





Explanatory notes to the introduction of the document FRAV-03-03

From the Framework Document (FD):

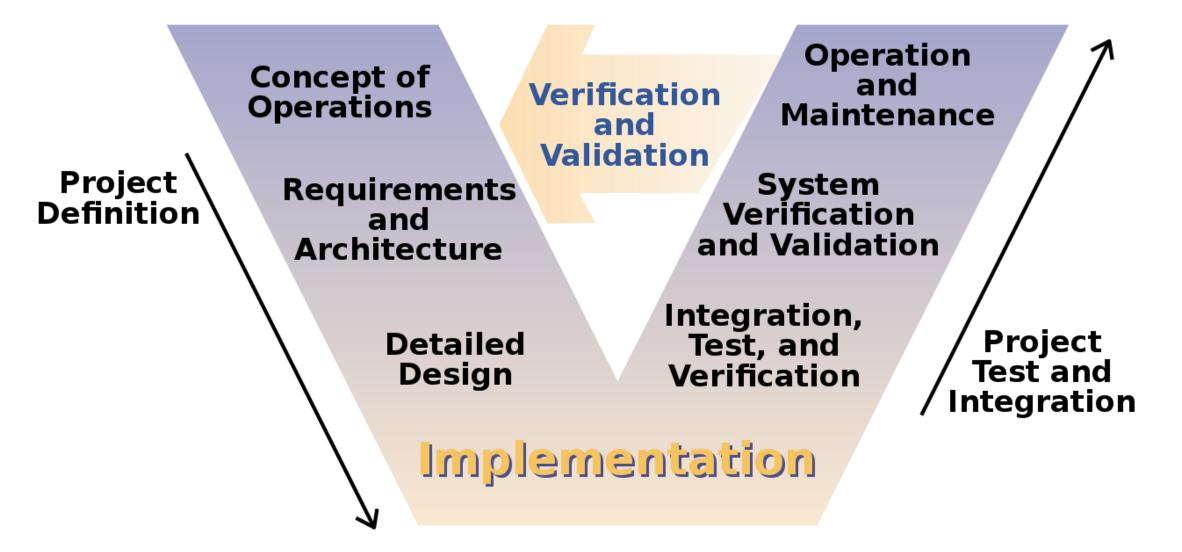
- "When in the automated mode, the automated/autonomous vehicle should be free of unreasonable safety risks to the driver and other road users and ensure compliance with road traffic regulations.",
- "This level of safety implies that an automated/autonomous vehicle shall not <u>cause</u> any nontolerable risk [introduce unreasonable risks], meaning that automated/autonomous vehicle systems, while in automated mode, shall <u>not cause any traffic accidents</u> [incidents/events] resulting in [destruction of property,] injury or death that were reasonably foreseeable and preventable."

Free of unreasonable risks: This is a strategic decision, acknowledging the residual risk

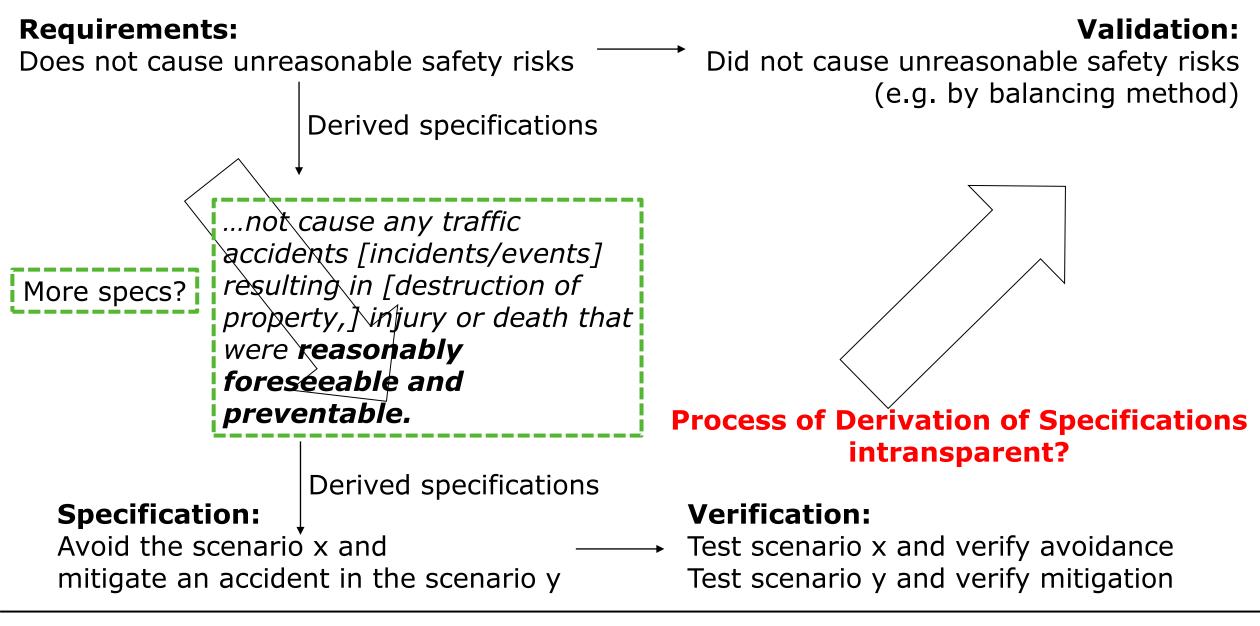
To cause a risk: a) cause an accident, b) to not succeed to avoid a non-caused accident <u>at least as</u> <u>good</u> a human driver.

To cause an accident: Cause an accident.

V-Model (Wikipedia):



V-Model



"Reasonably foreseeable and preventable"

- Foreseeable by whom?
 - Expert Driver
 - Computer with sensors
 - Programmer of ADS
 - Neural Network
- Preventable through what?
 - Expert Driver-like control system
 - Fast brake actuator
 - Fast steering system

RFaP needs further specification and interpretation!

Conclusions and Proposal from FRAV-03-03

- Framework Document defines top-level requirements
- Specifications need to be derived
- \bigcirc Some kind of "product development process" (→ V-Model)
- Define RFaP on a technical basis
- Process proposal: <u>Agree on Specifications top-down</u>!
 - As opposed to collecting requirements where the derivation is unclear
- Technical proposal (as an example):
 - Physical limitations (DE's preference)
 - (Safety Envelope is a special form of physical limitations)
 - Expert driver model