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# Future HD GHG Test Procedure Considerations

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# Outline

- Background
- Overview of Procedures Under Consideration
- Full Simulation
- Controller-in-Loop
- Powertrain-in-Loop
  - Vehicle dependant method
  - Vehicle independent methods
- Test programs to support our investigations



# Background

- In 2011 EPA and NHTSA finalized our first ever heavy-duty (HD) greenhouse gas emissions (GHG) and fuel economy standards.
  - HD vehicles are certified with full vehicle simulation
  - HD engines were given a CO<sub>2</sub> standard on the FTP and SET.
  - Hybrids that included a transmission could generate credits with an A to B chassis or powertrain test.
  - Hybrids that didn't include a transmission could generate credits against the engine standard.
- In the HD GHG 1 rule we also spoke about how future regulations will look at how to more completely capture the complex interaction of the complete vehicle.



# Overview of Procedures Being Considered for Both Hybrid and Conventional HDV

- Full vehicle simulation with inputs for engine, transmission, accessories, etc.
- Controller in loop
- Engine in loop
- Powertrain in loop



# Powertrain in Loop



# Vehicle Dependant Powertrain Procedure Under Consideration

## **Inputs into the model**

- Coastdown data (A, B, C and inertia)
- Final drive ratio
- Tire radius
- Accessory loads

## **Cycles**

- Vehicle speed and grade vs. time
- Could be application specific

# Vehicle Dependant Powertrain Procedure

$$V_i = \left( \frac{T \cdot k_d}{r} - (A + B \cdot V_{i-1} + C \cdot V_{i-1}^2) - F_{brake,i-1} \right) \cdot \frac{t_i - t_{i-1}}{m} + V_{i-1}$$

$$f_n = \frac{V \cdot k_d}{2 \cdot \pi \cdot r}$$

$m$ : vehicle mass

$a$ : acceleration

$V$ : velocity

$T$ : torque at trans. output shaft

$f_n$ : rotational speed of trans. output shaft

$F$ : force

$k_d$ : final drive ratio

$r$ : tire radius

$t$ : time

$A, B, C$ : coastdown coefficients



# Vehicle Independent Powertrain Procedure Option 1

## Inputs into the model

- Vehicle mass (function of maximum powertrain power)
- Representative final drive ratio and tire radius used to represent a group of vehicles the powertrain would go into.

## Cycle

- Vehicle speed and power vs. time.
- Power cycle created from powertrain torque curve and is equivalent to conventional engine test power vs. time.



# Vehicle Independent Powertrain Procedure Option 1

$$P_{powertrain} = P_{engine} = m \cdot a_{cycle} \cdot V_{cycle} + P_{residual} + P_{acc.} + P_{trans.losses}$$

$$V_i = \left( \frac{T \cdot k_d}{r} - \frac{P_{residual}}{2 \cdot \pi \cdot f_{n,i-1}} - F_{brake,i-1} \right) \cdot \frac{t_i - t_{i-1}}{m} + V_{i-1}$$

$$f_n = \frac{V \cdot k_d}{2 \cdot \pi \cdot r}$$

$m$ : vehicle mass

shaft

$a$ : acceleration

$F$ : force

$V$ : velocity

$k_d$ : final drive ratio

$T$ : torque at trans. output shaft

$r$ : tire radius

$f_n$ : rotational speed of trans. output

$t$ : time



# Vehicle Independent Powertrain Procedure Option 2

- No vehicle model.
- Normalized cycle like engine testing.
- Vehicle speed cycle will define the speed setpoint.
- Torque will be defined so that power vs. time schedule will be equivalent to engine cycle.
- Cycle denormalized using powertrain torque.



# Overview of HDV Test Programs

- Chassis, over the road and powertrain testing at contractor lab.
- Powertrain testing of hybrid powertrain at EPA using the vehicle dependant and independent procedures.
- Chassis testing of hybrid and conventional vehicles at EC.
- Powertrain testing at Oakridge National Laboratory in the planning stages to look at vehicle dependant and independent procedures.



# EPA-SwRI Phase 1 Project Overview

- Program objectives
  - Provide comprehensive data sets for GEM validations
  - Evaluate different driving cycle impacts on CO2 emissions
  - Provide baseline data for powertrain system evaluations
- Vehicle Chassis Tests
  - One class 6 box truck - completed
  - One class 4 flat bed truck - completed
  - One Class 8 with AMT is being procured
  - One transit city bus will be procured in 2013
  - One garbage truck may be tested in 2013



# EPA-SwRI Phase 2 Project Overview

- Additional chassis tests at SwRI
  - 6 additional sets of vehicle variants per vehicle ( “a” and “c” coefficients, weights, optimized road load coefficient , etc.)
  - A total of 108 vehicle tests covering from Class 4-6 and 8
- Drive cycle evaluations
  - Three EPA certification cycles: 55 mph and 65 mph and transient cycles
  - Three additional cycles: delivery, parcel, and world harmonize test cycle
  - A city cycle will be selected for city transit bus test
- Over-the-road vehicle tests with a class 8 truck
  - One of critical routes to validate GEM with grade measurement



# EPA-SwRI Project Overview

## Powertrain Test

- Program objectives
  - Evaluate powertrain concept as one of certification options
  - Validate full vehicle simulation tool – GEM
  - Quantify alignment of CO<sub>2</sub> and criteria emissions
- Medium duty powertrain with ISB 300hp rating engine and Allison transmission
  - Analysis of test-to-test data variation between chassis and powertrain tests
  - Identification of test-system differences and potential solutions to minimize correlation differences between chassis and powertrain-based tests
- The same driving cycles as vehicle will be evaluated
- It is planned to evaluate engine FTP based cycles



## Conclusions

- EPA is looking at a wide spectrum of test procedures for a possible future regulation.
- Vehicle independent powertrain options are very similar to the procedures the HDH group is considering.
- EPA is involve in a number of test programs that have started or that are being planed to address the accuracy, representativeness, and feasibility of the different options.
- A vehicle independent powertrain option could work well to harmonize the US and HDH procedures if the US goes forward with a vehicle independent powertrain procedure.