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Mis en forme : Français (France), Exposant

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Proposal for amendments to informal document GRRF-78-14

2.3.4. "Advanced Driver Assistance Steering System" means a system, additional to the main steering system, that provides assistance to the driver in steering the vehicle but in which the driver remains at all times in primary control of the vehicle. It comprises one or both of the following functions:

2.3.4.1. "Automatically commanded steering function" means the function within a complex electronic control system where actuation of the steering system can result from automatic evaluation of signals initiated on-board the vehicle, possibly in conjunction with passive infrastructure features, to generate continuous control action in order to assist the driver in following a particular path, **such as**;

- (a) low speed manoeuvring ~~or~~,
- (b) parking operations ~~or~~,
- (c) ~~driving operations in highway which is designed for non urban multilane road sections with constructional separation of the two directions of traffic and at least two lanes into the driving direction.~~
lane keeping operation or
- (d) lane changing operation.**

Commenté [HH1]:

1)Use instead Lane Keeping "Lane Guidance". To be confirmed by a native speaker. Our understanding: a comfortable lane keeping

2.3.4.2. "Corrective steering function" means the discontinuous control function within a complex electronic control system whereby, for a limited duration, changes to the steering angle of one or more wheels may result from the automatic evaluation of signals initiated on-board the vehicle, in order to maintain the basic desired path of the vehicle or to influence the vehicle's dynamic behaviour.

Systems that do not themselves positively actuate the steering system but that, possibly in conjunction with passive infrastructure features, simply warn the driver of a deviation from the ideal path of the vehicle, or of an unseen hazard, by means of a tactile warning transmitted through the steering control, are also considered to be corrective steering.

2.3.4.2.1. “Lane Keeping Assistance System” means a system which assists the driver in keeping the vehicle within the chosen lane, by influencing the lateral movement of the vehicle.

5.1.6. Advanced driver assistance steering systems shall only be approved in accordance with this Regulation where the function does not cause any deterioration in the performance of the basic steering system. In addition they shall be designed such that the driver may, at any time and by deliberate action¹⁾, override the function.

¹⁾ The vehicle manufacturer shall provide a list of these actions to the technical service at the time of type approval and it shall be annexed to the test report and mentioned in the communication form according to Annex I.

5.1.6.1. Whenever the Automatically Commanded Steering function becomes operational, this shall be indicated to the driver and the control action shall be automatically disabled if the vehicle speed exceeds the set limit of 10 km/h by more than 20 per cent or the signals to be evaluated are no longer being received. Any termination of control shall produce a short but distinctive driver warning by a visual signal and either an acoustic signal or by imposing a tactile warning signal on the steering control.

5.1.6.2. Notwithstanding the requirements of paragraph 5.1.6.1., the Automatically Commanded Steering function ~~designed for a restricted area where road traffic environment and infrastructure condition are well developed such as a highway, e.g. Automated Lane Change system, Enhanced Lane Keeping Assistance System, Automated Safety Stop System in case of Driver's Medical Emergency etc.~~ **to assist the driver in the following steering operations** may be enabled at vehicle speed greater than 10km/h, provided that the following requirements of paragraph 5.1.6.2.1. to ~~5.1.6.2.4.5.1.6.2.6.~~ are all met;

- **lane keeping operation or**
- **lane changing operation in a restricted area which has multilane road sections with constructional separation of the two directions of traffic, [no intersections] and no mixed traffic with pedestrians, cyclists and oncoming vehicles.**

5.1.6.2.1. The system shall be designed so that excessive intervention of steering control (e.g. an excessive steering torque) is suppressed to assure the steering operability by the driver and to avoid unexpected vehicle behaviour, during its operation. In addition, it shall be designed such that in its non-fault condition any intervention shall finish smoothly **to avoid the abrupt change of vehicle behavior [so as not to confuse the driver]**.

The steering control effort necessary to counteract an intervention shall not exceed the specified value in paragraph 6.2.4.2. for a normally operating intact system.

5.1.6.2.2. When the system is temporarily not available, for example due to inclement weather conditions, the system shall clearly inform the driver about the system status, except if the system is in the OFF mode, e.g. switched off. This exception does not affect the required warning in the case of a system malfunction.

5.1.6.2.3. The vehicle shall be equipped with a means for the driver to activate or deactivate the Automatically Commanded Steering function.

5.1.6.2.4. The Automatically Commanded Steering Function shall have an adequate steering control strategy ~~including a means to detect the events that is predicted to influence vehicle travelling path, such as lane markings and obstacles on a road etc. and ensuring the safe transition at the termination of its control from automatically commanded steering to manual steering which meets all the following conditions;~~

(a) **To include a means to detect the events elements, which are used to evaluate the ~~that is predicted to influence~~ vehicle travelling path, such as lane markings, obstacles on a road etc.,**

(b) **To ensure the safe transition at the termination of its control from automatically commanded steering to manual steering, based on the manufacture's safety concept including that on unordinary system conditions or driving situations, such as;**

- To choose whether the Automatically Commanded Steering Function for lane changing operation safely completes the vehicle movement to target lane or returns the vehicle to initial lane, against abrupt disturbance to vehicle travelling path, or

- To provide at least [2] seconds as the transient time from the Automatically Commanded Steering Function for lane keeping operation to manual steering by the driver,

- (b) The Automatically Commanded Steering Function shall have an adequate steering control and safety concept for safe operation of the function within use cases and operating conditions outlined ~~defined~~ by the vehicle manufacturer.

The control and safety concept shall include means to monitor the operation of the function continuously and shall ensure the transition to manual steering control by the driver, when the operation of the function exceeds the defined use cases or operating conditions. The system shall provide at least [2] seconds as the transient time from the Automatically Commanded Steering Function to manual steering by the driver.

- (c) To select the appropriate timing to produce the warning signal of termination prescribed in paragraph 5.1.6.1, to ensure the safe transition prescribed in above sub-paragraph (b) for the following conditions during the system intervention;

- System malfunction, or temporary ineffectiveness, or
- Abrupt disturbance to vehicle travelling path, such as sudden occurrences of a leading low-speed vehicle, closing adjacent-lane vehicle, stiff side wind, etc..

- (c) A visual warning signal clearly visible by the driver and at least an acoustic or haptic warning shall be provided to the driver when the system (function) becomes inoperational due to a system malfunction and the transition of control from the system to the driver is necessary.

~~The vehicle manufactures shall provide the Technical Service with the information on the control strategy at type approval.~~

- 5.1.6.2.5. The vehicle manufacturer shall provide the information on the system design including the conformity with the requirements of paragraph 5.1.6.2.1 to 5.1.6.2.4, to the Technical Service at the time of type approval,

[and it shall be annexed to the test report and mentioned in the communication form according to Annex I].

5.1.6.2.6. The vehicle manufacturer shall provide the owner's manual, cautionary statement or other appropriate means to clearly inform the driver of the responsibility of his/her steering operation even during the intervention of the automatically commanded steering function.

5.1.6.3. Special provisions for Lane Keeping Assistance System

5.1.6.3.1. The system shall meet the requirements of paragraph 5.1.6.2.1, 5.1.6.2.2 above.

5.1.6.3.2. The vehicle may be equipped with a means for the driver to activate or deactivate the Lane Keeping Assistance System.

5.1.6.3.3. [The system shall have at least 1 type of means to detect driver attention e.g. by sensing the driver's hands on the steering wheel. When the system detects inattention of the driver, it shall give an effective warning [, which shall be at least two means out of optical, acoustic and appropriate haptic,] to call the driver's attention.]

5.5.2. It must be possible to verify in a simple way the correct operational status of those Electronic Systems, which have control over steering. If special information is needed, this shall be made freely available. It must be possible to verify the correct operational status of those Electronic Systems ~~via the serial interface of the standard diagnostic connector (OBD).~~ via an electronic diagnostic interface or a visible observation of the failure warning signal status, following a "power-ON" and any bulb check.

In the case of the failure warning signal being in a common space, the common space must be observed to be functional prior to the failure warning signal status check.

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