

Transition Demand and Minimal Risk manoeuvre concepts

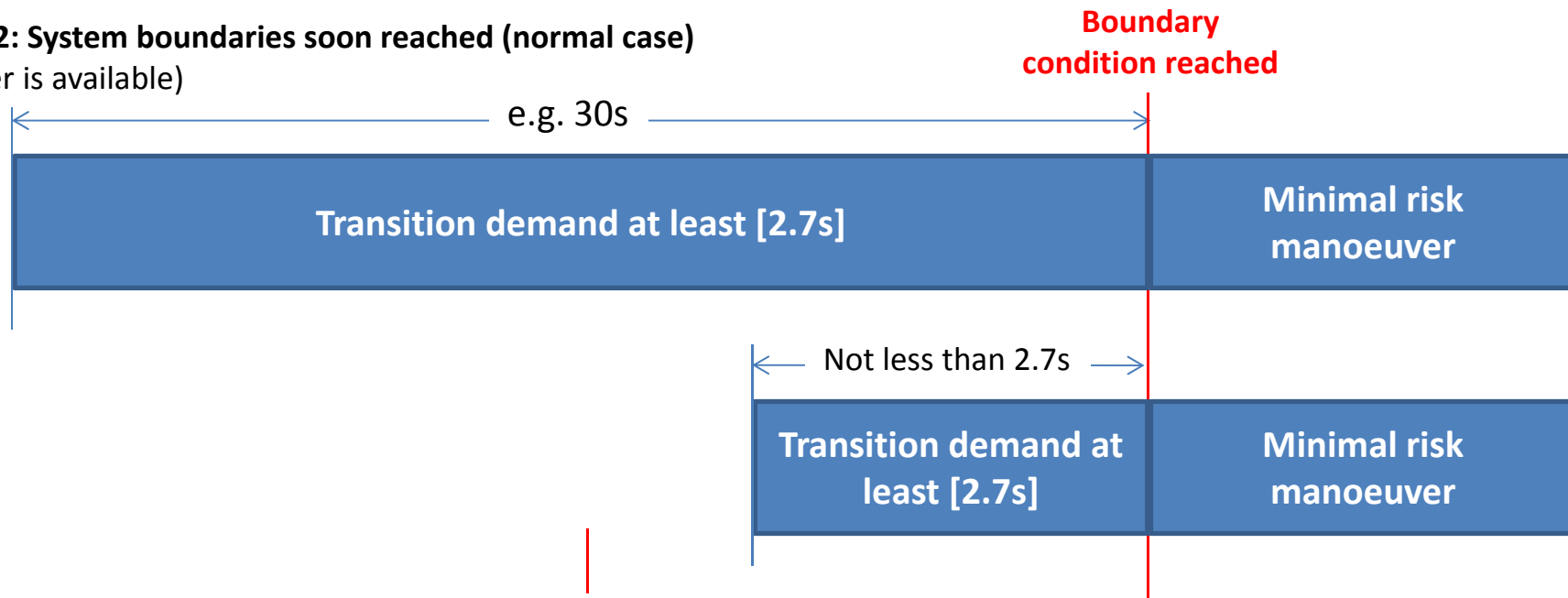
Case 1: Driver is detected not available

Driver can resume control at any time



Case 2: System boundaries soon reached (normal case)

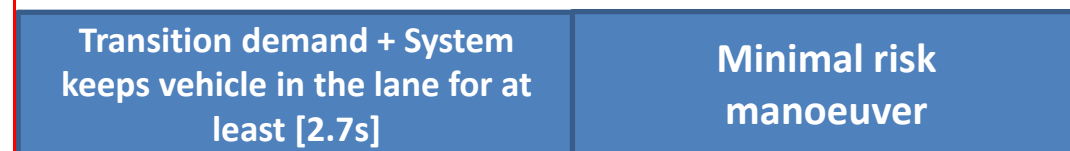
(Driver is available)



Case 3: Failure mode

(Driver is available)

Failure detected



* progressive measures; depends on the situation