- ✓ Lights enhance comfort with AVs
- ✓ Signals easily learned

AV EXTERNAL COMMUNICATIONS AUG 2, 2018





OVERVIEW

- Goals
 - Do light bar signals enable more 'trust/acceptance' of AVs?
 - Can these signals be learned?
 - Can previous VR study results hold with more complex

scenarios?

- Sample videos of scenarios tested
- Experimental design
- Study protocol
- Results
- Discussion









EXPERIMENTAL DESIGN

Independent Variables

- Vehicle intent message / signal
 - Driving
 - About to go
 - Yielding
- Structured traffic scenario
 - AV lead car at stop light
 - AV 3rd at stop light
 - AV 1st and 3rd at stop light
 - Parking
 - Turning
- Additional busy scenarios
 - Pedestrian at busy intersection
 - Passenger within vehicle traveling forward

Control Variables

- Order
 - Structured scenarios counterbalanced
 - Additional busy scenes presented after structured scenarios

Dependent Measures

- Trust
 - Trust survey
 - Given pre- and post- study
 - Included questions regarding lights in poststudy survey
- Light bar saliency
 - Participants noticing without prompting
- Signal learnability
 - Interpretation
 - Correct
 - Somewhat correct
 - Do not know
 - Incorrect
 - After X exposures, people learn what the signals mean









Trust Survey Questions:

- 1. I feel safe around automated vehicles.
- 2. I understand how automated vehicles work.
- 3. I think automated vehicles are reliable.
- 4. I trust automated vehicles.
- 5. The lights on the car help me understand what the vehicle will do.
- 6. Understanding what the vehicle will do is comforting.

Trust Survey Scoring:

- 1 Strongly Disagree
- 2 Somewhat Disagree
- 3 Slightly Disagree 4 Slightly Agree
- 5 Somewhat Agree
- 6 Strongly Agree



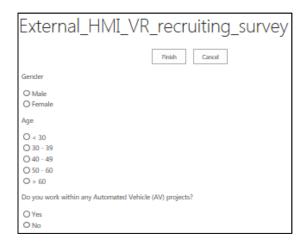


wrong -1
no answer / don't kn 0
somewhat correct 1
correct 2

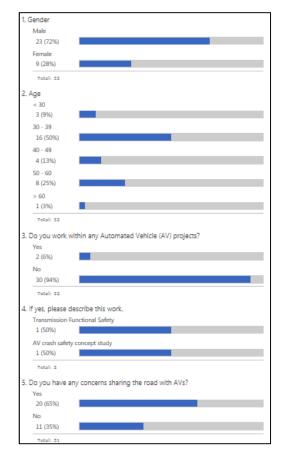


PARTICIPANTS

- Recruited non-manager, Ford employees in RIC
- 31 respondents
- 26 participated in study











PROTOCOL

- Trust "pre-survey"
 - Get a sense of how safe/comfortable participants feel with AVs on the road.
- Scenarios within VR environment learnability questions / scores
 - Five counterbalanced "simple scenarios"
 - After every structured scenario, participants described the situation in their own words.
 - Recorded when they commented on the lights and the accuracy of these comments.
 - If the participant had not mentioned the lights and what they mean after all presentations, they were shown the 3 light patterns and asked to explain what they mean.
 - Only one participant required this.
 - Two busy scenes, one as a pedestrian then one as a passenger in a vehicle, two minutes each
 - Participants were asked what each signal meant and comments were scored.
- Trust "post-survey"
 - Same as "pre-survey"
 - Two additional questions regarding lights
 - "The lights on the car helped me understand what the vehicle will do"
 - "Understanding what the vehicle will do is comforting"









RESULTS AND ANALYSIS - SUMMARY

Trust

• [positive impact]

Learnability

- [for any given signal, after 2 exposures]
- [for all signals, 5-10 exposures]
- Notice light bar
 - [2.9 exposures]
- Signal
 - [Yielding and About to Go learned first, Driving next]
- Scenario
 - [AV lead car most easily learned, other scenarios equal]
- Busy scenario carryover learning
 - [understanding maintains]



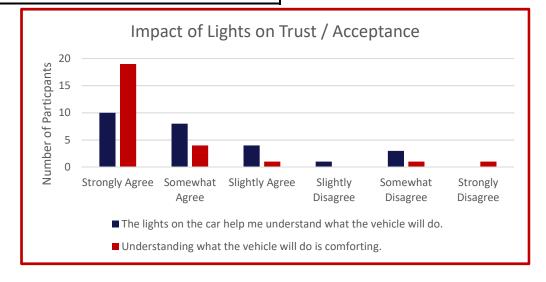


TRUST RESULTS AND ANALYSIS

	pre-study	post-study	
	survey average	survey average	change in score
1. I feel safe around automated vehicles.	4.04	4.31	0.27
2. I understand how automated vehicles work.	4.31	4.31	0.00
3. I think automated vehicles are reliable.	4.12	4.27	0.15
4. I trust automated vehicles.	3.92	4.15	0.23
5. The lights on the car help me understand what the vehicle wil	l do.	4.81	Not much
6. Understanding what the vehicle will do is comforting.		5.42	change

Trust Survey Scoring:						
1 Strongly Disagree						
2 Somewhat Disagree						
3 Slightly Disagree						
4 Slightly Agree						
5 Somewhat Agree						
6 Strongly Agree						

- The lights help people know what the vehicle will do and that is comforting to them
 - Likely increase with education







LEARNABILITY RESULTS AND ANALYSIS— SIMPLE SCENARIOS

Light bar noticeability

Average of 2.9 exposures

Signal

- "Yielding" and "about to go" were comprehended faster than "driving" (p < .05)
- "About to go" and "yielding" were comprehended equally (p = .58)

Scenario

- Simplest scenario [AV the lead car at a stop] was understood more easily than all others
 - · People understood other scenarios equally
- Learning translates from simple scenario to busy scenes
 - 76.9% [20/26 participants] noted their understanding stays the same after seeing all scenarios

Exposures to learn

- Comprehension of any given signal after 2 exposures.
 - Similar finding in previous VR studies
- 85% of participants took 9-10 exposures to comprehend all three signals.
 - 75% took 7 exposures, 50% took 5 exposures, 25% took 2-3 exposures
 - · Different finding than previous VR studies
 - · Could be a function of scenario complexity, counterbalanced order of scenes, number of participants, etc.

Learnability Scoring

wrong -1 no answer / don't kn 0 somewhat correct 1

orrect

Scenario Codes

- W] AV 1st/lead car at stop light
- [E] AV 3rd at stop light
- T] AV 1st/lead car and 3rd at stop light
- [O] Parking
- [R] Turning

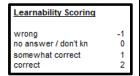
* Post-hoc Tukey tests on ordinal logistic regression models





LEARNABILITY RESULTS AND ANALYSIS — BUSY SCENES

- Majority of people understood.
- For the simplest scenario, scores were similar.
 - Some participants may have had this scenario early on in the study.
 - More people were unsure
 [compared to busy scenes] but few
 incorrectly interpreted.
 - Could indicate learning curve from simple scenario to busy scene.



		1		1		1			
Busy Ped	-1		0		1		2	1	Total
Driving		12%	2	8%	1	4%	19	76%	25
Yielding	1 1	4%	3	12%	1	4%	20	80%	25
A-t-G	1	4%	1	4%	1	4%	22	88%	25
Busy Pass	-1]	0]	1		2		Total
Driving	2	8%	4	16%	1	4%	18	72%	25
Yielding	3	12%	2	8%	2	8%	18	72%	25
A-t-G	1	4%	1	4%	0	0%	23	92%	25
Scenario W	-1	1	0	1	1	l	2	ı	Total
Driving	0	0%	5	23%	0	0%	17	77%	22
Yielding	1 1	5%	0	0%	2	10%	18	86%	21
A-t-G	0	0%	5	23%	0	0%	17	77%	22
			* Totalo or	o difforce	t due to sor	no portioin	anta nat na	tioina oiga	al
					'busy ped' a scenario w				order, at en



