GTR9-5-08



Proposal for Procedure to Process FlexPLI Measurements in Rebound Phase



Action List Item 1. f) Test procedure (rebound phase, best practice, velocity measurement etc.)

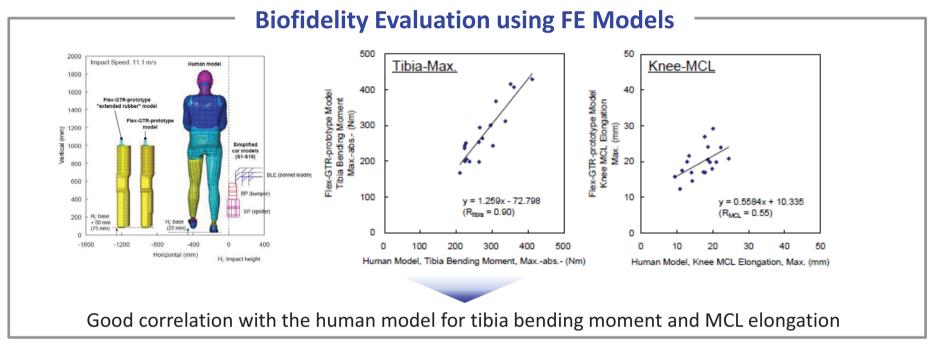
Presented by the pedestrian safety experts of the International Automobile Manufacturers' Organization (OICA)

5th IG GTR9-PH2 Meeting 6-7/December/2012



Background

The biofidelity of the FlexPLI has been validated by comparing its impact responses against simplified vehicle models with those of a human FE model.

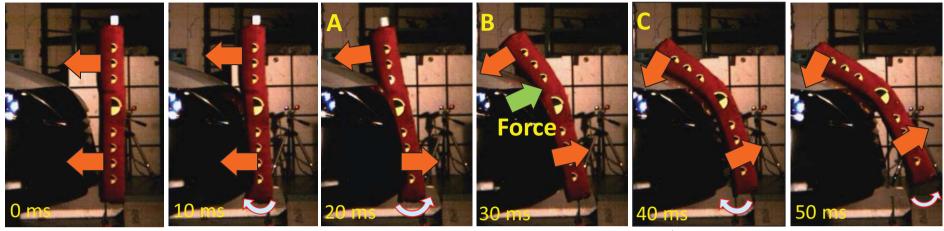


- However, some exceptional cases have been rarely seen that would require special processing of the measurements.
- Since the FlexPLI consists of elastic bone cores and ligament springs, a vibration may occur in the rebound phase of a car test, which could affect peak values of the injury measurements.
- The goal of this proposal is to come up with an appropriate assessment protocol by clarifying the time range where the vibration affects the results.

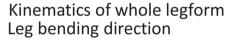


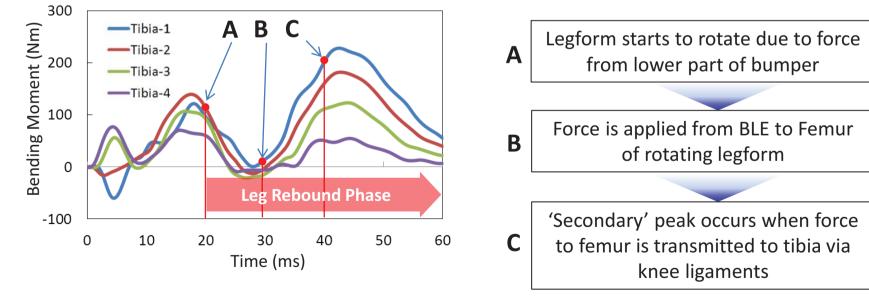
Example

GTR9-5-08



Tibia Bending Moment Time History

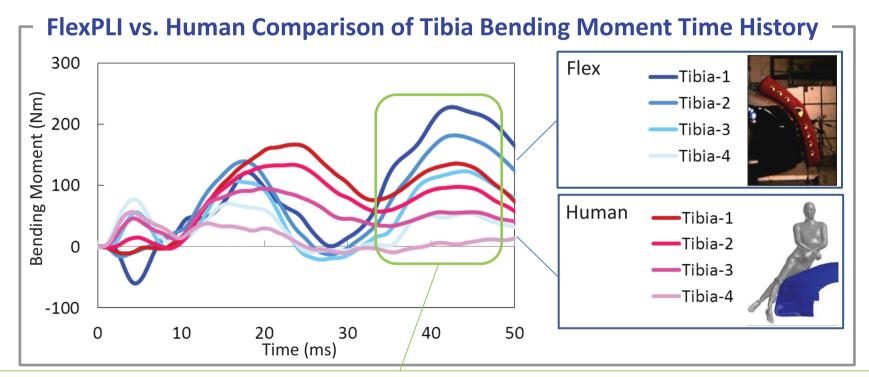




Overall peak of the tibia bending moment occurs at the timing when the leg is moving away from the vehicle during the rebound phase 3

Comparison with Human ResponseGTR9-5-08

Tibia bending moment time histories were compared between FlexPLI and human FE models for the same vehicle.



- Human model also exhibits bending moment increase during the rebound phase but overall peak bending moment is determined during vehicle interaction
- FlexPLI overestimates 'Secondary' peak and overall peak is determined in the rebound phase

Although human tibia also shows a 'secondary' peak of the tibia bending moment in the rebound phase, the FlexPLI overestimates it and the overall peak is determined in the rebound phase in some limited cases

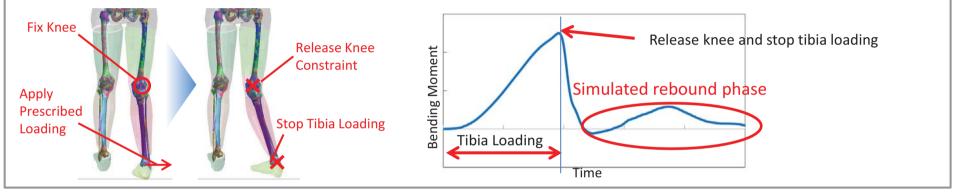


The largest possible tibia bending moment due to femur loading in the rebound phase was examined using a human FE model.

Methodology

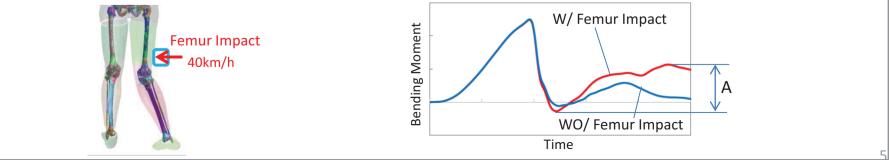
1. Prescribed Tibia Loading

- Prescribed load was applied to the tibia laterally with the knee fixed to represent bumper loading
- Then release the knee and stop tibia loading to represent 'rebound'



2. Femur Loading

- Femur was loaded from an impactor at 40 km/h in the simulated rebound phase to investigate bending moment increase in this phase (moment difference A in the figure below)
- Peak MCL eningation was limited to 19 mm, which corresponds to 22 mm of proposed FlexPLI limit

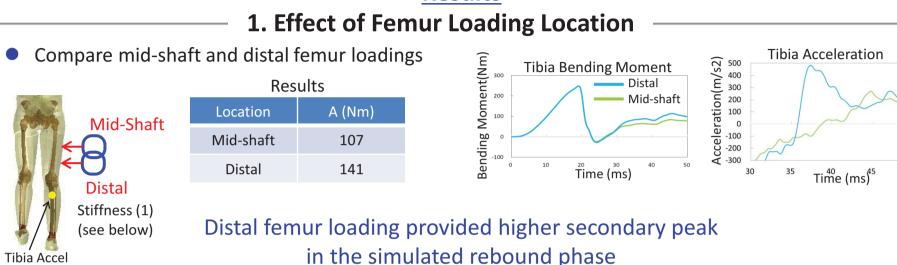




Measurement Location

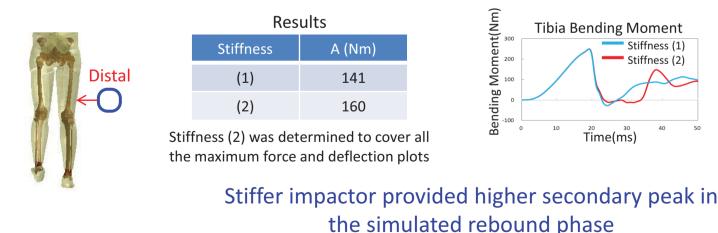
Estimation of Maximum Human Bending Monrehote in Rebound Phase

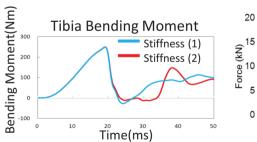
Results



2. Effect of Stiffness of Impactor Simulating BLE

Vary stiffness of impactor simulating BLE





Stiffness (1) Force (kN) Stiffness (2) 5 0 20 40 60 Λ 80 100 Deflection (mm) Peak force and deflection from BLE tests against passenger cars

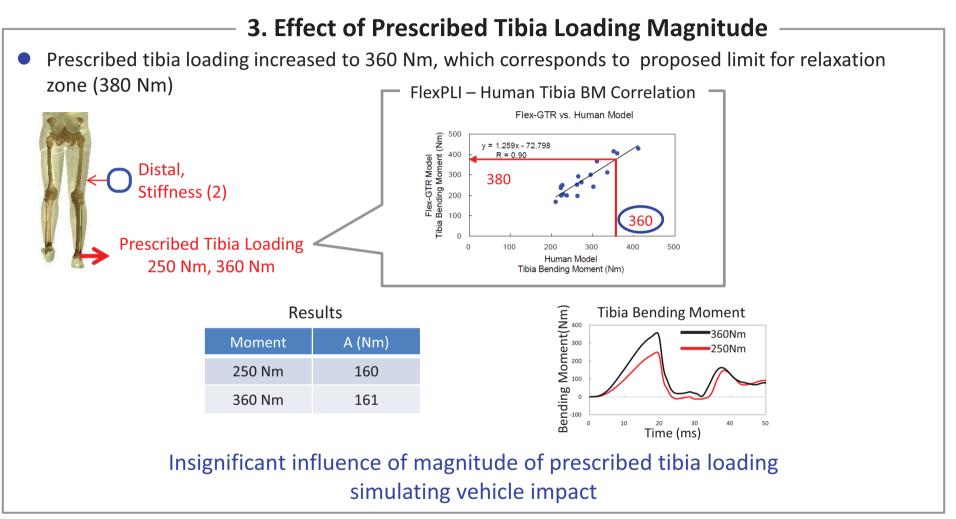
Impactor Force-Deflection

50



Estimation of Maximum Human Bending Moments in Rebound Phase

Results



Worst case scenario provided tibia bending moment increase of 161 Nm in the simulated rebound phase



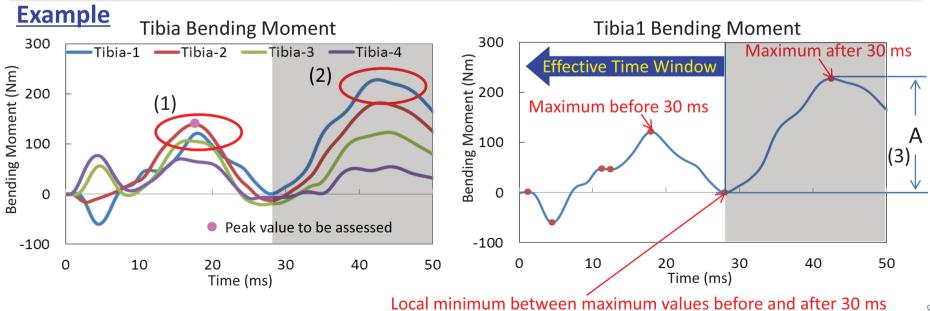
Proposed Protocol

The following protocol is proposed based upon the results of the investigation for the maximum possible bending moment in the rebound phase using a human model.

Proposal

In the cases where all of the following conditions (1) through (3) apply, tibia bending moment time histories shall be used up to the timing of the local minimum value between the maximum before 30 ms and the maximum after 30 ms. The timing shall be determined using the channel providing the maximum value of the four channels after 30 ms.

- (1) Local peak bending moments are clearly identified before 30 ms¹⁾
- (2) Overall maximum value is determined after 30 ms
- (3) Bending moment increase (A) of the channel providing the maximum value of the four channels after 30 ms is greater than 170 Nm
 1) Justification provided on the next page

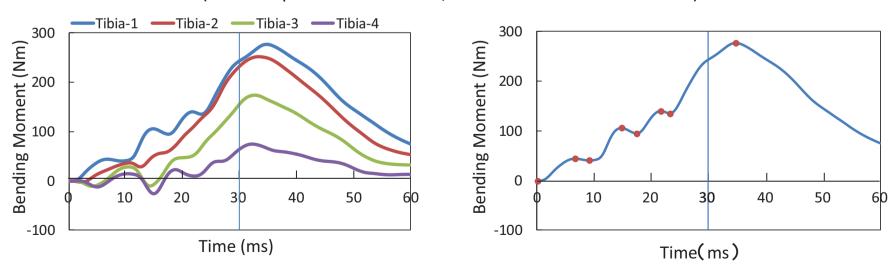




Justification for Note 1)

Why is it necessary to require clear identification of peak bending moment before 30 ms ?

- Tibia bending moment increase in the rebound phase is caused by the earlier impact of the legform against the lower part of the bumper and rotation of the femur
- Vehicles with later impact against the lower part of the bumper, such as SUVs, may result in later peak tibia bending moment
- Requirement (1) was included to avoid misinterpretation of the peak bending moment due to vehicle interaction with the tibia bending moment increase in the rebound phase in such cases



Example

(no clear peak before 30 ms, maximum value after 30 ms)



Case Study (1)

| Vehicle/Location | Sedan A/CTR | Sedan A/399 mm | Small Sport/CTR |
|---|---|---|--|
| Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 100 -100 0 10 20 30 40 50 | 300 200 -100 0 10 10 10 10 20 30 40 50 | 300 200 100 -100 0 10 20 30 40 50 |
| Channel for max after 30 ms Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 -100 0 10 20 30 40 50 | | $\begin{array}{c} 300\\ 200\\ 100\\ 0\\ -100\\ 0\\ 10\\ 20\\ 30\\ 40\\ 50\\ \end{array}$ |
| Clear Peak before 30 ms? | Yes | Yes | Yes |
| Overall peak after 30ms? | Yes | Yes | Yes |
| BM increase in rebound phase | 214 Nm | 244 Nm | 227 Nm |
| Apply proposed protocol? | Yes | yes | Yes |
| | Peak value to be asse | essed OPeak before 30 ms OPeak after 30 ms | Cocal minimum between two peaks Overall maximum |



Case Study (2)

| Vehicle/Location | Small Sport/347 mm | Sedan B/CTR | Sedan B/359 mm |
|---|---|---|--|
| Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 200 100 0 -100 | 300 200 100 -100 | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 200 100 0 -100 |
| Channel for max after 30 ms Vertical: Bending Moment (Nm) Horizontal: Time (ms) | $\begin{array}{c} 0 & 10 & 20 & 30 & 40 & 50 \\ \hline 300 \\ 200 \\ 100 \\ 0 \\ -100 \\ 0 \\ 10 & 20 & 30 & 40 \\ \end{array}$ | 0 10 20 30 40 50 300 200 100 -100 0 10 20 30 40 50 | $\begin{array}{c} 0 & 10 & 20 & 30 & 40 & 50 \\ 300 \\ 200 \\ 100 \\ 0 \\ -100 \\ 0 \\ 10 & 20 & 30 & 40 & 50 \end{array}$ |
| Clear Peak before 30 ms? | Yes | Yes | Yes |
| Overall peak after 30ms? | Yes | No | Νο |
| BM increase in rebound phase | 70 Nm | 23 Nm | 172 Nm |
| Apply proposed protocol? | No | No | No |
| | • Declaration to be see | OPeak before 30 ms | Local minimum between two peaks |

Peak value to be assessed

Peak before 30 msPeak after 30 ms



Case Study (3)

| Vehicle/Location | Sedan C/389 mm | Sedan D/CTR | Sedan D/512 mm |
|---|--|--|--|
| Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 -100 0 10 20 10 20 10 20 10 20 30 40 50 | 300 Tibia 1 Tibia-2 Tibia-3 Tibia-4 100 -100 0 10 20 30 40 50 | 300 100 -100 0 10 10 10 10 10 10 10 10 |
| Channel for max after 30 ms Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 -100 0 10 20 30 40 50 | $\begin{array}{c} 300\\ 200\\ 100\\ 0\\ -100\\ 0\\ 10\\ 20\\ 30\\ 40\\ 50\\ \end{array}$ | $\begin{array}{c} 300\\ 200\\ 100\\ 0\\ -100\\ 0 \end{array} \begin{array}{c} 0\\ 10\\ 20\\ 30\\ 40 \end{array} \begin{array}{c} 0\\ 0\\ 10\\ 20\\ 30\\ 40 \end{array} \begin{array}{c} 0\\ 50\\ 50\\ 50\\ 50\\ 50\\ 50\\ 50\\ 50\\ 50\\ $ |
| Clear Peak before 30 ms? | Yes | Yes | Yes |
| Overall peak after 30ms? | No | No | No |
| BM increase in rebound phase | 270 Nm | 169 Nm | 131 Nm |
| Apply proposed protocol? | No | No | No |
| | Deak value to be ass | OPeak before 30 ms | Local minimum between two peaks |

Peak before 30 msPeak after 30 ms



Case Study (4)

| Vehicle/Location | Sedan E/CTR | Sedan E/379 mm | Sedan F/CTR |
|---|--|---|--|
| Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 -100 0 10 20 30 40 50 | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 200 100 0 100 0 100 0 10 20 30 40 50 | 300 200 100 -100 0 10 20 30 10 20 30 40 50 |
| Channel for max after 30 ms Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 0 -100 0 10 20 30 40 50 | | $\begin{array}{c} 300 \\ 200 \\ 100 \\ 0 \\ -100 \\ 0 \\ 10 \\ 20 \\ 30 \\ 40 \\ 50 \end{array}$ |
| Clear Peak before 30 ms? | Yes | Yes | Yes |
| Overall peak after 30ms? | No | No | No |
| BM increase in rebound phase | 73 Nm | 62 Nm | 171 Nm |
| Apply proposed protocol? | No | No | No |
| | • Deckvelve to be see | OPeak before 30 ms | Local minimum between two peaks |

Peak value to be assessed

Peak before 30 msPeak after 30 ms

Local minimum between two peaks



Case Study (5)

| Vehicle/Location | Sedan F/502 mm | MPV/145 mm | MPV/348 mm |
|---|--|---|--|
| Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 -100 0 10 20 10 20 10 20 10 20 30 40 50 | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 200 0 -100 0 10 20 30 40 50 | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 200 100 -100 0 10 20 30 40 50 |
| Channel for max after 30 ms Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 0 -100 0 10 20 30 40 50 | $\begin{array}{c} 300\\ 200\\ 100\\ 0\\ -100\\ 0\\ 0\\ 10\\ 20\\ 30\\ 40\\ 50\\ \end{array}$ | $\begin{array}{c} 300 \\ 200 \\ 100 \\ 0 \\ -100 \\ 0 \end{array} \begin{array}{c} \hline \\ 0 \\ 0 \\ 10 \\ 20 \\ 30 \\ 40 \\ 50 \end{array}$ |
| Clear Peak before 30 ms? | Yes | Yes | Yes |
| Overall peak after 30ms? | No | No | No |
| BM increase in rebound phase | 176 Nm | _ | _ |
| Apply proposed protocol? | No | No | No |
| | Posk value to be asset | OPeak before 30 ms | Local minimum between two peaks |

Peak before 30 msPeak after 30 ms



Case Study (6)

| Vehicle/Location | Small MPV/85 mm | Small MPV/488 mm | Small SUV/CTR |
|---|--|--|--|
| Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 200 100 -100 0 10 20 30 40 50 | 300 200 100 -100 0 10 20 30 40 50 | 300 Tibia-1 Tibia-2 Tibi-3 Tibia-4 200 100 -100 0 10 20 30 40 50 |
| Channel for max after 30 ms Vertical: Bending Moment (Nm) Horizontal: Time (ms) | $\begin{array}{c} 300\\ 200\\ 100\\ 0\\ -100\\ 0\\ 10\\ 20\\ 30\\ 40\\ 50\\ \end{array}$ | $\begin{array}{c} 300 \\ 200 \\ 100 \\ 0 \\ -100 \\ 0 \\ 10 \\ 20 \\ 30 \\ 40 \\ 50 \end{array}$ | $\begin{array}{c} 300 \\ 200 \\ 100 \\ 0 \\ -100 \\ 0 \\ 10 \\ 20 \\ 30 \\ 40 \\ 50 \end{array}$ |
| Clear Peak before 30 ms? | Yes | Yes | No |
| Overall peak after 30ms? | No | No | No |
| BM increase in rebound phase | 64 Nm | 111 Nm | — |
| Apply proposed protocol? | No | No | No |
| | • Declaration to be see | Peak before 30 ms | Local minimum between two peaks |

Peak value to be assessed

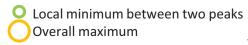
Peak before 30 msPeak after 30 ms

Local minimum between two peaks
Overall maximum





| Vehicle/Location | Simplified Vehicle (S08) |
|---|--|
| Tibia Moment Time History | 300 |
| Vertical: Bending Moment (Nm) Horizontal: Time (ms) | $\begin{array}{c} 200 \\ 100 \\ 0 \\ -100 \\ 0 \end{array} \begin{array}{c} 100 \\ 10 \end{array} \begin{array}{c} 20 \\ 30 \end{array} \begin{array}{c} 30 \\ 40 \end{array} \begin{array}{c} 50 \\ 50 \end{array}$ |
| Channel for max after 30 ms | ³⁰⁰ 200 - <u>O</u> <u>O</u> |
| Vertical: Bending Moment (Nm) Horizontal: Time (ms) | |
| Clear Peak before 30 ms? | Yes |
| Overall peak after 30ms? | Yes |
| BM increase in rebound phase | 95 Nm |
| Apply proposed protocol? | No |





FlexPLI vs. Human Model Comparisons-08

| Vehicle/Location | Small Sport/CTR | Small Sport/347 mm | Sedan B/CTR |
|--|-------------------------------------|----------------------|--|
| Flex Tibia Moment Time History | 300 | 300 | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 |
| Vertical: Bending Moment (Nm) Horizontal: Time (ms) | | | |
| Human Tibia Moment Time History | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 | 300 | 300 Tibia-1 Tibia-2 Tibia-3 Tibia-4 |
| Vertical: Bending Moment (Nm) Horizontal: Time (ms) | | | $\begin{array}{c} 200\\ 100\\ 0\\ -100\\ 0 \\ 5 \\ 10 \\ 15 \\ 20 \\ 25 \\ 30 \\ 35 \\ 40 \\ 45 \\ 50 \end{array}$ |
| Vehicle/Locatio | n Sedan B/3 | 359 mm Simplified Ve | biolo (COQ) |

| Vehicle/Location | Sedan B/359 mm | Simplified Vehicle (S08) |
|--|---|--|
| Flex Tibia Moment Time History Vertical: Bending Moment (Nm) Horizontal: Time (ms) | 300 Tibla-1 Tibla-2 Tibla-3 Tibla-4 200 100 0 100 0 10 0 10 0 10 20 30 40 50 | $\begin{array}{c} 300\\ 200\\ 100\\ -100\\ 0\\ 100\\ 0\\ 10\\ 20\\ 30\\ 40\\ 50 \end{array}$ |
| Human Tibia Moment Time History | 300 | 300 Tībia-1 Tībia-2 Tībia-3 Tībia-4 200 |
| Vertical:Bending Moment (Nm) Horizontal:Time (ms) | 100 | |
| | 0 10 20 30 40 50 | 0 10 20 30 40 50 |

FlexPLI tends to provide larger tibia bending moment increase in the rebound phase compared to the human model 17