

6th ACSF meeting

Tokyo, 19-21 April 2016

Industry proposal
Low Speed Systems < 60 kph Category B2

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5.6.1.1.4.1 The specified maximum lateral acceleration $a_{ys,max}$ shall not have a value of more than 3 m/s².
 Additionally, in case $v_{s,max}$ is greater than 60 km/h, $a_{yS,max}$ shall not be less than 1 m/s².

Justification:

The range of recommended design speeds in km/h on international roads is as follows:

Motorways	x	80	100	120	140
Express roads	60	80	100	120	x
Ordinary roads	60	80	100	x	x

Design speed (km/h)		60	80	100	120	140
Minimum radii in plane (corresponding to maximum superelevation 7%)		120	240	450	650	1 000
Maximum gradient (percentage not to be exceeded)*		8	7	6	5	4
Maximum longitudinal gradient in new tunnels**		5	5	5	5	5
Minimum radii at the highest point of the vertical alignment (in m)	One-way	1 500	3 000	6 000	10 000	18 000
	Two-way	1 600	4 500	10 000	-	-
Minimum radii at the lowest point of the vertical alignment		1 500	2 000	3 000	4 200	6 000

Source: ECE-TRANS-SC1-384e - EUROPEAN AGREEMENT ON MAIN INTERNATIONAL TRAFFIC ARTERIES (AGR)

Vsmax:

30 km/h: radius 240m = lateral acceleration is 0,289 m/s²

30 km/h: radius 650m = lateral acceleration is 0,107m/s²

60 km/h: radius 240m = lateral acceleration is 1,158m/s²

60 km/h: radius 650m = lateral acceleration is 0,428m/s²


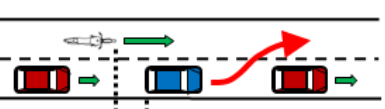

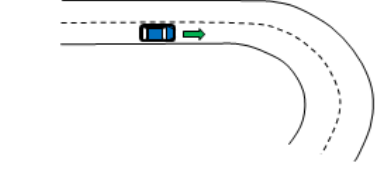
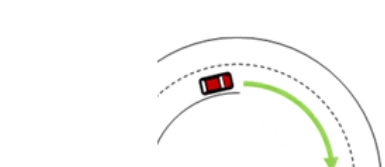
➤ Simplified calculation excluding e.g. Gradient

Conclusions:

- A low speed in a typical curve that can be found of a motorway will generate very low decelerations.
- Such low values of lateral acceleration (e.g. 0.2 m/s²) are very difficult to measure.
- From a practical standpoint, and given the lower criticality of the function at low speed (e.g. for a traffic jam assist), industry sees no necessity to define a minimum value for the lateral acceleration for maximum speed lower than 60km/h.

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Necessity of Tests for low speed systems $V_{smax} < 60 \text{ km/h}$

	<p>Tests for category E</p> <p>FU1 Lane keeping</p>	<p>➤ necessary, but with lower /other value of lateral acceleration</p>
	<p>FU2 Abort of lane change</p>	<p>➤ Not necessary, no lane change on B2 e.g. traffic jam assist</p>
	<p>FU3 Lane change</p>	
	<p>TR1 Lateral acceleration exceeded</p>	<p>➤ Not necessary, the system boundary of max. lateral acceleration of this systems is 1 m/s^2 on Highways</p>
	<p>TR2 Missing marking</p>	<p>➤ necessary, but with lower /other value of lateral acceleration</p>

Lateral accelerations from slide 2:

V_{smax} :

30 km/h: radius 240m = lateral acceleration is $0,289 \text{ m/s}^2$

30 km/h: radius 650m = lateral acceleration is $0,107 \text{ m/s}^2$




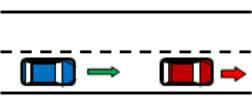
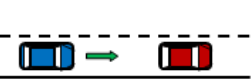
60 km/h: radius 240m = lateral acceleration is $1,158 \text{ m/s}^2$

60 km/h: radius 650m = lateral acceleration is $0,428 \text{ m/s}^2$

> Simplified calculation excluding e.g. gradient

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Neccesity of Tests for low speed systems $V_{smax} < 60$ kph

	TR3 Driver not available	<ul style="list-style-type: none"> ➤ necessary, but with lower /other value of lateral acceleration
	TR4 Failure	
	TR5 Taking over steering task by driver	
	EM1 Moving target (decel. 6 m/s^2)	<ul style="list-style-type: none"> ➤ Not necessary for systems $V_{smax} < [50 \text{ kph}]$, reflecting the Issue „measurability acceleration of 6 m/s^2“
	EM2 Stationary target	<ul style="list-style-type: none"> ➤ necessary

Lateral accelerations from slide 2:

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5.6.1.4.2.3

In case of a sudden unexpected event without imminent danger of a collision a transition demand shall be given immediately and the system shall follow the initial path ~~and shall not cross any lane marking for at least [4 s] after the transition demand, in the following cases~~

- if the speed of the vehicle with activated ACSF exceeds $v_{smax} + 5 \text{ km/h}$, ~~or a transition demand shall be given immediately and the.~~
- if the vehicle with activated ACSF [with V_{smax} higher than 60 km/h] ~~and~~ reaches a lateral acceleration of more than a_{ysmax} , or ~~3 m/s² a transition demand shall be given.~~
- if a system boundary is reached due to a missing lane marking, or
- if a single sensor failure occurs.

Justification:

For a lateral acceleration of 3 m/s^2 , the radius must be lower than 92m. The maximum lateral acceleration is lower than $1,2 \text{ m/s}^2$ for low speed systems (V_{smax} is 60 km/h or lower).