D proposal (restricted to M1 vehicles):
“A continuous activation of a remote control device by the driver during the parking manoeuvre is required. The vehicle shall stop safely and immediately if:
- the activation button is released, or
- control transmission is lost, or
- the distance between the nearest point of the vehicle and the remote control device exceeds 2.5 m or at a distance with no overview and no direct vision of the vehicle and its path.

System design shall prevent the activation and operation of the RCP system or interventions into the RCP system by unauthorized remote control devices.”