Proposal for a new UN Regulation on uniform provisions concerning the approval of devices for reversing motion and motor vehicles with regard to the driver’s awareness of vulnerable road users behind vehicles

*This revised draft is still under construction for reflecting VRU-Proxi IWG #9 discussion results.

[Submitted by the Informal Working Group on Awareness of Vulnerable Road Users Proximity]

I. Proposal

UN Regulation No. XXX

Proposal for a new UN Regulation on uniform provisions concerning the approval of devices for reversing motion and motor vehicles with regard to the driver’s awareness of vulnerable road users behind vehicles

0. Introduction (for information)

0.1. The purpose of this regulation is to provide the provisions of reversing safety concerning on awareness of vulnerable road users proximity. UN regulation No.46 provides the provisions of indirect vision of motor vehicles. This regulation is to expand driver’s vision or awareness for vehicle rear side direction when vehicles in reversing motion. Therefore some requirements of this regulation can be satisfied with the devices for UN regulation No.46.

1. Scope

This Regulation applies to:

1.1. Approval of devices for reversing safety defined in part I intended to be fitted to vehicles of category [M and N].

1.2. Approval of vehicle installation of devices for reversing safety defined in part II if fitted to vehicles of category [M and N].
1.3. At the request of the manufacturer, Contracting Parties may grant approvals under Parts I and II to vehicles of other categories and devices for fitment to such vehicles.

1.4 Exemption to be defined in further discussion in IWG.

I. Devices for Reversing Motion

2. Definitions

For the purposes of this Regulation:

2.1. "Devices for indirect vision" means devices intended to give a clear view of the rear, side or front of the vehicle within the fields of vision defined in paragraph 15.2.3. These can be conventional mirrors, camera-monitors or other devices able to present information about the indirect field of vision to the driver.

2.1.1. "Mirror" means any device, excluding devices such as periscopes, intended to give a clear view to the rear, side or front of the vehicle within the fields of vision defined in paragraph 15.2.3. by means of a reflective surface.

2.1.1.1. "Interior mirror" means a device as defined in paragraph 2.1.1. above, which can be fitted in the passenger compartment of a vehicle.

2.1.1.2. "Exterior mirror" means a device as defined in paragraph 2.1.1. above, which can be mounted on the external surface of a vehicle.

2.1.1.3. "Surveillance mirror" means a mirror other than the ones defined in paragraph 2.1.1. above which can be fitted to the inside or outside of the vehicle in order to provide fields of vision other than those specified in paragraph 15.2.3. of this Regulation.

2.1.1.4. "r" means the average of the radii of curvature measured over the reflecting surface, in accordance with the method described in Annex 7.

2.1.1.5. "The radius of curvature at one point on the reflecting surface (rp)" means the arithmetical average of the principal radii of curvature ri and ri', i.e.:

\[ r_p = \frac{r_i + r_i'}{2} \]

2.1.1.6. "Spherical surface" means a surface, which has a constant and equal radius in all directions.

2.1.1.7. "Aspherical surface" means a surface, which has only in one plane a constant radius.

2.1.1.8. "Aspherical mirror" means a mirror composed of a spherical and an aspherical part, in which the transition of the reflecting surface from the spherical to the aspherical part has to be marked. The curvature of the main axis of the mirror is defined in the x/y coordinate system defined by the radius of the spherical primary calotte with:

\[ y = R - \sqrt{(R^2 - x^2)} + k(x - a) \]
Where:

- **R**: nominal radius in the spherical part
- **k**: constant for the change of curvature
- **a**: constant for the spherical size of the spherical primary calotte

2.1.1.9. "Centre of the reflecting surface" means the centre of the visible area of the reflecting surface.

2.1.1.10. "The radius of curvature of the constituent parts of the mirror" means the radius "c" of the arc of the circle which most closely approximates to the curved form of the part in question.

2.1.2. "Camera-monitor system (CMS)" means a device for indirect vision as defined in paragraph 2.1., where the field of vision is obtained by means of a camera-monitor combination as defined in paragraphs 2.1.2.1. and 2.1.2.2. below.

2.1.2.1. "Camera" means a device that renders an image of the outside world and then converts this image into a signal (e.g. video signal).

2.1.2.2. "Monitor" means a device that converts a signal into images that are rendered into the visual spectrum.

2.1.3. "Other devices for indirect vision" means devices as defined in paragraph 2.1. above, where the field of vision is not obtained by means of a mirror or a camera-monitor device.

2.1.4. "Vision support system" means a system to enable the driver to detect and/or see objects in the area adjacent to the vehicle.

2.1.5. "Luminance contrast" means the brightness ratio between an object and its immediate background/surrounding that allows the object to be distinguished from its background/surroundings. The definition is in accordance with the definition given in ISO 9241-302:2008.

2.1.6. "Resolution" means the smallest detail that can be discerned with a perceptual system, i.e. perceived as separate from the larger whole. The resolution of the human eye is indicated as "visual acuity".

2.1.7. "Critical object" means a cylindrical object with a height of 1.0 m and a diameter of 0.30 m.

2.1.8. "Critical perception" means the level of perception that can just be obtained under critical conditions via the viewing system used. This corresponds to the situation in which the representative scale of the critical object is multiple times larger than the smallest detail that can be perceived via the viewing system.

2.1.9. "Field of vision" means the section of the tri-dimensional space which is monitored with the help of a device for indirect vision. Unless otherwise stated, this is based on the view on ground level offered by a device and/or devices other than mirrors. This may be limited by the relevant detection distance corresponding to the critical object.

2.1.10. "Detection distance" means the distance measured from the centre of the lens of the camera to the point at which a critical object can just be perceived (as defined by the critical perception).
"Visual spectrum" means light with a wavelength within the range of the perceptual limits of the human eyes: 380-780 nm.

"Smear" is a bright line displayed on the monitor while sun light or light from other bright light sources is directly hitting into the lens of the camera.

“Mirror and CMS dual function system” means a CMS of Class I in which a monitor complying with this regulation is placed behind a semi-transparent mirror complying with this regulation. The monitor is visible in the CMS mode.

“Detection System” means a system as defined in paragraph 2.1.4. above, which uses both audible and optical signals, to enable the driver to detect objects in the area adjacent to the vehicle. This system shall fulfill the provisions of Annex 14.

"Audible information" means information using auditory signals provided by detection system as defined in paragraph 2.1.4. above to enable the driver to detect objects in the area adjacent to the vehicle. This system shall fulfill the provisions of Annex 14.

"Optical information" means information using optical signals provided by detection system as defined in paragraph 2.1.4. above to enable the driver to detect objects in the area adjacent to the vehicle. This system shall fulfill the provisions of Annex 14.

"Type of device for indirect vision” means devices that do not differ on the following essential characteristics:

(a) Design of the device inclusive, if pertinent, the attachment to the bodywork;

(b) In the case of mirrors, the class, the shape, the dimensions and radius of curvature of the mirror’s reflecting surface;

(c) In the case of camera-monitor systems, the class, the field of view, the magnification and resolution.

"Surveillance camera-monitor-recording device" means a camera and either a monitor or recording equipment other than the camera-monitor system defined in paragraph 2.1.2. above which can be fitted to the inside or outside of the vehicle in order to provide fields of vision other than those specified in paragraph 15.2.3. of this Regulation or to provide a security system within or around the vehicle.

To be changed to “Surveillance detection system”

"Class of device for indirect vision” means all devices having one or more common characteristics or functions. They are classified as follows:

2.4.1. Class I: "Rear-view device", giving the field of vision fulfilling the provisions of Regulation No. 46, 04 series of amendment paragraph 15.2.4.

2.4.2. Class II and III: "Main rear-view device", giving the fields of vision fulfilling the provisions of Regulation No. 46, 04 series of amendment paragraph 15.2.4.

2.4.3. Class IV: "Wide-angle view device", giving the field of vision fulfilling the provisions of Regulation No. 46, 04 series of amendment paragraph 15.2.4.
2.4.4. Class V: "Close-proximity view device", giving the field of vision fulfilling the provisions of Regulation No. 46, 04 series of amendment paragraph 15.2.4.

2.4.5. Class VI: "Front-view device", giving the field of vision fulfilling the provisions of Regulation No. 46, 04 series of amendment paragraph 15.2.4.

2.4.6. Class VIII: "Close-proximity rear-view device", giving the field of vision defined in paragraph 15.2.4.3.

2.5. "Point light source detection factor - PLSDF" means the level of distinctness of a pair of point light sources, based on luminance intensities and horizontal and vertical dimension of the rendition on the monitor.

2.6. "Point light source contrast factor - PLSCF" means the level of distinctness of a pair of point light sources, based on luminance differences between the maximum luminance of the luminance profile $L_{H,\text{max}}$ and the minimum luminance of the luminance profile $L_{H,\text{min}}$ in the horizontal direction (see Figure 3 of Annex 12).

3. Application for approval

3.1. The application for approval of a type of device for indirect vision shall be submitted by the holder of the trade name or mark or by his duly accredited representative.

3.2. A model of information document is shown in Annex 1.

3.3. For each type of device for indirect vision the application shall be accompanied by three samples of the parts.

3.4. The CMS shall be provided by the applicant with the following documents:

(a) Technical specification of the CMS; and

(b) Operator's manual.

4. Markings

4.1. The samples of devices for indirect vision submitted for approval shall bear the trade name or mark of the manufacturer; this marking shall be clearly legible and be indelible.

4.2. Every device for indirect vision shall possess, on at least one of the main components a space large enough to accommodate the approval mark, which shall be legible; this space shall be shown on the drawings referred to in Annex 1. The approval mark shall also be legible when the device is mounted on the vehicle with exception of camera-monitor devices as defined in paragraph 2.1.2. or detection system that provides audible and optical information as defined in paragraph 2.1.14. Other components of the device shall bear a means of identification. In the case of limited space for the approval mark(s), other means of identification that link it to the approval mark shall be provided.
5. Approval

5.1. If the samples submitted for approval meet the requirements of paragraph 6 of this Regulation, approval of the pertinent type of device for indirect vision shall be granted.

5.2. An approval number shall be assigned to each type approved. Its first two digits (at present 00) shall indicate the series of amendments incorporating the most recent major technical amendments made to the Regulation at the time of issue of the approval. The same Contracting Party shall not assign the same number to another type of device for indirect vision.

5.3. Notice of approval or of refusal or of extension or withdrawal of approval or of production definitively discontinued of a type of device for indirect vision pursuant to this Regulation shall be communicated to the Parties to the Agreement which apply this Regulation by means of a form conforming to the model in Annex 3 to this Regulation.

5.4. There shall be affixed, on at least one of the main components, conspicuously and in the space referred to in paragraph 4.2. above, to every device for indirect vision, conforming to a type approved under this Regulation, in addition to the mark prescribed in paragraph 4.1. above, an international approval mark consisting of:

5.4.1. A circle surrounding the letter "E" followed by the distinguishing number of the country which has granted approval;¹

5.4.2. An approval number;

5.4.3. Additional symbol VIII, specifying the class to which the type of device for indirect vision belongs. The additional symbol shall be placed in any convenient position in the vicinity of the circle containing the letter "E".

5.5. The approval mark and the additional symbol(s) shall be clearly legible and be indelible.

5.6. Annex 5 to this Regulation gives an example of the arrangement of the aforesaid approval mark and additional symbol.

6. Requirements

6.1. Mirrors

6.1.1. General specifications

6.1.1.1. All mirrors shall be adjustable.

6.1.1.2. Mirrors installed outside the vehicles shall comply with sub-paragraph (a) above and mirrors installed inside the vehicle shall comply with sub paragraph (b).

(a) Outside rear-view mirrors

The edge of the reflecting surface shall be enclosed in a protective housing (holder, etc.) which, on its perimeter, shall have a value "c"
greater than or equal to 2.5 mm at all points and in all directions. If the reflecting surface projects beyond the protective housing, the radius of curvature "c" on the edge of the projecting part shall be not less than 2.5 mm and the reflecting surface shall return into the protective housing under a force of 50 N applied to the point of greatest projection, relative to the protective housing, in a horizontal direction, approximately parallel to the longitudinal median plane of the vehicle.

(b) Inside rear-view mirrors

In cases, where the edge of the reflecting surface is enclosed in a protective housing (holder, etc.), the radius of curvature "c" on its perimeter shall be not less than 2.5 mm at all points and in all directions. In cases, where the edge of the reflecting surface projects beyond the protective housing, this requirement shall apply to the edge of the projecting part.

6.1.1.3. When the mirror is mounted on a plane surface, all parts, irrespective of the adjustment position of the device, including those parts remaining attached to the support after the test provided for in paragraph 6.3.2. below, which are in potential, static contact with a sphere either:

(a) for a mirror installed inside the vehicle: 165 mm in diameter; or

(b) for a mirror installed outside the vehicle, 100 mm in diameter;

shall have a radius of curvature 'c' of not less than 2.5 mm.

6.1.1.4. The requirements in paragraphs 6.1.1.2. and 6.1.1.3. above shall not apply to parts of the external surface which protrude less than 5 mm, but the outward facing angles of such parts shall be blunted, save where such parts protrude less than 1.5 mm. For determining the dimension of the projection, the following method shall apply:

6.1.1.4.1. The dimension of the projection of a component which is mounted on a convex surface may be determined either directly or by reference to a drawing of an appropriate section of this component in its installed condition.

6.1.1.4.2. If the dimension of the projection of a component which is mounted on a surface other than convex cannot be determined by simple measurement, it shall be determined by the maximum variation of the distance of the centre of a 100 mm diameter sphere from the nominal line of the panel when the sphere is moved over and is in constant contact with that component. Figure 1 shows an example of the use of this procedure.
6.1.5. Edges of fixing holes or recesses of which the diameter or longest diagonal is less than 12 mm are exempt from the radius requirements of paragraph 6.1.1.3. above provided that they are blunted.

6.1.6. The device for the attachment of mirrors to the vehicle shall be so designed that a cylinder with a 70 mm radius (50 mm in the case of an L-category vehicle), having as its axis the axis, or one of the axes, of pivot or rotation which ensures deflection of the mirror in the direction of impact concerned, passes through at least part of the surface to which the device is attached.

6.1.7. The parts of Class VIII mirrors installed outside the vehicle referred to in paragraphs 6.1.1.2. and 6.1.1.3. above which are made of a material with a Shore A hardness not exceeding 60 are exempt from the relevant provisions.

6.1.8. The parts of Class VIII mirrors installed inside the vehicle which are made of a material with a Shore A hardness of less than 50 and which are mounted on a rigid support, the requirements of paragraphs 6.1.1.2. and 6.1.1.3. above shall only apply to the support.

6.1.2. Special specifications

6.1.2.1. Dimensions

6.1.2.1.1. Close-proximity rear” view mirrors (Class VIII)

The contours of the reflecting surface shall be of simple geometric form and its dimensions such that the mirror provides the field of vision specified in paragraph 15.2.4.3. of this Regulation.

6.1.2.2. Reflecting surface and coefficients of reflection

6.1.2.2.1. The reflecting surface of a mirror shall be either flat or spherically convex. Exterior mirrors may be equipped with an additional aspherical part provided that the main mirror fulfils the requirements of the indirect field of vision.

6.1.2.2.2. Differences between the radii of curvature of mirrors

6.1.2.2.2.1. The difference between $r_1$ or $r'_1$, and $r_p$ at each reference point shall not exceed 0.15 $r$.

6.1.2.2.2.2. The difference between any of the radii of curvature ($r_{p1}$, $r_{p2}$, and $r_{p3}$) and $r$ shall not exceed 0.15 $r$.

6.1.2.2.2.3. When $r$ is not less than 3,000 mm, the value of 0.15 $r$ quoted in paragraphs 6.1.2.2.2.1. and 6.1.2.2.2.2. above is replaced by 0.25 $r$. 
6.1.2.2.3. Requirements for aspherical parts of mirrors

6.1.2.2.3.1. Aspherical mirrors shall be of sufficient size and shape to provide useful information to the driver. This normally means a minimum width of 30 mm at some point.

6.1.2.2.3.2. The radius of curvature \( r_i \) of the aspherical part shall not be less than 150 mm.

6.1.2.2.3.4. The value of the normal coefficient of reflection, as determined according to the method described in Annex 6, shall be not less than 40 per cent.

In the case of reflecting surfaces with a changeable degree of reflection, the "day" position shall allow the colours of the signals used for road traffic to be recognized. The value of the normal coefficient of reflection in the "night" position shall be not less than 4 per cent.

6.1.2.2.5. The reflecting surface shall retain the characteristics laid down in paragraph 6.1.2.2.4. above in spite of prolonged exposure to adverse weather conditions in normal use.

6.2. Devices for indirect vision other than mirrors

6.2.1. General requirements

6.2.1.1. If adjustment by the user is needed, the device for indirect vision shall be adjustable without the use of tools.

6.2.1.2. Scanning process to be amended.

FMVSS started wake-up from door open until 2 seconds to be considered.

6.2.1.3. The effectiveness of the CMS and other vision supporting devices of Class VIII shall not be adversely affected by magnetic or electrical fields. This shall be demonstrated by compliance with the technical requirements and transitional provisions of Regulation No. 10, 05 series of amendments or any later series of amendments.

6.2.2. Camera-monitor systems

The requirements of paragraph 6.2.2.1. shall be considered to be satisfied in the case of monitors of a vehicle that fulfills the provisions of Regulation No. 21.

6.2.2.1. General requirements

6.2.2.1.1. When the devices of the camera-monitor system are mounted in the position recommended by the manufacturer for normal driving, all parts, irrespective of the adjustment position of the device which are in potential, static contact with a sphere either 165 mm in diameter in the case of a CMS or parts of CMS installed inside the vehicle or 100 mm in diameter in the case of a CMS or parts of CMS installed outside the vehicle, shall have a radius of curvature "c" of not less than 2.5 mm.

6.2.2.1.2. Edges of fixing holes or recesses of which the diameter or longest diagonal is less than 12 mm are exempt from the radius requirements of paragraph 6.2.2.1.1. above provided that they are blunted.
6.2.2.1.3. For parts of the camera and the monitor which are made of a material with a Shore A hardness of less than 60 and which are mounted on a rigid support, the requirements of paragraph 6.2.2.1.1. above shall only apply to the support.

6.2.2.2. Functional requirements for camera-monitor devices of Class VIII

6.2.2.2.1. The camera shall function well in conditions in which sunlight falls on the camera. The saturated area, defined as the area in which the luminance contrast ratio \( \text{C}=\frac{L_w}{L_b} \) of a high contrast pattern falls below 2.0, shall not cover more than 15 per cent of the displayed image under the conditions of paragraphs 6.2.2.2.1.1. to 6.2.2.2.1.4. below.

In the case the camera system shows dynamical changes in the blooming area during the test the maximum blooming area shall fulfill the requirements.

6.2.2.2.1.1. A black and white test pattern, having a minimum contrast ratio of 20 shall be positioned in front of the camera.

The test pattern shall be evenly illuminated at an illumination of 3,000 ± 300 lx.

The test pattern shall be medium gray on average and cover the complete area viewed by the camera; the camera shall view no other objects than the test pattern.

6.2.2.2.1.2. The camera shall be hit by a (simulated sun) light of 40 klx, spanning an angle between 0.6 and 0.9° with an elevation angle of 10° (directly or indirectly via a mirror) removed from the optical axis of the sensor.

The light source shall:

(a) Have a spectrum D65 with a tolerance of ±1,500 K;
(b) Be homogeneous in space and time within a tolerance of 2 klx.

The emission of the light source in infrared shall be negligible.

6.2.2.2.1.3. There shall be no ambient illumination of the monitor during the test.

6.2.2.2.1.4. An example of the set-up is given in the Figure A below.
Figure A

Diagram of the blooming measurement set-up

1: Black and white test pattern.
2: Lamps to make the test pattern evenly illuminated.
3: Mirror.
4: High intensity light.
5: Camera.
6: Monitor.

6.2.2.2. The monitor shall render a minimum contrast under various light conditions as specified by ISO 15008:2003.

6.2.2.3. It shall be possible to adjust the average luminance of the monitor either manually or automatically to the ambient conditions.

6.2.2.4. The measurements for the luminance contrast of the monitor shall be carried out according to ISO 15008:2009.

6.2.2.3. Functional requirements for camera-monitor devices of Classes I to IV (see Annex 12).

Updated from draft (To be removed, this paragraph is based on Class I to IV)

Unless otherwise specified in this Regulation, the definitions and symbols used in paragraph 6.2.2.3. are in accordance with ISO 16505:2015, Chapters 3 and 4.

Unless otherwise specified in this Regulation, the requirements given in paragraph 6.2.2.3. shall be verified according to the test procedures given in ISO 16505:2015, Chapter 7, where available.

6.2.2.3.1. Luminance adjustment

It shall be possible to adjust the average luminance of the monitor either manually or automatically to the ambient conditions.

6.2.2.3.2. Operating readiness (System availability)

If the system is not operational (e.g. CMS failure), it shall be indicated to the driver by i.e. warning indication, display information, absence of status indicator. The operator's manual shall explain the information indicated.
6.2.2.3.3. Image quality

6.2.2.3.3.1. Monitor isotropy

The monitor shall conform to optical requirements over the range of viewing directions that is specified in the following paragraphs.

6.2.2.3.3.1.1. Directional uniformity

When driven by an artificial 70 per cent grey-scale image, the deviation of the monitor luminance from the luminance white level with specific viewing direction \((\Theta, \phi) = (\Theta_{\text{monitor}}, \phi_{\text{monitor}})\) shall be such that the ratio relative to the luminance white level for the same specific viewing direction \(L(\Theta_{\text{monitor}}, \phi_{\text{monitor}})\) does not exceed 35 per cent of the luminance white level for the monitor standard isotropy range and shall not exceed 50 per cent of the luminance white level for the monitor extended isotropy range.

For the standard isotropy range:

\[
\frac{\max \left[ L_i - L(\Theta_{\text{monitor}}, \phi_{\text{monitor}}) \right]}{L(\Theta_{\text{monitor}}, \phi_{\text{monitor}})} < 35\%
\]

for points \(i = 1, 2, 3, 4, 5, 6, 7, 8, 9\) as defined in Table 1 below.

Table 1
Measurement directions for standard isotropy range

<table>
<thead>
<tr>
<th>Direction (i)</th>
<th>horizontal/degree</th>
<th>vertical/degree</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-7</td>
<td>+6</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>+6</td>
</tr>
<tr>
<td>3</td>
<td>+7</td>
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</tr>
<tr>
<td>4</td>
<td>-7</td>
<td>0</td>
</tr>
<tr>
<td>5</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>6</td>
<td>+7</td>
<td>0</td>
</tr>
<tr>
<td>7</td>
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<td>-6</td>
</tr>
<tr>
<td>9</td>
<td>+7</td>
<td>-6</td>
</tr>
</tbody>
</table>

For the extended isotropy range:

\[
\frac{\max \left[ L_i - L(\Theta_{\text{monitor}}, \phi_{\text{monitor}}) \right]}{L(\Theta_{\text{monitor}}, \phi_{\text{monitor}})} < 50\%
\]

for points \(i' = 1, 2, 3, 4, 5, 6, 7, 8, 9\) as defined in Table 2 below.
Table 2
Measurement directions for extended isotropy range

<table>
<thead>
<tr>
<th>Direction i'</th>
<th>horizontal/ degree</th>
<th>vertical/ degree</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-12</td>
<td>+11</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>+11</td>
</tr>
<tr>
<td>3</td>
<td>+12</td>
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<td>8</td>
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<td>-11</td>
</tr>
<tr>
<td>9</td>
<td>+12</td>
<td>-11</td>
</tr>
</tbody>
</table>

6.2.2.3.3.1.2. Lateral uniformity

The luminance white lateral dependency shall satisfy:

$$\frac{\max \left( L_{j/w}\left(\Theta, \Phi\right) \right) - \min \left( L_{j/w}\left(\Theta, \Phi\right) \right)}{\max \left( L_{j/w}\left(\Theta, \Phi\right) \right)} < 35\%.$$ 

for points \( j = 1, 2, 3, 4, 5, 6, 7, 8, 9 \) as defined in Table 3 below, where \((\Theta, \Phi) = (0, 0)\).

Table 3
Measurement points for the lateral uniformity

<table>
<thead>
<tr>
<th>Point j</th>
<th>Percentage of ( W_{\text{max}} )/horizontal from top left corner</th>
<th>Percentage of ( H_{\text{max}} )/horizontal from top left corner</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>20</td>
<td>20</td>
</tr>
<tr>
<td>2</td>
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</tr>
<tr>
<td>3</td>
<td>80</td>
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<tr>
<td>9</td>
<td>80</td>
<td>80</td>
</tr>
</tbody>
</table>

6.2.2.3.3.2. Luminance and contrast rendering

For luminance and contrast rendering the following requirements shall apply:

(a) The minimum luminance contrast at the monitor (including any screen protector) reproducing a high contrast pattern shall be:

(i) For direct sunlight condition: 2:1;

(ii) For day condition with diffuse ambient light: 3:1;

(iii) For sunset condition: 2:1;

(iv) For night condition: 10:1 except in the case of Mirror and CMS dual function system of class I: 5:1.
(b) The night condition for the camera's field of view is replicated in a dark environment such that the maximum illuminance on the objects to be measured shall not exceed 2.0 lx;

(c) The background luminance of the monitor shall be limited under the night condition. The maximum background luminance under the night condition shall be less than 2.0 cd/m²;

(d) The instructions for use shall contain a note that sunlight or light from other intense light source upon the monitor reduces the luminance contrast which may require the driver to be particularly alert and attentive.

6.2.2.3.2.1. Day condition with diffuse sky-light exposure test

For the day condition with diffuse sky-light exposure, the test method given in ISO 16505:2015, subclause 7.8.2., Test 2 shall be applied, but a value of 4,000 to 4,200 cd/m² for luminance diffuse illuminator shall be used.

At the request of the manufacturer, the value for luminance diffuse illuminator may be determined by using the diagram of figure below.

![Diagram of Luminance vs. Ratio of Projected Area]

Ratio of projected area vs. luminance of the diffuse illuminator

Procedure for determining the ration of the projected area leaving the vehicle:

(a) Determine the projected area in the vehicle that represents the mirror reflected direction from the monitor extended isotropy range.

(b) Evaluation shall be made in the centre of the monitor defined size, under consideration of the monitor design viewing direction (see figure below).
This projected area represents the 100 per cent of the surface to be considered.

Based on virtual testing, evaluate the ratio of the projected area that leaves the vehicle openings (e.g. through a side door window, rear window or sunroof; however, for example a sunroof having an opaque shutter shall not be considered an opening).

6.2.2.3.3. Grey scale rendering

A CMS shall have a sufficient grey scale rendering. CMS shall display a tonal range of at least eight distinguishable different grey tonal steps on the monitor.

For the grey scale rendering, the test method of paragraph 1.4. of Annex 12 shall be applied.

6.2.2.3.4. Colour rendering

For colour rendering, the hue angle of reproduced colour of the chart patches on the monitor shall satisfy the following requirements. The colour coordinates are described based in the CIE 1976 uniform colour space:

(a) Red colour coordinates shall not exceed the range of (0°, 44.8°) or (332.2°, 360°);
(b) Green colour coordinates shall not exceed the range of (96.6°, 179.9°);
(c) Blue colour coordinates shall not exceed the range of (209.9°, 302.2°);
(d) Yellow colour coordinates shall not exceed the range of (44.8°, 96.6°);
(e) To distinguish from the white colour, define distance from white as $R_i \geq 0.02$, where $R_i$ is the chromatic distance of each colour patch (i = Red, Green, Blue, Yellow), relative to white (i = White).
Figure B shows an illustrative tolerance range described on CIE 1976 uniform colour space.

Figure B

Amber, blue and red light signals shall be distinguishable from each other.

6.2.2.3.5. Artefacts

The operator's manual shall refer to possible artefacts and their impact on the partial occlusion of the field of view and of the objects which may require the driver to be particularly alert and attentive.

6.2.2.3.5.1. Smear

Smear shall be transparent and not be more than 10 per cent of the maximum luminance value of the displayed glare source luminance level, which causes smear effect.

6.2.2.3.5.2. Blooming and lens flare

The total area of disturbing blooming and lens flare areas shall not cover more than 25 per cent of the displayed camera image.

6.2.2.3.5.3. Point light sources

The CMS shall have an operation mode in which the driver of the vehicle equipped with CMS can recognize two point light sources (e.g. passing beam headlights) rendered as two distinguishable separate point light sources.

In this operation mode, a set of two point light sources corresponding to a vehicle passing beam headlamp each having a reference luminous intensity $1,750 \text{ cd}$ and being separated each other laterally by $1.3 \text{ m}$ and located at a distance of $250 \text{ m}$ away from the CMS shall be distinguishable as two point light source. This requirement is applicable to Class I, Class II and Class III devices for indirect vision.
The point light source detection factor (PLSDF) shall be at least 2.7 or the point light source contrast factor (PLSCF) shall be at least 0.12, whichever is satisfied by the CMS test under the conditions and the test procedure described in Annex 12, paragraph 1.3.

If the system is in a mode where point light sources are not rendered as described above, this shall be indicated to the driver. The information indicated shall be explained in the operator’s manual.

6.2.2.3.6. Sharpness and depth of field

6.2.2.3.6.1. Sharpness

The sharpness is represented by the MTF50_{1:1} and it shall satisfy:

(a) Horizontal and vertical MTF50_{1:1} at center

\[ MTF50_{(11)} \geq \frac{1}{2} \frac{MTF10_{MIN(11)}}{\langle LW/PH \rangle} \]

\[ -0.34 \leq \frac{M_{system/hor/avg}}{M_{system/ver/avg}} \leq \]

(b) Horizontal and vertical MTF50_{1:1} at corners (70 per cent of image height)

\[ MTF50_{(11)} \geq \frac{1}{2} \frac{1}{2} \left( MTF10_{MIN(11)} \right) \langle LW/PH \rangle \]

6.2.2.3.6.2. Depth of field

The CMS shall enable the driver to observe the occupied space by the object and perceive the content shown within the range of interest with detailed resolution. The MTF10_{1:1}, when measured at different distances to the object, shall satisfy at least the minimum resolution for the following points:

(a) Resolution at point 1 (10 m as representative point for infinity) and point 2 (middle distance at 6 m)

\[ MTF10_{(11)} \geq 0.9 \cdot MTF10_{MIN(11)} \langle LW/PH \rangle \]

\[ -0.34 \leq \]

\[ \frac{M_{system/hor/avg}}{M_{system/ver/avg}} \leq \]

(b) Resolution at point 3 (Close distance at 4 meters)

\[ MTF10_{(11)} \geq \frac{1}{2} \frac{1}{2} \left( MTF10_{MIN(11)} \right) \langle LW/PH \rangle \]

6.2.2.3.7. Further image quality requirements

6.2.2.3.7.1. Flicker

The entire image area of the monitor shall be free of flicker according to the test method of Annex 12, paragraph 1.2.

6.2.2.3.4. Time behaviour
6.2.2.3.4.1. Frame rate

Movements of objects in front of the camera shall be rendered smooth and fluid. The minimum frame rate of the system (update rate of the image information) shall be at least 30 Hz. At low light conditions or while maneuvering at low speed, the minimum frame rate of the system (i.e. update rate of the image information) shall be at least 15 Hz.

6.2.2.3.4.2. Image formation time

The image formation time of the monitor shall be less than 55 ms at a temperature of 22 °C ± 5 °C.

This performance shall be tested according to the method given in ISO 9241-305:2008.

6.2.2.3.4.3. System latency

A CMS shall have a sufficient short latency to render the scenery nearly at the same time. The latency shall be lower than 200 ms at room temperature 22 °C ± 5 °C.

6.2.2.3.5. Quality and further ergonomic requirements

6.2.2.3.5.1. Glare due to high luminance of the monitor

In order to avoid glare from a high luminance of the monitor, the luminance shall be dimmable in the night condition either manually or automatically.

6.2.3. Other devices for indirect vision

It has to be proved that the device meets the following requirements:

6.2.3.1. The device shall perceive the visual spectrum and shall always render this image without the need for interpretation into the visual spectrum.

6.2.3.2. The functionality shall be guaranteed under the circumstances of use in which the system shall be put into service. Depending on the technology used in obtaining images and presenting them paragraph 6.2.2.2. above shall be entirely or partly applicable. In other cases this can be achieved by establishing and demonstrating by means of system sensitivity analogous to paragraph 6.2.2.2. above that a function is ensured that is comparable to or better than what is required for and by demonstrating that a functionality is guaranteed that is equivalent or better than that required for mirror- or camera-monitor type devices for indirect vision.

6.3. Test

The requirements of paragraph 6.3. shall be considered to be satisfied in the case of monitors of a vehicle fulfilling the provisions of Regulation No. 21.

6.3.1. Devices for indirect vision in Class VIII mirrors shall be subjected to the tests described in paragraphs 6.3.2.1. and 6.3.2.2. below.

6.3.1.1. The test provided for in paragraph 6.3.2. below shall not be required in the case of Class VIII exterior device for indirect vision of which no part is less than 2 m from the ground, regardless of the adjustment position, when the vehicle is under a load corresponding to its maximum technically permissible mass.
This derogation also applies to the attachments of devices for indirect vision (attachment plates, arms, swivel joints, etc.) which are situated less than 2 m from the ground and which do not project beyond the overall width of the vehicle, measured in the transverse plane passing through the lowest mirror attachments or any other point forward of this plane if this configuration produces a greater overall width.

In such cases, a description specifying that the device for indirect vision shall be mounted so as to conform to the above-mentioned conditions for the positioning of its attachments on the vehicle shall be provided.

Where advantage is taken of this derogation, the arm shall be indelibly marked with the symbol

\[ \Delta \]

and the type approval certificate shall be endorsed to this effect.

6.3.2. Impact test

The test according to this paragraph is not to be carried out for devices integrated in the bodywork of the vehicle and providing a frontal deflecting area of an angle not more than 45° measured in relation to the longitudinal median plane of the vehicle, or devices not protruding more than 100 mm measured beyond the circumscribing bodywork of the vehicle according to Regulation No. 26, 03 series of amendments.

6.3.2.1. Description of the test rig

6.3.2.1.1. The test rig consists of a pendulum capable of swinging about two horizontal axes at right angles to each other, one of which is perpendicular to the plane containing the "release" trajectory of the pendulum.

The end of the pendulum comprises a hammer formed by a rigid sphere with a diameter of 165 ± 1 mm having a 5 mm thick rubber covering of Shore A hardness 50.

A device is provided which permits determination of the maximum angle assumed by the arm in the plane of release.

A support firmly fixed to the structure of the pendulum serves to hold the specimens in compliance with the impact requirements specified in paragraph 6.1.3.2.2.6. below.

Figure 2 below gives the dimensions (in mm) of the test rig and the special design specifications:
6.3.2.1.2. The centre of percussion of the pendulum coincides with the centre of the sphere, which forms the hammer. It is at a distance $l$ from the axis of oscillation in the release plane, which is equal to $1 \text{m} \pm 5 \text{mm}$. The reduced mass of the pendulum is $m_\circ = 6.8 \pm 0.05 \text{kg}$. The relationship of $m_\circ$ to the total mass $m$ of the pendulum and to the distance $d$ between the centre of gravity of the pendulum and its axis of rotation is expressed in the equation:

$$m_\circ = m \times \frac{d}{l}$$

6.3.2.2. Description of the test

6.3.2.2.1. The procedure used to clamp the device for indirect vision to the support shall be that recommended by the manufacturer of the device or, where appropriate, by the vehicle manufacturer.

6.3.2.2.2. Positioning of the device for indirect vision for the test

6.3.2.2.1. Devices for indirect vision shall be positioned on the pendulum impact rig in such a way that the axes which are horizontal and vertical when the mirror is installed on a vehicle in accordance with the applicant's mounting instructions are in a similar position;

6.3.2.2.2. When a device for indirect vision is adjustable with respect to the base, the test position shall be that in which any pivoting device is least likely to operate, within the limits of adjustment provided by the applicant;

6.3.2.2.3. When the device for indirect vision has a device for adjusting its distance from the base, the device shall be set in the position in which the distance between the housing and the base is shortest;
6.3.2.2.4. In the case of mirrors, when the reflecting surface is mobile in the housing, it shall be so adjusted that the upper corner, which is furthest from the vehicle, is in the position of greatest projection relative to the housing.

6.3.2.2.3. In the case of mirrors, when the pendulum is in a vertical position the horizontal and longitudinal vertical planes passing through the centre of the hammer shall pass through the centre of the reflecting surface as defined in paragraph 2.1.1.10. of this Regulation. The longitudinal direction of oscillation of the pendulum shall be parallel to the longitudinal median plane of the vehicle.

6.3.2.2.4. In the case of camera-monitor systems, when the pendulum is in a vertical position the horizontal and longitudinal vertical planes passing through the centre of the hammer shall pass through the centre of the lens or of the transparent protection part protecting the lens. The longitudinal direction of oscillation of the pendulum shall be parallel to the longitudinal median plane of the vehicle. If the test is performed with a shutter camera system, the shutter has to be open during the pendulum impact.

6.3.2.2.5. When, under the conditions governing adjustment laid down in paragraphs 6.3.2.2.1. and 6.3.2.2.2. above parts of the device for indirect vision limit the return of the hammer, the point of impact shall be displaced in a direction perpendicular to the axis of rotation or pivoting in question. The displacement shall be no greater than is strictly necessary for the execution of the test; it shall be limited in such a way that:

(a) Either the sphere delimiting the hammer remains at least tangential to the cylinder as defined in paragraph 6.1.1.6.;
(b) Or, in the case of mirrors, the point of contact with the hammer is located at least 10 mm from the periphery of the reflecting surface.

6.3.2.2.6. The test consists in allowing the hammer to fall from a height corresponding to a pendulum angle of 60° from the vertical so that the hammer strikes the device for indirect vision at the moment when the pendulum reaches the vertical position.

6.3.2.2.7. The devices for indirect vision are subjected to impact under the following different conditions:

6.3.2.2.7.1. Classes VIII mirrors

(a) Test 1: The point of impact shall be as defined in paragraphs 6.3.2.2.3. or 6.3.2.2.5. above. The impact shall be such that the hammer strikes the mirror on the reflecting surface side.

(b) Test 2: The point of impact shall be as defined in paragraphs 6.3.2.2.3. or 6.3.2.2.5. above. The impact shall be such that the hammer strikes the mirror on the side opposite to the reflecting surface.

6.3.2.2.7.2. Camera-Monitor Systems

(a) Test 1: The point of impact shall be as defined in paragraphs 6.3.2.2.4. or 6.3.2.2.5. The impact shall be such that the hammer strikes the camera on the lens side.
(b) Test 2: The point of impact shall be as defined in paragraphs 6.3.2.2.4. or 6.3.2.2.5. The impact shall be such that the hammer strikes the camera on the side opposite to the lens.

Where more than one camera is fixed to the same mounting, the above-mentioned tests shall be executed on the lower camera. Nevertheless, the Technical Service responsible for testing may repeat one or both of these tests on the upper camera if this is less than 2 m from the ground.

6.3.3. Results of the tests

6.3.3.1. In the tests described in paragraph 6.3.2. above, the pendulum shall continue to swing after impact in such a way that the projection of the position assumed by the arm on the plane of release makes an angle of at least 20° with the vertical. The accuracy of measurement of the angle shall be within ±1°.

6.3.3.1.1. In the case of mirrors, this requirement is not applicable to mirrors stuck to the windscreen, in respect of which the requirement stipulated in paragraph 6.3.3.2. shall apply after the test.

6.3.3.2. In the case of mirrors, should the mounting of the mirror break during the tests described in paragraph 6.3.2. above for mirrors stuck to the windscreen, the part remaining shall not project beyond the base by more than 10 mm and the configuration remaining after the test shall satisfy the conditions laid down in paragraph 6.1.3. of this Regulation.

6.3.3.3. The reflecting surface shall not break during the tests described in paragraph 6.3.2. However, breakage of the reflecting surface will be allowed if one of the following conditions is fulfilled.

6.3.3.3.1. The fragments of glass still adhere to the back of the housing or to a surface firmly attached to the housing; partial separation of the glass from its backing is admissible provided that this does not exceed 2.5 mm on either side of the cracks. It is permissible for small splinters to become detached from the surface of the glass at the point of impact;

6.3.3.3.2. The reflecting surface is made of safety glass.

6.3.3.4. In the case of camera-monitor systems, the lens shall not break during the tests described in paragraph 6.3.2. above.

7. Modification of the type of device for indirect vision and extension of approval

7.1. Every modification to an existing type of device for indirect vision including its connection to the bodywork shall be notified to the Type Approval Authority which approved the type of device for indirect vision. The Type Approval Authority shall then either:

(a) Decide, in consultation with the manufacturer, that a new type-approval is to be granted; or

(b) Apply the procedure contained in paragraph 7.1.1. (Revision) and, if applicable, the procedure contained in paragraph 7.1.2. (Extension).

7.1.1. Revision
When particulars recorded in the information folder have changed and the Type Approval Authority considers that the modifications made are unlikely to have an appreciable adverse effect and that in any case the device for indirect vision still complies with the requirements, the modification shall be designated a "revision".

In such a case, the Type Approval Authority shall issue the revised pages of the information folder as necessary, marking each revised page to show clearly the nature of the modification and the date of re-issue. A consolidated, updated version of the information folder, accompanied by a detailed description of the modification, shall be deemed to meet this requirement.

7.1.2. Extension

The modification shall be designated an "extension" if, in addition to the change of the particulars recorded in the information folder;

(a) Further inspections or tests are required; or

(b) Any information on the communication document (with the exception of its attachments) has changed; or

(c) Approval to a later series of amendments is requested after its entry into force.

7.2. Confirmation or refusal of approval, specifying the alterations shall be communicated by the procedure specified in paragraph 5.3. above to the Parties to the Agreement which apply this Regulation. In addition, the index to the information package, attached to the communication document, shall be amended accordingly to show the date of the most recent revision or extension.

7.3. The Type Approval Authority issuing the extension of approval shall assign a series number to each communication form drawn up for such an extension.

8. Conformity of production

8.1. The conformity of production procedure shall comply with those set out in the Agreement, Appendix 2 (E/ECE/324-E/ECE/TRANS/505/Rev.2).

8.2. Every device for indirect vision approved under this Regulation shall be so manufactured as to conform to the type approved by meeting the requirements set out in paragraph 6. above.

9. Penalties for non-conformity of production

9.1. The approval granted in respect of a type of device for indirect vision pursuant to this Regulation may be withdrawn if the requirement laid down in paragraph 8.1. above is not complied with or if the type of device for indirect vision did not satisfy the requirements prescribed in paragraph 8.2. above.

9.2. If a Contracting Party to the Agreement which applies this Regulation withdraws an approval it has previously granted, it shall forthwith so notify the other Contracting Parties applying this Regulation by means of a copy of the communication form bearing at the end, in large letters, the signed and dated annotation "APPROVAL WITHDRAWN".
10. Production definitively discontinued

If the holder of the approval completely ceases to manufacture a type of device for indirect vision approved in accordance with this Regulation, he shall so inform the Type Approval Authority which granted the approval. Upon receiving the relevant communication, the Authority shall inform thereof the other Parties to the Agreement applying this Regulation by means of a copy of the approval form bearing at the end, in large letters, the signed and dated annotation "PRODUCTION DISCONTINUED".

11. Names and addresses of Technical Services responsible for conducting approval tests, and of Type Approval Authorities

The Contracting Parties to the Agreement applying this Regulation shall communicate to the United Nations Secretariat the names and addresses of the Technical Services responsible for conducting approval tests and of the Type Approval Authorities which grant approval and to which forms certifying approval or refusal or extension or withdrawal of approval, issued in other countries, are to be sent.

II. Installation of devices for indirect vision

12. Definitions

For the purpose of this Regulation:

12.1. "The driver's ocular points" means two points 65 mm apart and 635 mm vertically above point R of the driver's seat as defined in Annex 8. The straight line joining these points runs perpendicular to the vertical longitudinal median plane of the vehicle. The centre of the segment joining the two ocular points is in a vertical longitudinal plane which shall pass through the centre of the driver's designated seating position, as specified by the vehicle manufacturer.

12.2. "Ambinocular vision" means the total field of vision obtained by the superimposition of the monocular fields of the right eye and the left eye (see Figure 3 below).
"Type of vehicle as regards indirect vision" means motor vehicles which are identical in respect of the following basic features:

12.3.1. Type of device for indirect vision;

12.3.2. The bodywork features which reduce the field of vision;

12.3.3. The coordinates of point R (where applicable);

12.3.4. The prescribed positions, and type-approval markings of compulsory and (if fitted) optional devices for indirect vision.

12.4. "Vehicles of categories L₂, L₅, M₁, M₂, M₃, N₁, N₂ and N₃" means those defined in the Consolidated Resolution on the Construction of Vehicles (R.E.3), (document ECE/TRANS/WP.29/78/Rev.4, para. 2).

12.5. "Forward control" means a configuration in which more than half of the engine length is rearward of the foremost point of the windshield base and the steering wheel hub in the forward quarter of the vehicle length.

12.6. "Ocular reference point" means the middle point between the driver's ocular points.

12.7 Backing event means an amount of time which starts when the vehicle's direction selector is placed in reverse, and ends at the manufacturer's choosing, when the vehicle forward motion reaches:

(a) a speed of 16 km/h,

(b) a distance of 10 meters traveled, or

(c) a continuous duration of 10 seconds.

13. Application for approval

13.1. The application for approval of a vehicle type with regard to the installation of devices for indirect vision shall be submitted by the vehicle manufacturer or by his duly accredited representative.

13.3. A vehicle representative of the vehicle type to be approved shall be submitted to the Technical Service responsible for conducting the approval tests.

13.4. The Type Approval Authority shall verify the existence of satisfactory arrangements for ensuring effective checks on conformity of production before type-approval is granted.

13.5. The CMS shall be provided by the applicant with the following documents:

(a) Technical specification of the CMS;
(b) Operator's manual;
(c) Documentation referred to in Annex 12, paragraph 2.3.

14. Approval

14.1. If the vehicle type submitted for approval in accordance with paragraph 13. above meets the requirements of paragraph 15. of this Regulation, approval shall be granted.

14.2. An approval number shall be assigned to each type approved. Its first two digits (at present 00) shall indicate the series of amendments incorporating the most recent or technical amendments made to the Regulation at the time of issue of the approval. The same Contracting Party shall not assign the same number to another vehicle type.

14.3. Notice of approval or of refusal or of extension or withdrawal of approval of a vehicle type pursuant to this Regulation shall be communicated to the Parties to the Agreement which apply this Regulation by means of a form conforming to the model in Annex 4 to this Regulation.

15. Requirements

15.1. General

15.1.1. The compulsory and optional devices for indirect vision, set out in the table under paragraph 15.2.1.1.1. below, installed on the vehicle shall be of a type approved under this Regulation.

15.1.2. Devices for indirect vision shall be fitted in such a way that the devices do not move so as significantly to change the field of vision as measured or vibrate to an extent which would cause the driver to misinterpret the nature of the image perceived.

15.1.3. The conditions laid down in paragraph 15.1.2. above shall be maintained when the vehicle is moving at speeds of up to 80 per cent of its maximum design speed, but not exceeding 150 km/h.

15.1.4. The fields of vision defined below shall be established using ambinocular vision, the eyes being at the "driver's ocular points" as defined in paragraph 12.1. above. The fields of vision shall be determined when the vehicle is in running order as defined in the consolidated Resolution on the Construction of vehicles (R.E.3) (ECE/TRANS/WP.29/78/Rev.4, para. 2.2.5.4.), plus for M₁ and N₁ vehicles one front seat passenger (75 kg).
through windows, the glazing shall have a total light transmission factor in accordance with Regulation No. 43, Annex 21.

15.2. Devices for indirect vision

15.2.1. Number

15.2.1.1. Minimum number of compulsory devices for indirect vision

15.2.1.1.1. The fields of vision prescribed in paragraph 15.2.3. shall be obtained from the minimum number of mirrors or camera-monitor device.

A minimum number of camera-monitor systems is undefined, but they shall provide the same field of vision and the provision on the minimum mounting height does not apply.

In the case of camera-monitor systems, the maximum number of monitors shall not exceed the corresponding number of mirrors.

15.2.1.1.2. In the case a camera-monitor system is used for rendering (the) field(s) of vision, the relevant field(s) of vision shall be permanently visible to the driver when the ignition is on or the vehicle master control switch is activated (whichever is applicable). Multiple images may be used or displayed provided that the monitor has been approved in this mode.

Furthermore, in the case of a camera-monitor system intended for rendering the Class VIII field of vision, it shall be such that the relevant field of vision is permanently visible to the driver when the reverse gear is selected.

To be reflected discussion

15.2.1.2. The provisions of this Regulation do not apply to the surveillance mirrors defined in paragraph 2.1.1.3. of this Regulation. Nevertheless, the exterior surveillance mirrors shall be mounted at least 2 m above the ground when the vehicle is under a load corresponding to its maximum technical permissible mass.

15.2.2. Position

15.2.2.1. Devices for indirect vision shall be so placed that the driver, when sitting on the driving seat in a normal driving position, has a clear view of the road to the rear, side(s) or front of the vehicle.

15.2.2.2. Class VIII mirrors shall be visible through the windows or through the portion of the windscreen that is swept by the windscreen wiper. Nevertheless, for design reasons, this last provision (i.e. the provisions relating the cleaned part of the windscreen) shall not apply to Class VIII mirrors.

15.2.2.3. In the case of any vehicle, which is in chassis/cab form when the field of vision is measured, the minimum and maximum body widths shall be stated by the manufacturer and, if necessary, simulated by dummy headboards. All vehicles and devices for indirect vision configurations taken into consideration during the tests shall be shown on the type-approval certificate for a vehicle with regard to the installation of devices for indirect vision (see Annex 4).

15.2.2.4. Devices for indirect vision shall not project beyond the external bodywork of the vehicle substantially more than is necessary to comply with the
requirements concerning fields of vision laid down in paragraph 15.2.4. below.

15.2.3. Fields of vision

15.2.3.1. Class VIII close-proximity rear-view device

15.2.3.1.1. The field of vision shall be bounded by the following planes and shall be such that the driver can see at least part of each cylindrical objects with a height of 1,000 mm and a diameter of 300 mm which is located on the ground plane at nine positions within the boundaries of the field of vision as defined in Figure 3 below:

(a) A transverse vertical plane through the outermost point of the rear of the vehicle;
(b) A transverse vertical plane [3,500] mm behind the outermost point of the rear of the vehicle;
(c) Two longitudinal vertical planes parallel to the longitudinal vertical median plane going through the outermost point of each side of the vehicle.

15.2.3.1.2. If the field of vision defined in paragraph 15.2.3.1.1. can be perceived via a combination of devices for indirect vision of other Classes of devices for indirect vision, it is not mandatory to equip the vehicle with a Class VIII close-proximity rear-view device.

In addition, the requirement may be met using a combination of mirrors of Class VII and other Class(es) fulfilling the provisions of Regulation No. 46, 04 series of amendment or using an detection system defined in 2.1.14 of this regulation.

The vehicles that satisfied the conditions of exemption described below, the field of vision defined in paragraph 15.2.3.1.1. can be perceived directly from the driver’s looking back ocular points described in paragraph 15.2.3.1.3., it is not mandatory to equip the vehicle with a Class VIII close-proximity rear-view device.

The conditions of exemption for direct vision are:

Direct vision exemption for further discussion in IWG to be described.

If the field of vision defined in paragraph 15.2.3.1.1. can be perceived directly by the driver, the vertical position of rear seat headrests should be set at [the designed position assumed to use or the highest position if the headrest has multiple position settings or agreed position with the Technical Service].
15.2.3.1.3. "The driver's looking back ocular points" means two points located at 96 mm longitudinally rearward, 158 mm horizontally inside vehicle centre and 6 mm vertically above from "the driver's ocular points" described in paragraph 12.1.

15.2.3.1.4. Each transverse row of cylindrical objects should be perceived by one device.

15.2.4.2. In the case of mirrors consisting of several reflecting surfaces which are either of different curvature or make an angle with each other, at least one of the reflecting surfaces shall provide the field of vision and have the dimensions (paragraph 6.1.2.1.2.2. of this Regulation) specified for the class to which they belong.

15.2.4.3. Obstructions

15.2.4.3.1. Classes VIII devices for indirect vision and Class VIII mirrors

In the fields of vision specified above, obstruction due to the bodywork and its components, such as other cab devices for indirect vision, door handles, outline marker lights, direction indicators and front and rear bumpers, as well as reflective-surface cleaning components, shall not be taken into account if they are responsible for a total obstruction of less than 10 per cent of the specified field of vision. In the case of a vehicle designed and constructed for special purposes where, due to its special features, it is not possible to meet this requirement, the obstruction of the required field of vision of a Class VIII mirror caused by the special features may be more than 10 per cent but not more than necessary for its special function.

15.2.4.4. Test procedure

The field of vision shall be determined by placing powerful light sources at the ocular points and examining the light reflected on the vertical monitoring screen. Other equivalent methods may be used.
16. Requirements for devices for indirect vision other than mirrors

16.1 Class I to IV camera-monitor devices

The requirements of Class I to IV camera-monitor devices shall be considered to be satisfied in the case of devices fulfilling the provisions of Regulation No. 46.

16.1.1 Intended use, activation and deactivation

The intended use shall be mentioned within the operator's manual. The procedure for activation and deactivation of the CMS of Class VIII shall allow a safe use of the vehicle.

The CMS shall be activated when the vehicle is opened (e.g. unlocking of the doors, opening of a front door or any other means by the choice of the manufacturer).

In addition to the requirements mentioned in paragraph 15.2.1.1.2., after each engine switch-off the system shall remain operational for a period of at least $T_1 = 120$ s. After $T_1$ period and for a period of at least $T_2 = (420 - T_1)$ seconds the system shall be able to be reactivated such that the required field of vision is made available within 1 second by manoeuvring any front door opening automatically and, if available, manually by the driver. After $T_2$ period the system shall be able to be reactivated within 7 seconds (e.g. by initiating any front door opening process).

Notwithstanding the provisions above, any other concept to activate or deactivate the system shall be demonstrated to the satisfaction of the Technical Service within the safety concept that is provided according to the provisions of Regulation No. 46, 04 series of amendment.

16.1.1.1 Default view

In default view the CMS shall show the field of view at least as defined in paragraph 15.2.4., with at least the required magnification and resolution as defined in paragraph 16.1.3.

The rear view CMS system must default to the rearview image at the beginning of each backing event regardless of any modifications to the field of view the driver has previously selected.

16.1.1.2 Luminance and contrast adjustment

If manual adjustment is provided, the operator's manual shall provide information on how to change the luminance/contrast.

16.1.1.3 Overlay requirements within the minimum required field of vision

Overlays shall display only rearward driving-related visual information.

Only safety related information overlays are allowed.

Overlays for other purposes of information shall be considered as an obstruction regardless of their transparency.

Each overlay shall not exceed 2.5 per cent of the required field of view displayed surface of the corresponding class.
The total surface of all obstructions shall not exceed the provision of paragraph 15.2.4.9.1. or 15.2.4.9.2. at the same time.

Overlay and any other obstruction surface shall be determined (for example on screenshots) taking into account the worst case(s).

16.1.1.3. Deactivation

The rearview image shall remain visible during the backing event until either, the driver modifies the view, or the vehicle direction selector is removed from the reverse position.

16.1.2. Operating readiness (System availability)

Non-operation of the system shall be recognizable to the driver is (e.g. CMS failure by, i.e. warning indication, display information, absence of status indicator). The information for the driver shall be explained in the operator's manual.

16.1.3. Resolution

16.1.3.1. Resolution (MTF)

The resolution (MTF) defines the minimum distinguishable details observable in an image as is represented by the MTF10. For reasons of simplicity the requirement is defined assuming an aspect ratio of 1:1.

Resolution MTF10, at the centre of the monitor defined size shall fulfil the following requirements:

\[
MTF_{10(\text{hor})} \geq MTF_{10 \text{MIN(\text{hor})}}, \quad \text{in horizontal direction}, \quad -0.34 \leq \frac{1}{M_{\text{system/hor/avg}}} \leq \frac{1}{M_{\text{system/ver/avg}}}
\]

\[
MTF_{10(\text{ver})} \geq MTF_{10 \text{MIN(\text{ver})}}, \quad \text{in vertical direction}, \quad -0.34 \leq \frac{1}{M_{\text{system/hor/avg}}} \leq \frac{1}{M_{\text{system/ver/avg}}}
\]

Resolution MTF10, at the corner measurement points as illustrated in the figure below shall fulfil the following requirements:

\[
MTF_{10(\text{hor})} \geq \frac{1}{2} MTF_{10 \text{MIN(\text{hor})}}, \quad \text{in horizontal direction}, \quad -0.34 \leq \frac{1}{M_{\text{system/hor/avg}}} \leq \frac{1}{M_{\text{system/ver/avg}}}
\]

\[
MTF_{10(\text{ver})} \geq \frac{1}{2} MTF_{10 \text{MIN(\text{ver})}}, \quad \text{in vertical direction}, \quad -0.34 \leq \frac{1}{M_{\text{system/hor/avg}}} \leq \frac{1}{M_{\text{system/ver/avg}}}
\]
16.1.4. Monitor inside the vehicle

16.1.4.1. The centre of the monitor(s) shall not be below a plane passing through the driver's ocular points, as defined in paragraph 12.1., and declined 30° below.

16.1.4.2. The arrangement of the monitor(s) inside the vehicle shall be convenient to the driver.

Thus, the image of the right side field of view shall be presented to the right of the longitudinal vertical plane through the ocular reference point, defined in paragraph 12.6. The image of the left side field of view shall be presented to the left of the longitudinal vertical plane through the ocular reference point.

If the CMS shows more than one field of vision on one display, non-continuous images shall be clearly separated from each other. Provided that the required field of vision of different classes of devices for indirect vision are shown on the monitor(s) without hiding any part of the required field of vision, a combined continuous image without clear separation is allowed.

16.1.4.3. The monitor defined size shall be visible without any obstruction from the ocular reference point. A virtual testing is acceptable.

16.1.5. Obstruction of the driver's direct view caused by the installation of a device for indirect vision shall be restricted to a minimum.

16.1.6. Decreasing accommodation

The installation of the monitor inside the vehicle should follow the needs of the intended user group. The operator's manual shall provide information on the decreasing capacity of the human being to accommodate and shall recommend suitable assistance for the user's needs.

16.1.7. Safety of electronic systems for indirect vision

The requirements to be applied to the safety aspects of electronic systems for indirect vision are given in Annex 12, paragraph 2.
16.2. Classes VIII camera-monitor devices

16.2.1. A device for indirect vision shall give such performances that a critical object can be observed by the driver over the entire required field of vision, taking into account the critical perception according the procedure of Annex 10.

Alternatively, the determination of the displayed object size shall be performed according to Annex 11.

16.2.2. Obstruction of the driver's direct view caused by the installation of a device for indirect vision shall be restricted to a minimum.

16.2.3. Installation requirements for the monitor

The viewing direction of the monitor shall roughly be the same direction as the one for the main mirror.

16.2.4. Vehicles may be equipped with additional devices for indirect vision.

16.2.5. The provisions of this Regulation do not apply to the surveillance camera-monitor-recording devices defined in paragraph 2.3. of this Regulation. Exterior surveillance cameras either shall be mounted at least 2 m above the ground when the vehicle is under a load corresponding to its maximum technical permissible mass, or, if their lower edge is less than 2 m from the ground, shall not project more than 50 mm beyond the overall width of the vehicle measured without this device and have a radii of curvature of not less than 2.5 mm.

17. Modifications of the vehicle type and extension of approval

17.1. Every modification of the vehicle type shall be notified to the Type Approval Authority which approved the vehicle type. Type Approval Authority shall then either:

(a) Decide, in consultation with the manufacturer, that a new type approval is to be granted; or

(b) Apply the procedure contained in paragraph 17.1.1. (Revision) and, if applicable, the procedure contained in paragraph 17.1.2. (Extension).

17.1.1. Revision

When particulars recorded in the information folder have changed and the Type Approval Authority considers that the modifications made are unlikely to have an appreciable adverse effect, and that in any case the vehicle still complies with the requirements, the modification shall be designated a "revision".

In such a case, the Type Approval Authority shall issue the revised pages of the information folder as necessary, marking each revised page to show clearly the nature of the modification and the date of re-issue. A consolidated, updated version of the information folder, accompanied by a detailed description of the modification, shall be deemed to meet this requirement.

17.1.2. Extension
The modification shall be designated an "extension" if, in addition to the change of the particulars recorded in the information folder,

(a) Further inspections or tests are required; or

(b) Any information on the communication document (with the exception of its attachments) has changed; or

(c) Approval to a later series of amendments is requested after its entry into force.

17.2. Confirmation or refusal of approval, specifying the alterations, shall be communicated to the Parties to the Agreement which apply this Regulation by means of a form conforming to the model in Annex 4 to this Regulation. In addition, the index to the information package, attached to the communication document, shall be amended accordingly to show the date of the most recent revision or extension.

17.3. The Type Approval Authority issuing the extension of approval shall assign a series number to each communication form drawn up for such an extension.

18. **Conformity of production**


18.2. Every vehicle approved under this Regulation shall be so manufactured as to conform to the type approved by meeting the requirements set out in paragraph 15., and where applicable paragraph 16. above.

19. **Penalties for non-conformity of production**

19.1. The approval granted in respect of a vehicle type pursuant to this Regulation may be withdrawn if the requirement laid down in paragraph 18.1. above is not complied with or if the vehicle fails to pass the checks prescribed in paragraph 18.2. above.

19.2. If a Party to the Agreement which applies this Regulation withdraws an approval it has previously granted, it shall forthwith so notify the other Contracting Parties applying this Regulation by means of a copy of the approval form bearing at the end, in large letters, the signed and dated annotation "APPROVAL WITHDRAWN".

20. **Production definitively discontinued**

If the holder of the approval completely ceases to manufacture a type of vehicle approved in accordance with this Regulation, he shall so inform the Type Approval Authority which granted the approval. Upon receiving the relevant communication, the Authority shall inform thereof the other Parties to the Agreement applying this Regulation by means of a copy of the approval form bearing at the end, in large letters, the signed and dated annotation "PRODUCTION DISCONTINUED".
21. **Names and addresses of Technical Services responsible for conducting approval tests, and of Type Approval Authorities**

The Parties to the Agreement applying this Regulation shall communicate to the United Nations Secretariat the names and addresses of the Technical Services responsible for conducting approval tests and of the Type Approval Authorities which grant approval and to which forms certifying approval or refusal or extension or withdrawal of approval, issued in other countries, are to be sent.
Annex 1

Information document for type approval of a device for indirect vision

The following information, if applicable, shall be supplied in triplicate and shall include a list of contents.

Any drawings shall be supplied in appropriate scale and in sufficient detail on size A4 paper or on a folder of A4 format.

Photographs, if any, shall show sufficient details.

1. Make (trade name of manufacturer): .................................................................
2. Type and general commercial description(s): ......................................................
3. Means of identification of the type, if indicated on the device: ..............................
4. Category of vehicle for which the device is intended: ........................................
5. Name and address of manufacturer: ....................................................................
6. Location and method of affixing of the approval mark: ........................................
6.1. Other mean of identification link to the approval mark: ....................................
7. Address(es) of assembly plant(s): ......................................................................
8. Mirrors (state for each mirror): ..............................................................................
8.1. Variant ..............................................................................................................
8.2. Drawing(s) for the identification of the mirror: ..................................................
8.3. Details of the method of attachment: .................................................................
9. Devices for indirect vision other than mirrors: ......................................................
9.1. Type and characteristics (such as a complete description of the device): ..........
9.1.1. In the case of camera-monitor systems of Class VIII, the class, the detection distance [mm], contrast, luminance range, glare correction, display performance (black and white/colour) image repetition frequency, luminance reach of the monitor: .................................................................
9.1.2. In the case of detection system of Classes VIII, the class, field of view, latency and rear horizontal area and detection rate: ..................................................
9.2. Sufficiently detailed drawings to identify the complete device including installation instructions; the position for the type-approval mark has to be indicated on the drawings: ............................................................................
 Annex 2

Need to modify for application of detection system.

Information document for type approval of a vehicle with respect to the installation of devices for indirect vision

The following information, if applicable, shall be supplied in triplicate and include a list of contents.

Any drawings shall be supplied in appropriate scale and in sufficient detail on size A4 paper or on a folder of A4 format.

Photographs, if any, shall show sufficient details.

General
1. Make (trade name of manufacturer): ...........................................................
2. Type and general commercial description(s): ............................................
3. Means of identification of type, if marked on the vehicle: ............................
4. Location of that marking: ..........................................................................
5. Category of vehicle: ..................................................................................
6. Name and address of manufacturer: ............................................................
7. Address(es) of assembly plant(s): .................................................................

General construction characteristics of the vehicle
8. Photograph(s) and/or drawing(s) of a representative vehicle: ........................
9. Driving cab (forward control or bonneted): ............................................... 1
10. Driving position: left/right1 ........................................................................ 1
10.1. The vehicle is equipped to be driven in right-hand/left hand traffic1 .......... 1
11. Range of vehicle dimensions (overall): ......................................................
11.1. For chassis without bodywork .................................................................
11.1.1. Width:2 .............................................................................................

1 Strike out where not applicable
2 “Overall width” of a vehicle means a dimension which is measured according to ISO standard 612-1978, term No. 6.2. In the case of vehicles of category other than M1, in addition to the provisions of that standard, when measuring the vehicle width the following devices shall not be taken into account:

(a) Customs sealing devices and their protection;
(b) Devices for securing the tarpaulin and their protection;
(c) Tyre failure tell-tale devices;
(d) Protruding flexible parts of a spray-suppression system;
(e) Lighting equipment;
(f) For buses, access ramps in running order, lifting platforms and similar equipment in running order provided that they do not exceed 10 mm from the side of the vehicle and the corners of the ramps facing forwards or rearwards are rounded to a radius of not less than 5 mm; the edges shall be rounded to a radius of not less than 2.5 mm;
(g) Devices for indirect vision;
(h) Tyre-pressure indicators;
11.1.1.1. Maximum permissible width: .................................................................
11.1.1.2. Minimum permissible width: ..............................................................
11.2. For chassis with bodywork: .................................................................
11.2.1. Width:\[a\] ............................................................................................
12. Bodywork
12.1. Devices for indirect vision
12.1.1. Mirrors ....................................................................................................
12.1.1.1. Drawing(s) showing the position of the mirror relative to the vehicle structure: .................................................................
12.1.1.2. Details of the method of attachment including that part of the vehicle structure to which it is attached: ........................................
12.1.1.3. Optional equipment which may affect the rearward field of vision: ..............
12.1.1.4. A brief description of the electronic components (if any) of the adjustment device: .................................................................
12.1.2. Devices for indirect vision other than mirrors: ........................................
12.1.2.1. Sufficiently detailed drawings with the installation instructions: ..............
12.1.2.2. In the case of camera-monitor system of Classes VIII: .............................
12.1.2.2.1. Drawing(s)/photograph(s) showing the position of the camera(s) relative to the vehicle structure: .................................................................
12.1.2.2.2. Drawing(s)/photograph(s) showing the arrangement of the monitor(s) including surrounding interior parts: .................................................................
12.1.2.2.3. Drawing(s)/photograph(s) showing the drivers view onto the monitor(s): ......
12.1.2.2.4. Drawing(s)/photograph(s) showing the setup and monitor image of the required field of view: .................................................................
12.1.2.2.5. Details of the method of attachment of the camera-monitor device(s) including that part of the vehicle structure to which it is attached: ......................
12.1.2.2.6. Optional equipment which may affect the rearward field of vision: ..............
12.1.2.2.7. A brief description of the electronic components (if any) of the adjustment device: .................................................................
12.1.2.2.8. A technical specification and operator's manual of the camera-monitor system according to ISO 16505: 2015: .................................................................

(i) Retractable steps;
(j) The deflected part of the tyre walls immediately above the point of contact with the ground.
Annex 3

Need to modify for application of detection system.

Communication

(Maximum format: A4 (210 x 297 mm))

issued by: Name of administration:

................................................................. ................................................................. .................................................................

Concerning: Approval granted
Approval extended
Approval refused
Approval withdrawn
Production definitively discontinued

of a type of device for indirect vision pursuant to Regulation No. 46

Approval No. ............................................. Extension No. .............................................

1. Trade name or mark of device: .................................................................
2. Manufacturer's name for the type of device: .................................................................
3. Manufacturer's name and address: .................................................................
4. If applicable, name and address of manufacturer's representative: .................................................................
5. Submitted for approval on: .................................................................
6. Technical Service responsible for conducting approval tests: .................................................................
7. Date of report issued by that Service .................................................................
8. Number of report issued by that Service .................................................................
9. Brief description .................................................................

Identification of the device: mirror, camera/monitor, other device

Device for indirect vision of Classes VIII
Symbol \(\frac{\Delta}{2m}\) as defined in paragraph 6.3.1.1. of this Regulation: yes/no

10. Position of the approval mark: .................................................................
11. Reason(s) for extension (if applicable): .................................................................
12. Approval granted/refused/extended/withdrawn:

---

1 Distinguishing number of the country which has granted/extended/refused/withdrawn approval (see approval provisions in the Regulations).
2 Strike out what does not apply.
13. Place:........................................................................................................................................
14. Date:........................................................................................................................................
15. Signature:..................................................................................................................................
16. The list of documents deposited with the Type Approval Authority which has granted approval is annexed to this communication and may be obtained on request.
Annex 4

Communication

(Maximum format: A4 (210 x 297 mm))

Issued by: .................................................................
Name of administration: .............................................

Concerning: 2  
Approval granted  
Approval extended  
Approval refused  
Approval withdrawn  
Production definitively discontinued

of a type of vehicle with regard to the mounting of devices for indirect vision pursuant to Regulation No. 46

Approval number: ............................................ Extension No.: ............................................

1. Make (trade name of manufacturer): .................................................................
2. Type and general commercial description(s) ....................................................
3. Means of identification of type, if marked on the vehicle: ....................................
3.1. Location of that marking: .................................................................
4. Category of vehicle: (M₁, M₂, M₃, N₁, N₂ ≤ 7.5 t, N₃ > 7.5 t, N₄) 2
5. Name and address of manufacturer: .................................................................
6. Address(es) of the production plant(s) ............................................................
7. Additional information: (where applicable). See appendix
8. Technical Service responsible for carrying out the tests: ....................................
9. Date of test report: .........................................................................................
10. Number of test report: ..................................................................................
11. Remarks: (if any). See appendix
12. Place: ...........................................................................................................
13. Date: ...........................................................................................................
14. Signature: ......................................................................................................
15. The index to the information package lodged with the Type Approval Authority, which may be obtained on request is attached.

1 Distinguishing number of the country which has granted/extended/refused/withdrawn approval (see approval provisions in the Regulation).
2 Strike out what does not apply.
Annex 4 – Appendix

Appendix to type approval communication form No. …….. concerning the type approval of a vehicle with regard to the mounting of devices for indirect vision under Regulation No. XXX.

1. Trade name or mark of mirrors and supplementary devices for indirect vision and component type-approval number: ..........................................................................................................................

2. Class of mirrors and devices for indirect vision (VIII)\(^1\)

3. Extension of type approval of the vehicle to cover the following device for indirect vision........................................................................................................................................................................

4. Data for identification of the R point of the driver’s seating position: ..............................

5. Maximum and minimum bodywork width in respect of which the mirror and the devices for indirect vision has been granted type-approval (in the case of chassis/cab referred to in paragraph 15.2.2.3. of this Regulation) ...................................................................................

6. The following documents, bearing the type approval number shown above, are annexed to this certificate:

   (a) Drawings showing the mounting of the devices for indirect vision .........................

   (b) Drawings and plans showing the mounting position and characteristics of the part of the structure where the devices for indirect vision are mounted............

7. Remarks: (e.g. valid for right hand/left hand traffic\(^1\)) ............................................................

---

\(^1\) Strike out what does not apply.
Annex 5

Arrangement of approval mark of a device for indirect vision

(See paragraph 5.4. of the Regulation)

The above approval mark affixed to a device for indirect vision indicates that the device is a main rear-view device, of Class VIII, which has been approved in the Japan (E43) pursuant to Regulation No. XXX and under approval number 002439. The first two digits of the approval number indicate that the approval was granted in accordance with the requirements of UN Regulation No. XXX in its original form.

Note: The approval number and the additional symbol shall be placed close to the circle and either above or below the "E" or to the left or right of that letter. The digits of the approval number shall be on the same side of the "E" and point in the same direction. The additional symbol shall be directly opposite the approval number. The use of Roman numerals as approval numbers shall be avoided so as to prevent any confusion with other symbols.
Annex 6

Test method for determining reflectivity

1. Definitions

1.1. CIE standard illuminate A: Colorimetric illuminate, respecting the full radiator at T_{68} = 2,855.6 K.

1.1.2. CIE standard source A: Gas-filled tungsten filament lamp operating at a correlated colour temperature of T_{68} = 2,855.6 K.

1.1.3. CIE 1931 standard colorimetric observer: Receptor of radiation whose colorimetric characteristics correspond to the spectral tristimulus values (see table).

1.1.4. CIE spectral tristimulus values: Tristimulus values of the spectral components of an equi energy spectrum in the CIE (XYZ) system.

1.1.5. Photopic vision: Vision by the normal eye when it is adapted to levels of luminance of at least several cd/m².

2. Apparatus

2.1. General

The apparatus shall consist of a light source, a holder for the test sample, a receiver unit with a photodetector and an indicating meter (see Figure 1), and means of eliminating the effects of extraneous light.

The receiver may incorporate a light-integrating sphere to facilitate measuring the reflectance of non-flat (convex) mirrors (see Figure 2).

2.2. Spectral characteristics of light source and receiver

The light source shall consist of a CIE standard source A and associated optics to provide a near-collimated light beam. A voltage stabiliser is recommended in order to maintain a fixed lamp voltage during instrument operation.

The receiver shall have a photodetector with a spectral response proportional to the photopic luminosity function of the CIE (1931) standard colorimetric observer (see table). Any other combination of illuminate-filter-receptor giving the overall equivalent of CIE standard illuminate A and photopic vision may be used. When an integrating sphere is used in the receiver, the interior surface of the sphere shall be coated with a matt (diffusive) spectrally non-selective white coating.

2.3. Geometrical conditions

The angle of the incident beam (Θ) should preferably be 0.44 ± 0.09 rad (25 ± 5°) from the perpendicular to the test surface and shall not exceed the upper limit of the tolerance (i.e. 0.53 rad or 30°). The axis of the receptor

---

1 Definitions taken from CIE publication 50 (45), International Electronic Vocabulary, Group 45, Lighting
shall make an angle (θ) with this perpendicular equal to that of the incident beam (see Figure 1). The incident beam upon arrival at the test surface shall have a diameter of not less than 13 mm (0.5 inch). The reflected beam shall not be wider than the sensitive area of the photodetector, shall not cover less than 50 per cent of such area, and as nearly as possible shall cover the same area segment as used during instrument calibration.

When an integrating sphere is used in the receiver section, the sphere shall have a minimum diameter of 127 mm (5 inch). The sample and incident beam apertures in the sphere wall shall be of such a size as to admit the entire incident and reflected light beams. The photodetector shall be so located as not to receive direct light from either the incident or the reflected beam.

2.4. Electrical characteristics of the photodetector-indicator unit

The photodetector output as read on the indicating meter shall be a linear function of the light intensity of the photosensitive area. Means (electrical and/or optical) shall be provided to facilitate zeroing and calibration adjustments. Such means shall not affect the linearity or the spectral characteristics of the instrument. The accuracy of the receptor indicator unit shall be within ±2 per cent of full scale, or ±10 per cent of the magnitude of the reading, whichever is the smaller.

2.5. Sample holder

The mechanism shall be capable of locating the test sample so that the axes of the source arm and receptor intersect at the reflecting surface. The reflecting surface may lie within or at either face of the mirror sample, depending on whether it is a first surface, second surface or prismatic "flip" type mirror.

3. Procedure

3.1. Direct calibration method

In the direct calibration method, air is used as the reference standard. This method is applicable for those instruments, which are so constructed as to permit calibration at the 100 per cent point by swinging the receiver to a position directly on the axis of the light source (see Figure 1).

It may be desired in some cases (such as when measuring low-reflectivity surfaces) to use an intermediate calibration point (between 0 and 100 per cent on the scale) with this method. In these cases, a neutral density filter of known transmittance shall be inserted in the optical path, and the calibration control shall then be adjusted until the meter reads the percentage transmission of the neutral density filter. This filter shall be removed before reflectivity measurements are performed.

3.2. Indirect calibration method

The indirect calibration method is applicable in the case of instruments with fixed source and receiver geometry. A properly calibrated and maintained reflectance standard is required. This reference standard should preferably be a flat mirror with a reflectance value as near as possible to that of the test samples.
3.3. Flat mirror measurement

The reflectance of flat mirror samples can be measured on instruments employing either the direct or the indirect calibration method. The reflectance value is read directly from the indicating meter.

3.4. Non-flat (convex) mirror measurement

Measurement of the reflectance of non-flat (convex) mirrors requires the use of instruments which incorporate an integrating sphere in the receiver unit (see Figure 2). If the instrument-indicating meter indicates $n_d$ divisions with a standard mirror of $E$ per cent reflectance, then, with a mirror of unknown reflectance, $n_e$ divisions will correspond to a reflectance of $X$ per cent, in accordance with the formula:

$$X = E \frac{n_x}{n_e}$$

Figure 1
**Generalised reflectometer showing experimental set-ups for the two calibration methods**
Figure 2
Generalised reflectometer, incorporating an integrating sphere in the receiver

- Light source and collimating optics
- Photo detector
- Sample holder
- Meter with Adjustment
- Reflectance (%)
- Calibration adjustment
- Zero adjustment

[Diagram of the generalised reflectometer with labels for each component]
4. Spectral tristimulus values for the CIE 1931 standard colormetric observer

This table is taken from CIE publication 50 (45) (1970)

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<th>( \lambda ) nm</th>
<th>( \bar{X}(\lambda) )</th>
<th>( \bar{Y}(\lambda) )</th>
<th>( \bar{Z}(\lambda) )</th>
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<td>0.000 0</td>
<td>0.006 5</td>
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<td>0.000 1</td>
<td>0.020 1</td>
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<td>0.000 4</td>
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<td>0.091 0</td>
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<td>0.208 0</td>
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<td>0.323 0</td>
<td>0.272 0</td>
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<td>0.710 0</td>
<td>0.078 2</td>
</tr>
<tr>
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<td>0.862 0</td>
<td>0.042 2</td>
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<td>0.954 0</td>
<td>0.020 3</td>
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<td>0.952 0</td>
<td>0.002 1</td>
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<td>0.870 0</td>
<td>0.001 7</td>
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<td>0.757 0</td>
<td>0.001 1</td>
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<td>0.002 1</td>
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</tr>
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<td>0.001 4</td>
<td>0.000 5</td>
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<td>740</td>
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<td>0.000 2 (*)</td>
<td>0.000 0</td>
</tr>
<tr>
<td>750</td>
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<td>0.000 1</td>
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<td>0.000 1</td>
<td>0.000 0</td>
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<tr>
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<td>0.000 0</td>
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</tr>
<tr>
<td>780</td>
<td>0.000 0</td>
<td>0.000 0</td>
<td>0.000 0</td>
</tr>
</tbody>
</table>

\( (*) \) Changed in 1966 (from 3 to 2)

---

\(^2\) Abridged table. The values of \( Y(\lambda) = \sqrt{V(\lambda)} \) are rounded off to four decimal places
Explanatory figure

Example of device for measuring the reflection factor of spherical mirrors

C = Receiver
D = Diaphragm
E = Window of entry
F = Window of measurement
L = Lens
M = Object window
S = Light source
(S) = Integrating sphere
Annex 7

Procedure for determining the radius of curvature "r" of the reflecting surface of a mirror

1. Measurement

1.1. Equipment

A "spherometer" similar to the one described in Figure 1 of this annex having the indicated distances between the tracing pin of the dial gauge and the fixed legs of the bar is used.

1.2. Measuring points

1.2.1. The principal radii of curvature shall be measured at three points situated as close as possible to positions at one-third, one-half and two-thirds of the distance along the arc of the reflecting surface passing through the centre of this surface and parallel to segment b, or of the arc passing through the centre of the reflecting surface which is perpendicular to it if this arc is the longer.

1.2.2. Where, owing to the size of the reflecting surface, it is impossible to obtain measurements in the directions defined in paragraph 2.1.1.5. of this Regulation, the Technical Services responsible for the tests may take measurements at the said point in two perpendicular directions as close as possible to those prescribed above.

2. Calculation of the radius of curvature "r"

"r" expressed in mm is calculated from the formula:

\[ r = \frac{r_p^1 + r_p^2 + r_p^3}{3} \]

Where:

- \( r_p^1 \) = the radius of curvature at the first measuring point,
- \( r_p^2 \) = the radius of curvature at the second measuring point,
- \( r_p^3 \) = the radius of curvature at the third measuring point.
Figure 1
Spherometer

18
5
10
6
80

5
10
18
5
6
80
100

α 4.5 pitch F 90.4

 comparator

 mobile point
Annex 8

Procedure for determining the "H" point and the actual torso angle for seating positions in motor vehicles

Appendix 1 - Description of the three dimensional "H" point machine (3-D H machine)

Appendix 2 - Three-dimensional reference system

Appendix 3 - Reference data concerning seating positions

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1 The procedure is described in Annex 1 to the Consolidated Resolution on the Construction of Vehicles (R.E.3) (document ECE/TRANS/WP.29/78/Rev.4).

Annex 9

Check compatibility for new pole specification.

Calculation of the detection distance for CMS of Class VIII

1. Camera monitor device for indirect vision

1.1. Determination of the smallest discernable detail

The smallest discernable detail of the naked eye shall be defined according to standard ophthalmologic tests like the Landolt C test or the Triangle Orientation Discrimination (TOD) test. The smallest discernable detail at the centre of the viewing system can be determined using the Landolt C test or the TOD test. In the rest of the viewing area the smallest discernable detail may be estimated from the centrally determined smallest discernable detail and the local image deformation. For instance, in the case of a digital camera the smallest discernable detail at a given pixel location (in the monitor) scales inversely with the solid angle of the pixel.

1.1.1. Landolt-C test

In the Landolt-C test, test symbols are judged by the subject under test. In accordance with this test the smallest discernable detail is defined as the visual angle of the gap size of the Landolt C symbol at threshold size and is expressed in arcmin. The threshold size corresponds to the size at which the subject judges the orientation correctly in 75 per cent of the trials. The smallest discernable detail is determined in a test involving a human observer. A test chart containing test symbols is placed in front of the camera and the observer judges the orientation of test symbols from the monitor. From the threshold gap size of the Landolt C symbol \( d \) [m] and the distance between the test pattern and the camera \( D \) [m] the smallest discernable detail \( \omega_c \) [arcmin] is calculated as follows:

\[
\omega_c = \frac{d}{D} \cdot \frac{180 \cdot 60}{\pi}
\]

1.1.2. TOD test

The Landolt C test can be used to determine the smallest discernable detail of the camera-monitor system. However, for sensor systems it is more suitable to use the TOD (Triangle Orientation Discrimination) method which is similar to the Landolt C method, but involves equilateral triangular test patterns. The Triangle Orientation Discrimination method is described in detail by Bijl & Valeton (1999), who provide practical guidelines on how to perform a TOD measurement. In the method, triangular test patterns (see Figure 1) are viewed through the viewing system under test. Each triangle can have one out of four possible orientations (apex up, left, right or down) and the observer indicates/guesses for each triangle its orientation. When this procedure is repeated for many (randomly oriented) triangles of different sizes the fraction of correct responses can be plotted (see Figure 2), and increases with test pattern size. The threshold is defined as the point at which the fraction correct crosses the 0.75 level and can be obtained by fitting a smooth function through the data (see Bijl & Valeton, 1999). Critical perception is reached when the critical object diameter equals two times the
width of the triangle at threshold size. The smallest discernable detail \( \omega_c \) is equal to 0.25 times the width of the triangle at threshold size. This means that, from the threshold triangle width \( w \) [m] and the distance between test pattern and the camera \( D \) [m] the smallest discernable detail \( \omega_c \) [arcmin] is calculated as follows:

\[
\omega_c = \frac{w}{4 \cdot D} \frac{180 \cdot 60}{\pi}
\]

Figure 1
Triangular test patterns used in the Triangle Orientation Discrimination (TOD) method

![Figure 1](image1.png)

Figure 2
Typical relationship between the size of the triangle and the fraction of correct responses

![Figure 2](image2.png)

1.2. Determination of the critical viewing distance of the monitor

For a monitor having certain dimensions and properties, the distance to the monitor can be calculated within which the detection distance is dependent only on the performances of the camera. The critical viewing distance \( r_{mcrit} \) is defined as the distance at which the smallest discernable detail displayed on the monitor spans 1 arcmin measured from the eye (the acuity threshold of a standard observer).

\[
r_{mcrit} = \frac{\delta \cdot 60 \cdot 180}{\pi}
\]

Where:

\( r_{mcrit} \): critical viewing distance of the monitor [m]
1.3. Determination of the detection distance

1.3.1. Maximum detection distance within the critical viewing distance where, due to the installation, the distance eye-monitor is less than the critical viewing distance, the maximum attainable detection distance is defined as:

\[ r_{\text{dclose}} = \frac{D_0 \cdot 60 \cdot 180}{\omega_c \cdot \pi \cdot f} \]

Where:
- \( r_{\text{dclose}} \): detection distance [m]
- \( D_0 \): diameter of the critical object [m] according to paragraph 2.1.2.6. of this Regulation; for the calculation of \( r_{\text{dclose}} \) for Class V and VI devices, a representative value of 0.30 m shall be used.
- \( f \): threshold increasing factor, which is equal to 8
- \( \omega_c \): smallest discernable detail [arcmin]

1.3.2. Detection distance greater than the critical viewing distance. Where, due to the installation, the distance eye-monitor is more than the critical viewing distance, the maximum obtainable detection distance is defined as:

\[ r_{\text{dfar}} = \frac{r_{\text{mcrit}}}{r_{\text{m}}} r_{\text{dclose}} \quad \text{[m]} \]

Where:
- \( r_{\text{dfar}} \): detection distance for distances larger than the critical viewing distance [m]
- \( r_{\text{dclose}} \): detection distance for distances smaller than the critical viewing distance [m]
- \( r_{\text{m}} \): viewing distance, i.e. distance between eye and monitor [m]
- \( r_{\text{mcrit}} \): critical viewing distance [m]

2. Secondary functional requirements

Based on the installation conditions, a determination shall be made to discover whether the entire device can still satisfy the functional requirements listed in paragraph 6.2.2. of this Regulation, specifically the glare correction, the maximum and the minimum luminance of the monitor. It shall also be determined the degree to which the glare correction will be addressed and the angle at which sunlight can strike a monitor and these shall be compared to the corresponding measuring results from the system measurements. This can be either based on a CAD-generated model, a determination of the angles of light for the device when mounted on the relevant vehicle, or by carrying out relevant measurements on the relevant vehicle as described in paragraph 6.2.2.2. of this Regulation.
Annex 11

Check compatibility for new pole specification.

**Determination of the displayed object size for CMS of Class VIII**

1. Camera monitor device for indirect vision

1.1. General

   Determination of the displayed object size considers the possible appearance of smear. The impact on the monitors image and consequence is the occultation of the field of view and therefore of the object. The following differentiation is made:

1.2. Case A: Smear appears

   1.2.1. Step 1: Under the condition described in paragraph 6.2.2.1.2. of this Regulation, measure the width ($s$) of the vertical bar displayed on the monitor e.g. with a measurement microscope.

   1.2.2. Step 2: Place the object at a defined distance from the camera. Measure the width of the object displayed on the monitor ($b$) in a situation without real sun light condition e.g. with a measurement microscope.

   1.2.3. Step 3: Calculate the residual object width ($\alpha$) according to the following equation:

   $$\alpha \left[ \text{arcmin} \right] = 60 \times 2 \times \arctan \left( \frac{b - s}{2 \times r} \right)$$

   Where:

   - $\alpha$: residual width of the object displayed on the monitor (with smear) [minutes of arc]
   - $b$: width of the object displayed on the monitor (without smear) [mm]
   - $s$: width of the smear [mm]
   - $r$: viewing distance [mm]

1.3. Case B: Smear does not appear

   1.3.1. Step 1: Place the object at a defined distance from the camera. Measure the width of the object displayed on the monitor ($b$) in a situation without real sun light condition e.g. with a measurement microscope.

   1.3.2. Step 2: Calculate the object width ($\alpha$) according to the following equation:

   $$\alpha \left[ \text{arcmin} \right] = 60 \times 2 \times \arctan \left( \frac{b}{2 \times r} \right)$$

   Where:

   - $\alpha$: width of the object displayed on the monitor (without smear) [minutes of arc]
   - $b$: width of the object displayed on the monitor (without smear) [mm]
r: viewing distance [mm]

1.4. Data supplied by the instructions for use

In the case of Classes VIII camera monitor devices the instructions for use shall include a table that shows the minimum and maximum mounting height of the camera above ground under consideration of different viewing distances. The camera shall be mounted within the applicable height range. The viewing distances shall be selected from the intended context of use. The following table shows an example.

<table>
<thead>
<tr>
<th>Viewing distance</th>
<th>0.5 m</th>
<th>1.0 m</th>
<th>1.5 m</th>
<th>2.0 m</th>
<th>2.5 m</th>
</tr>
</thead>
<tbody>
<tr>
<td>Minimum mounting height</td>
<td>para. 1.4.1.</td>
<td>para. 1.4.1.</td>
<td>para. 1.4.1.</td>
<td>para. 1.4.1.</td>
<td>para. 1.4.1.</td>
</tr>
<tr>
<td>Maximum mounting height</td>
<td>para. 1.4.2.</td>
<td>para. 1.4.2.</td>
<td>para. 1.4.2.</td>
<td>para. 1.4.2.</td>
<td>para. 1.4.2.</td>
</tr>
</tbody>
</table>

1.4.1. The value of the minimum mounting height is the same for all viewing distances as it is independent of the viewing distance. It is determined by the dimensions of the field of vision and the field of view of the camera. Use the following working steps for determination of the minimum mounting height.

1.4.1.1. Step 1: Draw the intended field of vision on ground.

1.4.1.2. Step 2: Place the camera above the field of vision in such a way that the camera is viewing the field of vision. The lateral position shall be in accordance with the intended mounting position at the vehicle.

1.4.1.3. Step 3: Change the height of the camera above ground in such a way, that the field of vision displayed on the monitor covers an area at least as large as the field of vision. Furthermore, the field of vision display shall encompass the entire monitor screen.

1.4.1.4. Step 4: Measure the height between camera and ground which is the minimum mounting height. Report the result value.

1.4.2. The value of the maximum mounting height is different for different viewing distances as the displayed object size varies with the mounting height. Use the following working steps for determination of the maximum mounting height:

1.4.2.1. Step 1: Determine the minimum width \( b_{\text{min}} \) of the critical object displayed on the monitor for each viewing distance.

\[
b_{\text{min}} = 2 \times r \times \tan \frac{8'}{2 \times 60}
\]

Where:

r: viewing distance [mm]

\( b_{\text{min}} \): minimum width of the critical object displayed on the monitor [mm]

1.4.2.2. Step 2: Place the critical object inside the drawn intended field of vision in a position at which the distance between the critical object and the camera is...
largest. The illumination conditions shall be in such a way that the critical object is clearly visible on the monitor.

1.4.2.3. Step 3: Select the first value of the possible viewing distances.

1.4.2.4. Step 4: Change the height of the camera above ground in such a way, that the residual width \( B \) of the object displayed on the monitor is equal to the minimum width allocated to that viewing distance.

\[ B = b_{\text{min}} \]

Where:

\( B \): residual width of the object displayed on the monitor (which is "b" in cases without smear and "b – s" in cases with smear) in mm (see paragraph 1.1. General)

1.4.2.5. Step 5: Measure the height between camera and ground which is the maximum mounting height allocated to that viewing distance. Report the result value.

1.4.2.6. Step 6: Repeat the aforementioned steps 4 and 5 for the other viewing distances.
Test methods and safety provisions for CMS of Class VIII

1. Test methods

1.1. General specifications

The Technical Service shall use recognized test methods to check compliance with the requirements defined above in the Regulation. These test methods shall be agreed upon by the Type Approval Authority.

1.2. Flicker test

The entire image area of the monitor shall be free of flicker for at least 90 per cent of the user population. The flicker evaluation uses the determination given in Annex B of ISO13406-2: 2001. The following measurement procedure applies:

1.2.1. Position the camera of the CMS in front of a still scene (e.g. chessboard chart). Use a scene illumination of about 500 lx. Measure the time resolved luminance value of a portion of the monitor that displays a white patch of the chessboard chart. The measurement location shall be near the centre of the monitor defined size and the measurement direction is perpendicular onto the monitor. Perform a Fourier transform of the luminance-time function for determination of the amount of energy $E_{\text{obs}}$ at various frequencies up to 120 Hz. These numbers are then compared to the amounts of energies that people will detect as flicker, the predicted flicker threshold $E_{\text{pred}}$.

If $E_{\text{obs}} < E_{\text{pred}}$ at every frequency < 120 Hz then it is likely that people will not see flicker.

If $E_{\text{obs}} \geq E_{\text{pred}}$ at any frequency < 120 Hz then it is likely that people will see flicker.

1.2.2. Determination of $E_{\text{obs}}$, which is the observed energy at every frequency < 120 Hz:

$$E_{\text{obs},n} = DC \times AMP_n = A \times c_0 \times AMP_n = b_0 \times L_t^h \times c_0 \times AMP_n$$

where:

$$b_0 = 12.45184$$

$$b_1 = -0.16032$$

For $L_t$, which is the adaption luminance:

Use $L_t = L_{\text{monitor/chart/white/ambient}}$ from ISO 16505:2015 (subclause 7.8.2: Test 2: Day condition with diffuse sky-light exposure).

For $c_0$, which is the zero Fourier coefficient, and is the dark-room luminance averaged over time.

Use $c_0 = L_{\text{monitor/chart/white}}$ from ISO 16505:2015

(see ISO 16505:2015, subclause 7.8.2.: Test 2: Day condition with diffuse sky-light exposure with the diffuse light source switched off).
For $AMP_n$:

$$AMP_n = \frac{2 \cdot |c_n|}{c_0}$$

For $c_n$, which is the $n^{th}$ Fourier coefficient. Take the $n^{th}$ Fourier coefficient from the Fourier transform.

1.2.3. Determination of $E_{\text{pred}}$, which is the predicted energy at every frequency $< 120$ Hz:

$$E_{\text{pred}, n} = a \cdot e^{b \cdot f_n}$$

The variables $a$ and $b$ depend on the monitor diagonal as seen from the driver's ocular reference point and is measured in degree (see Table B.1 in the standard ISO 13406-2:2001). For a monitor diagonal $\alpha_{\text{monitor Diagonal}}$ of less than 20°, variables $a$ and $b$ equals to $a = 0.1276$ and $b = 0.1424$.

The monitor diagonal $\alpha_{\text{monitor Diagonal}}$ is given by the following equation:

$$\alpha_{\text{monitor Diagonal}} = 2 \cdot \arctan \left( \frac{\text{Diagonal}}{\text{Diagonal}} \right)$$

Where:

Diagonal  diagonal of the monitor, measured in metres

$a_{\text{monitor D}}$  Distance of the ORP to the centre of the monitor coordinate system.

1.2.4. For every frequency $< 120$ Hz compare the observed energy $E_{\text{obs}}$ with the predicted energy $E_{\text{pred}}$ and report the result value for passed or failed.

1.3. Point light sources test method

Figure 1 shows the test arrangement for the point light source test.
The point light source lab model is an emulation of a set of vehicle passing beam headlamps at a distance of 250 m with luminous intensity of 1,750 cd, in accordance to the maximum allowance of luminous intensity of a vehicle passing-beam headlamp at point "BR" described in Regulation No. 112, 01 series of amendments. The test is performed considering a set of lamps with 0.09 m diameter and separated by 1.3 m. This results in a luminance of 275,000 cd/m². For laboratory evaluation purposes the light sources shall be adjusted to have a luminance within the range of 250,000 to 300,000 cd/m² by using a constant current source.

For laboratory evaluation purpose a shorter distance than 250 m can be used.

The distance \( a_{\text{PLS}} \) from the camera entrance pupil to the point light source lab model shall be within the depth of field of the camera. The point light source lab model shall be adjusted to the measuring distance \( a_{\text{PLS}} \) in terms of lamp size \( d_{\text{PLS}} \) and distance \( SD_{\text{PLS}} \). The value for \( d_{\text{PLS}} \) and \( SD_{\text{PLS}} \) shall be rounded to the nearest 0.1 mm.

A typical white LED having a correlated colour temperature of 6,500 K with a tolerance of \( \pm 1,500 \) K is used for this evaluation. The emitting surface of
the LED shall keep an even luminance or it shall be diffused using an optional diffuser as shown in Figure 1.

The angular size corresponding to the headlamp of 0.09 m diameter and the angular orientation of the two point light source separated by 1.3 m of each other, at 250 m distance, are calculated as:

$$\alpha_{\text{LampDia}} = 2 \times \arctan \left( \frac{0.09/2}{250} \right) = 2 \times \arctan \left( \frac{d_{\text{PLS}}/2}{a_{\text{PLS}}} \right) = 1.24'$$

and

$$\alpha_{\text{PLS}} = 2 \times \arctan \left( \frac{1.3/2}{250} \right) = 2 \times \arctan \left( \frac{S\text{D}_{\text{PLS}}/2}{a_{\text{PLS}}} \right) = 17.9'$$

For example, at 6 m distance from CMS to this emulated LED, the corresponding aperture opening of the LED shall be $d_{\text{PLS}} = 2.2$ mm in diameter and separated by $S\text{D}_{\text{PLS}} = 31.2$ mm to emulate the set of passing beam headlamps located 250 m from the CMS.

Ambient illumination at the point light source lab model and at the monitor-side shall be less than 2 lx.

The luminance of the LED shall be measured at the same angular direction of the CMS to confirm that light emitted from the aperture delivers the correct luminance.

The luminance of the rendered point light sources on the monitor is measured by using a reference (luminance) camera according to ISO 16505:2015 providing a sufficient spatial resolution, or equivalent.

For the evaluation, the CMS shall be switched to the operation mode intended to observe the point light sources.

Position the camera of the CMS such that its optical axis is aligned to the perpendicular orientation of the point light source lab model (Figure 1). Target the CMS camera to display the point light sources in the middle of the monitor defined size. The distance from the camera entrance pupil to the point light source lab model shall be set to $d_{\text{PLS}}$.

For determination of the point light source detection factor PLSDF evaluate the luminance profile in horizontal and vertical direction (Figure 2).
The point light source detection factor - PLSDF is determined by the following equation:

\[ PLSDF = \frac{s_H \times L_{H,\text{max}}}{s_V \times L_{V,\text{max}}} \]

Where:

- \( s_H \) = full width at half maximum of the luminance profile in horizontal direction at the vertical centre
- \( L_{H,\text{max}} \) = maximum luminance of the luminance profile in horizontal direction at the vertical centre
- \( s_V \) = full width at half maximum of the luminance profile in vertical direction at hourglass point
- \( L_{V,\text{max}} \) = maximum luminance of the luminance profile in vertical direction at hourglass point

Verify the consistency of the result with slightly shifted position of the point light source lab model.

For determination of the point light source contrast factor PLSCF, evaluate the luminance profile in horizontal direction (Figure 3) at the vertical centre.
The point light source contrast factor PLSCF is determined by the following equation:

$$PLSCF = 1 - \frac{L_{H,\text{min}}}{L_{H,\text{max}}}$$

Where:

- $L_{H,\text{max}}$ maximum luminance of the luminance profile in horizontal direction
- $L_{H,\text{min}}$ luminance value at saddle point of the luminance profile, which is equivalent to the minimum luminance value between the two luminance peaks (see Figure 3)

Verify the consistency of the result with slightly shifted position of the point light source lab model.

1.4. Grey scale rendering test method

The grey scale rendering test shall verify that CMS are capable of displaying at least 8 tonal grey steps distinguishable within the darkest and brightest output range from the reproduced chart on the CMS monitor. The grey scale rendering test is evaluated using a 20:1 low contrast grey scale chart as described in ISO 14524:2009, Table A.1, under 500 lx illuminated scene environment.

The distinguishable tonal difference described herein is defined as an display output signal whose lightness difference between two different tonal input through the CMS satisfy at least $\Delta L^* \geq 3.0$, with $L^*$ defined as lightness according to the definition in CIE 1976 $L^*a^*b^*$ colour space.

Figure 4 shows the test arrangement for the grey scale rendering test.
Figure 4
Test arrangement for the grey scale rendering test

1: Test chart (grey scale rendering chart)
2: Illumination for test chart
3: Camera being tested
4: Monitor being tested
5: Reference camera
6: Optical or spatial isolation between camera and monitor display environment
7: Optical isolation barrier to avoid direct light into lens
8: Camera-side
9: Monitor-side

Figure 5 shows an example of a grey scale rendering chart to be used in this measurement. The grey scale rendering chart shall consists of 12 different tonal density grey patches.

The density value $D_i$ shall follow the values as defined by ISO 14524:2009 Table A.1 for low contrast 20:1. The definition of $D_i$ is given in the ISO 14524:2009.

The background of the patches shall be covered with a neutral grey colour having a density value $D_i$ of $0.54 \pm 0.05$.

Both reflective and transmissive charts with Lambertian characteristics can be used.

The whole camera image area shall be covered by the chart image. The grey scale rendering chart shall be placed in such a way so that the grey patches are visible in the centre of the monitor defined size.

Adjust the distance between the camera under test and the test chart to have individual patches of the chart displayed by at least 50 x 50 pixels on the monitor under test, whenever possible. For Class IV devices exhibiting high
distortion and/or optical vignetting, a reduced size area may also be used to minimize the vignette effect on the measurement results.

The illumination shall be similar to the CIE D65 standard illuminant and have a correlated colour temperature of $T = 6,500$ K with a tolerance of ±1,500 K.

The test is performed with a scene illumination of 500 lx (this test condition is equivalent to test condition for colour rendering as defined in ISO 16505:2015 clause 7.8.3), and at room temperature 22 °C ± 5 °C.

Ambient illumination at the monitor-side shall be ≤ 10 lx, and glare light source to the monitor shall be avoided.

Figure 5
Example of the grey scale rendering chart

Each patch on the grey scale rendering chart shall have a size of 50 x 50 mm. The distance between the patches shall be 5 mm.

Table 1 shows density value $D_i$ of the 12 different grey patches as well $D_i$ of the background.

<table>
<thead>
<tr>
<th>Grey patch No.</th>
<th>Density $D_i$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1.40</td>
</tr>
<tr>
<td>2</td>
<td>1.21</td>
</tr>
<tr>
<td>3</td>
<td>1.05</td>
</tr>
<tr>
<td>4</td>
<td>0.90</td>
</tr>
<tr>
<td>5</td>
<td>0.77</td>
</tr>
<tr>
<td>6</td>
<td>0.65</td>
</tr>
<tr>
<td>7</td>
<td>0.54</td>
</tr>
<tr>
<td>8</td>
<td>0.44</td>
</tr>
<tr>
<td>9</td>
<td>0.35</td>
</tr>
<tr>
<td>10</td>
<td>0.26</td>
</tr>
<tr>
<td>11</td>
<td>0.18</td>
</tr>
<tr>
<td>12</td>
<td>0.10</td>
</tr>
<tr>
<td>Background</td>
<td>0.54 ±0.05</td>
</tr>
</tbody>
</table>
Measure the luminance $Y_i$ of each grey patch $i = 1...12$ by using the reference camera. Then, calculate the lightness of each grey patch:

$$L'_i = 116 \times \left( \frac{Y_i}{Y_{12}} \right)^{\frac{1}{3}} - 16 , \text{ when } Y_i/Y_{12} > 0.008856$$

$$L'_i = 903.3 \times \left( \frac{Y_i}{Y_{12}} \right) , \text{ when } Y_i/Y_{12} \leq 0.008856$$

Calculate the lightness difference between each grey patch:

$$\Delta L^*_i = L^*_{i+1} - L^*_i$$

and compare the result with the requirement.

2. Special requirements to be applied to the safety aspects of camera monitor systems for indirect vision

2.1. General

The purpose of this paragraph is to specify the requirements for documentation and verification for CMS for indirect vision of Classes I to IV to replace mandatory rear-view mirrors for road vehicles.

"The System", referred to herein, is the one for which type approval is being sought.

This paragraph 2. does not specify the performance criteria for "The System" but covers the methodology applied to the design process and the information which shall be disclosed to the Technical Service, for type approval purposes.

This information shall show that "The System" respects, under normal and fault conditions, all the appropriate performance requirements specified elsewhere in this Regulation.

2.2. Definitions

2.2.1. Camera Monitor System (CMS)

A CMS is used in road vehicles to present the required outside information of a specific field of view to the driver. It replaces a conventional legally prescribed mirror system on the vehicle by means of electronic image capture and display systems.

It consists of a camera that is usually installed at the bodywork of a vehicle and a monitor that is usually placed inside the vehicle.

2.2.2. Camera

A camera is a device to capture colour images of a specific field of view. It mainly consists of two relevant items: imager and lens.

2.2.3. Monitor

A monitor is a device for displaying images. It either consists of a matrix of active areas that radiate light of different wavelengths or is a (usually diffuse) reflector that is illuminated in different wavelengths and in a matrix of specific points by a projector.
2.2.4. Control unit
A control unit is a component which controls communication and coordination between electronic components, e.g. a camera and a monitor.

2.2.5. Safety concept
A safety concept is a description of the measures designed into the system, for example within the electronic units, so as to address system integrity and thereby ensure safe operation even in the event of a system or electrical failure.

2.2.6. "Boundary of functional operation"
"Boundary of functional operation" defines the boundaries of the external physical limits within which the system is able to maintain functionality.

2.3. Documentation
2.3.1. The vehicle manufacturer shall provide the following documentation:
(a) A description of the camera monitor system which gives an explanation of the main function of the system, incl. drawings, pictures, block diagrams, etc.
(b) A description of the location of the camera and the monitor in the vehicle (system overview).
(c) Name of manufacturer of camera, monitor and electronic control units.
(d) Type of camera and monitor. Each unit shall be clearly and unambiguously identifiable (e.g. by marking for hardware and marking or software output for software content) to provide corresponding hardware and documentation association.
(e) Explanation of the warning strategy and the safety concept, as defined by the manufacturer, covering at least the list of failures of paragraph 2.4.

2.3.2. For periodic technical inspections, the documentation shall describe how the current operational status of "The System" can be verified.

2.3.3. The limits for the boundary of functional operation (e.g. environmental parameters) shall be stated where appropriate to the system performance.

2.3.4. Safety concept of the manufacturer
The manufacturer shall provide a statement which affirms that the strategy chosen allows a safe operation of "The System".
In the case of a failure, the driver shall be informed for example by a clear and visible warning signal or message display. When the system is activated, the warning shall be present as long as the fault condition persists.
The fault conditions shall be established and maintained by the manufacturer and shall be made open for inspection by the Technical Service at the time of the type approval.

2.3.5. The chosen analytical approach(es) shall be established and maintained by the manufacturer and shall be made open for inspection by the Technical Service at the time of the type approval.
2.4. List of failures

2.4.1. Camera
(a) Failure of the camera;
(b) Electronic noise, reduced detail resolution;
(c) Defocus of the optics, reduced detail resolution.

2.4.2. Monitor
(a) Failure of monitor display, no image content is displayed;
(b) Freeze of displayed monitor content, image content is not refreshed;
(c) Enlarged image formation time, changing image content is blurred.

2.4.3. Control unit
(a) Failure of the control unit;
(b) Failure in the communication between camera and control unit;
(c) Failure in the communication between control unit and monitor.

2.5. Verification

2.5.1. Verification of the performance of the camera monitor system under no-fault and fault conditions shall be conducted against the manufacturer's specification.

2.5.2. The verification of the safety concept of the reaction of the camera monitor system shall, at the discretion of the Type Approval Authority, be verified according to the influence of failures in paragraph 2.4. The verification results shall correspond with the documented summary of the failure analysis in paragraph 2.4., to a level of overall effect such that the safety concept and execution are confirmed as being adequate.
Annex 13

Test conditions for Class VIII field of vision.

1. Field of vision

The requirements of field of vision defined in paragraph 15.2.3. of this regulation can be tested in the conditions described in this Annex.

1.1. Test objects

Each test object is a right circular cylinder that is 1.0 m high and 0.3 m in external diameter. Each test are marked as follows.

(a) Test objects are marked with a horizontal line 50mm apart from the bottom to the uppermost of the side of the cylinder.

(b) Test objects are marked on the side with a solid vertical stripe of 150 mm width extending from the top to the bottom of each cylinder.

(c) Both the horizontal band and vertical stripe shall be of a color that contrasts with both the rest of the cylinder and the test surface.

Figure A

Test object

Pole marking specification to be updated.

1.2. Test object locations and orientation.

Place the test objects at locations specified in (a) to (h) and illustrated in Figure B. Measure the distances shown in Figure B from a test object to another test object or other object from the cylindrical center (axis) of the test object as viewed from above. Each test object is oriented so that its axis is vertical.

(a) Place test objects A, B and C so that their centers are in a transverse vertical plane that is 0.3 m to the rear of a transverse vertical plane tangent to the rearmost surface of the rear bumper.

(b) Place test object B so that its center is in a longitudinal vertical plane passing through the vehicle’s longitudinal centerline.

(c) Place test objects D, E and F so that their centers are in a transverse vertical plane that is 1.5 m to the rear of a transverse vertical plane tangent to the rearmost surface of the rear bumper.

(d) Place test object E so that its center is in a longitudinal vertical plane passing through the vehicle’s longitudinal centerline.
(e) Place test objects G, H and I so that their centers are in a transverse vertical plane that is 3.5 m to the rear of a transverse vertical plane tangent to the rearmost surface of the rear bumper.

(f) Place test object H so that its center is in a longitudinal vertical plane passing through the vehicle's longitudinal centerline.

(g) Place test objects A, D, and G so that their outermosts are in a longitudinal vertical plane tangent to the left-side outermost surface of the vehicle.

(h) Place test objects C, F, and I so that their outermosts are in a longitudinal vertical plane tangent to the right-side outermost surface of the vehicle.

Test object locations can be added between A to I by Technical Service.

Figure B
Test object location

1.3. Requirements.

(a) for the test objects in the first row (Test object A, B, and C);

0.15 m x 0.15 m area or top of the test object should be seen to at least at one position on each test object. 0.15 m x 0.15 m area can be replaced to at least 3 bands 0.05 m apart continuously on each test object.

(b) for the test objects in the second row (Test object D, E, and F) and the third row (Test object G, H, and I);

Whole height of the test object should be seen.
Annex 14

Test Methods and Safety Provisions for Detection Systems

1. System activation

The system shall be activated when the reverse gear is selected. If proper functioning cannot be effected, either the system shall automatically shut off or the driver shall be able to deactivate the system manually.

There may be an on/off switch or push-button to override automatic (de)activation by driver. In the case, vehicle can detect coupling with towing vehicles, automatic off function can be activated.

2. Driver interface and information presentation strategy

2.1. Audible information

When an object is detected in the rear horizontal area as described in paragraph 5.1. below, audible information in accordance with ISO 15006:2010 shall be given.

In presenting audible information, the distance may be identified at two or more levels. These zones may be indicated by changing the frequency of intermittent sound, and faster intermittent sound or continuous sound shall be used as the distance becomes closer.

2.2. Duration of signaling

Signaling for an object shall last as long as the object is detected and shall end when the object is no longer detected or when the system is deactivated.

To reduce the driver's discomfort, the audible signal can be automatically suspended temporarily after a certain time set by the manufacturer has elapsed, provided that the system remains to be activated. If, while the audible signal is automatically suspended temporarily, the distance to the object becomes short, the audible signal shall be automatically resumed. If the distance to the object becomes long, the audible signal may remain suspended.

3. General test conditions

The test object shall be as per paragraph 7.1. of ISO 17386:2010. During testing, the wind speed shall not exceed 1 m/s. The temperature shall be 20 ± 5°C and the humidity shall be 60 ± 25 percent. There shall be no rain or snow. The test shall be performed on a flat, dry asphalt or concrete surface. The test shall not be affected by the reflection of sound waves or electromagnetic waves from any walls, auxiliary testing equipment or any other objects in the environment.

4. Dynamic performance of object detection

4.1. Detection latency

The detection latency as measured according to paragraph 4.2. shall not exceed 0.6 s.

4.2. Detection latency test method

4.2.1. Test conditions
The testing environment and test object shall be as per paragraph 3. of this annex. One test object is used. The distance from the rear edge to the test object and the position of the test object are selected by the manufacturer to ensure the detection of the test object. The test object shall be located in the detectable grids within the rear horizontal area in paragraph 5. of this annex. The test vehicle in the initial state shall be with the detection system being activated, which is declared [by the manufacturer OR in owner’s manual] and shall be in a parking condition. Here, parking condition means the P (park) position being selected in the case of vehicles equipped with automatic transmissions, whereas it means the neutral gear being selected and the parking brake being engaged in the case of vehicles equipped with manual transmissions.

4.2.2. Test procedures

(a) With the vehicle being in the initial state, locate the test object behind the vehicle and select the reverse gear. In the case of vehicles equipped with manual transmissions, release the parking brake after selecting the reverse gear.

(b) Measure the elapsed time (detection latency) from the moment at which the reverse gear is selected as specified by the manufacturer of the vehicle to the moment at which the audible warning starts. In the case of vehicles equipped with manual transmissions, the detection latency shall be the elapsed time from the moment at which the parking brake is released to the moment at which the audible warning starts.

5. Rear horizontal area detection test methods

Audible warning systems shall fulfil the test as specified in paragraphs 5.1 or 5.2. in this Annex.

5.1. Test method for detection of the test objects for Class VIII field of vision

Test object is put on each point as shown in below figure 1. Audible warning systems shall detect each test object and provide warning signal. The test object shall be defined the pole as [300] mm diameter, [1] m height and [hard plastic] material.

When the warning provided more than [five] seconds continuously, it is judged as test object is detected. The detection test shall be performed [one] time for each test object. However, if necessary, according to the agreement of Technical Service and manufacturer, it can be judged as the test object is detected in case that warnings are provided in [four] tests out of [five] tests.
To be verify the compatibility the method of 5.1 and 5.2. in IWG.

5.2 Test method for detection of the test objects for ISO 17386 (MALSO)

5.2.1 Monitoring area

The maximum detection distance in paragraphs 5.4.2. and 5.4.3. of ISO 17386:2010 shall be [1.0] m (Class R2). The width of the rectangle, \( w_r \), is equal to the vehicle width, measured along the rear axle. The dimensions shall be rounded up to the nearest 0.1 m.

Example 1

In the case of \( w_r = 1.67 \) m
Example 2
In the case of \( w_r = 1.74 \text{m} \)

5.2.2. Minimum detection rate

The minimum detection rate required for the rear horizontal area shall be as follows:

(a) 90 percent for A1 as defined in paragraph 5.4.3. of ISO 17386:2010;

(b) 87 percent for the rear-2 range in A2 as defined in paragraph 5.4.3. of ISO 17386:2010.

There shall be no undetected hole larger than a square consisting of two-by-two grids.

Here, the rear horizontal area test procedures shall be as per paragraph 7.3. of ISO 17386:2010.

When the warning provided more than [five] seconds continuously, it is judged as test object is detected. The detection test shall be performed [one] time for each test object. However, if necessary, according to the agreement of Technical Service and manufacturer, it can be judged as the test object is detected in case that warnings are provided in [four] tests out of [five] tests.

6. Self-test capabilities and failure indication

As per paragraph 5.5. of ISO 17386:2010. The system shall provide the self-test functions. It shall generate a warning signal, which is audible or visible or both, whenever a fault condition is detected.
II. Justification

This proposal is an update and rebuild of GRSG-116-10 on the Class VIII field of vision based on the discussions and conclusions of VRU-Proxi Informal Working Group. Key update are rebuild as new regulation proposal and modifications of requirements. This proposal is also under reflection of ongoing discussions in the VRU-Proxi Informal Working Group.