.trentzsch@dai mlertruck.com	1b	Yes	CW25: M3 Citybus CW26-27: N3 Truck >16t Rigid	JRC , Elena Paffumi, Gian Luca UTAC , Jose Fernandes TÜV Nord , Manuel Hagemann (<i>Witnessing as technical service</i>)



SOCE verification by $UBE_{measured}$ in Part A & certification

- Based on the current text, SOCE correlation has to be verified based on $UBE_{measured}$
- For $UBE_{measured}$ we believe in possible alternatives which are displayed below
- OICA intends to verify the following items during the pilot phase of Method1a and 1b
 - ⇒ The impact of loading rates on UBE and UBC
 - ⇒ Justification of alternative proposals listed below, especially #4
 - ⇒ Improvement of WD description for Method1a and 1b



#	$UBE_{measured}$ verification	comments	Resulting formular
1	Verify Current, Multiply with on-board Voltage to get $UBE_{measured}$	Accuracy low, feasibility limited and external influences of voltage measurement too high	$x_i = SOCE_{read,i} - \frac{\int I_{external} dt * U_{monitored}}{UBE_{certified}} * 100$
2	Verify current and Voltage begin of life externally on pack level By that, sensors are being certified life-long (see also EU-VI PEMS)	On test rig level, accuracy of signal verification is very high and approved/well established	$x_{I,i} = I_{read} - I_{measured}$ $x_{U,j} = U_{read} - U_{measured}$
3	Verify current and Voltage in alignment with authorities	Depending on each cps authority	No formular needed anymore
4	Verify $UBE_{measured}$ by comparing charged energy from charger with on-board energy	Using the charge cycle to verify UBE $UBE_{discharged}$ and $UBE_{charged}$ may be subject to a maximum allowed deviation of e.g. 5% (comparing slides 3 & 4)	$x_i = SOCE_{read,i} - \frac{UBE_{charged}}{UBE_{certified}} * 100; UBE_{certified} = UBE_{charged,begin\ of\ life}$